MXSlowControl

MeπX

Stefan Lunkenheimer

MAGIX Collaboration Meeting 2017-02-17

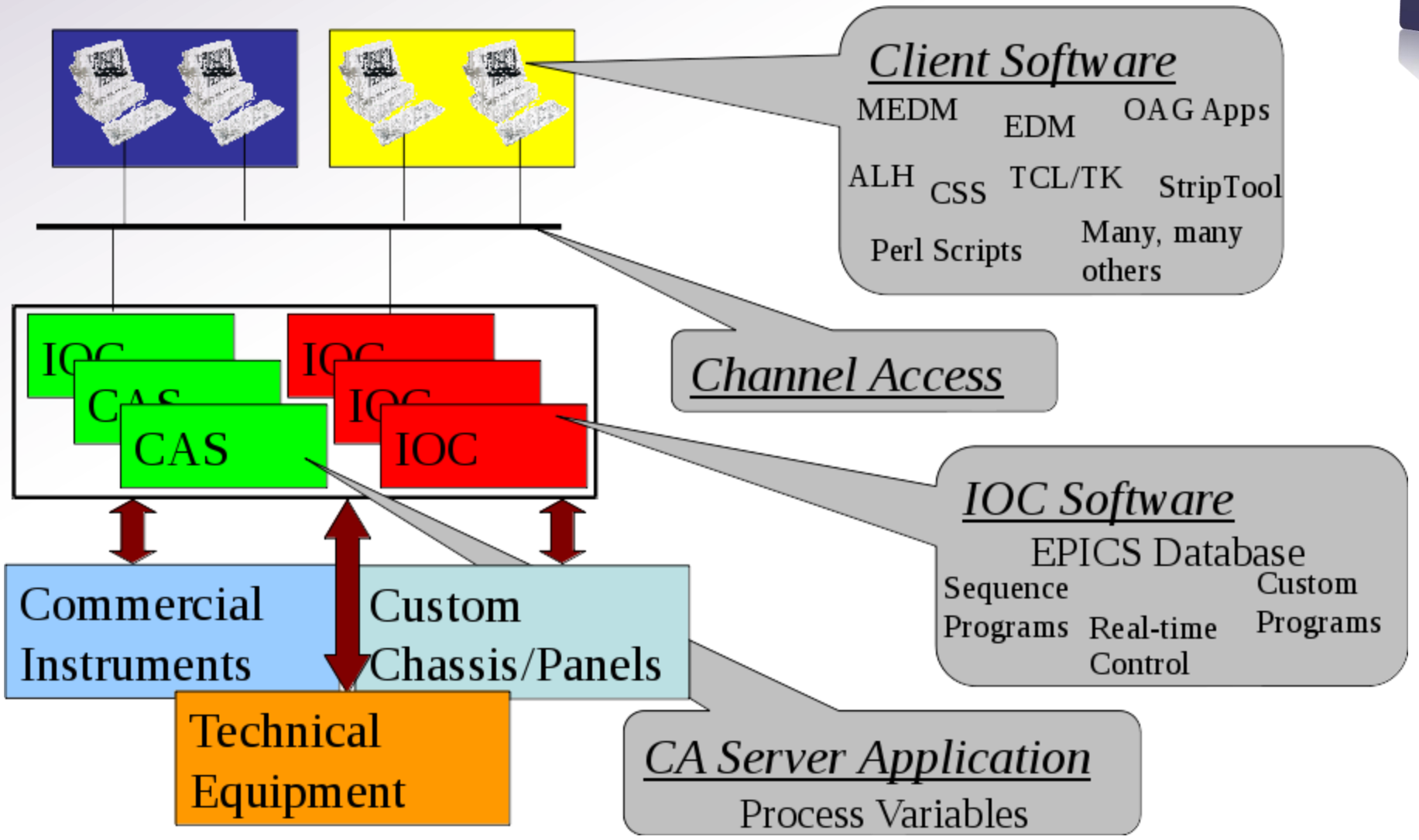
Topics

- EPICS Overview
- Status quo
- Strategy / Outlook

EPICS

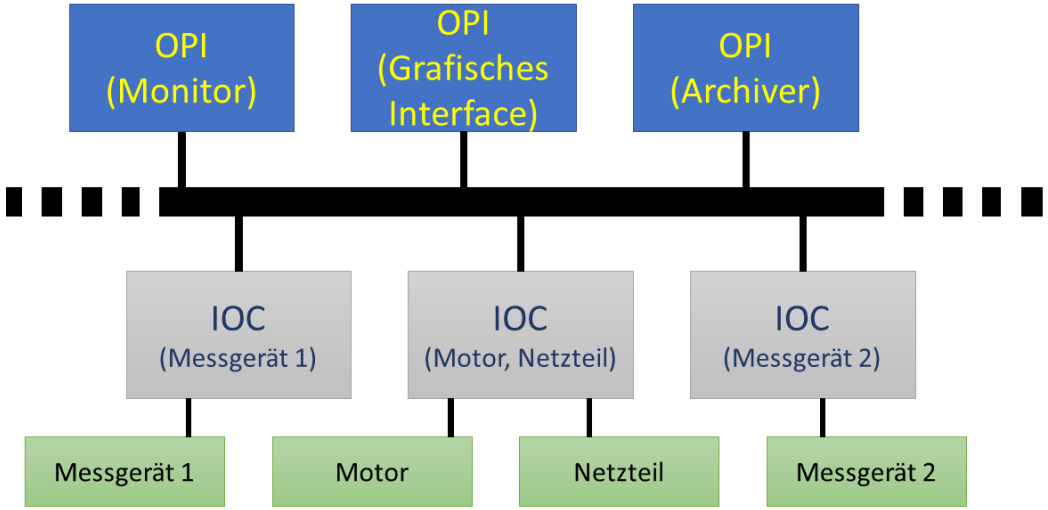
- Software to control physical experiments
- Distributed system
  - Multiple closed systems
- Maintained by community and external
  - A lot of solutions available

Structure


Client Software
MEDM
EDM
OAG Apps
ALH
CSS
TCL/TK
StripTool
Perl Scripts
Many, many others
Channel Access
IOC
CAS
IOC
IOC Software
EPICS Database
Sequence Programs
Real-time Control
Custom Programs
Commercial Instruments
Custom Chassis/Panels
Technical Equipment
CA Server Application
Process Variables

Structure

- Channel Access
  - Communication Protocol
- Input-Output Controller (IOC)
- Operator Interface
  - EPICS Clients
  - Communicate via CA



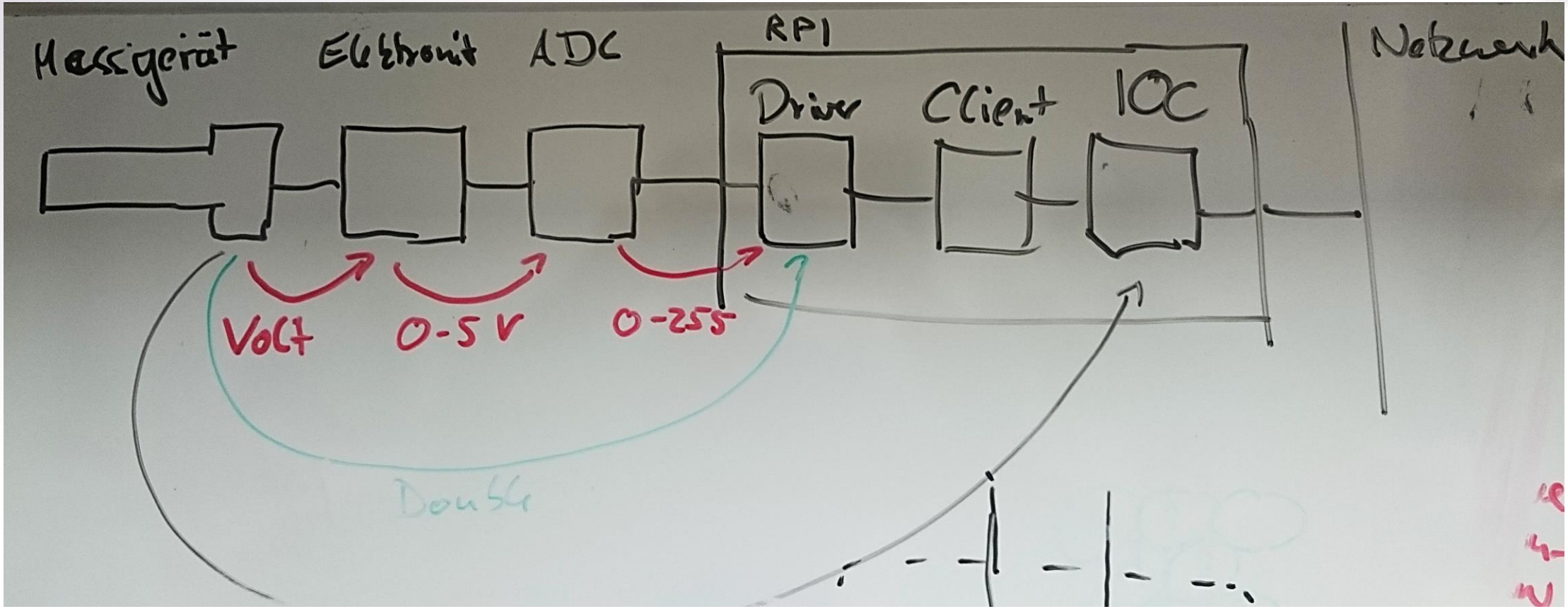
Server

- Multiple servers (IOC‘s)
- Defines Process-Variables with database
- Span virtual bus (Channel Access)
- Configuration for each IOC needed

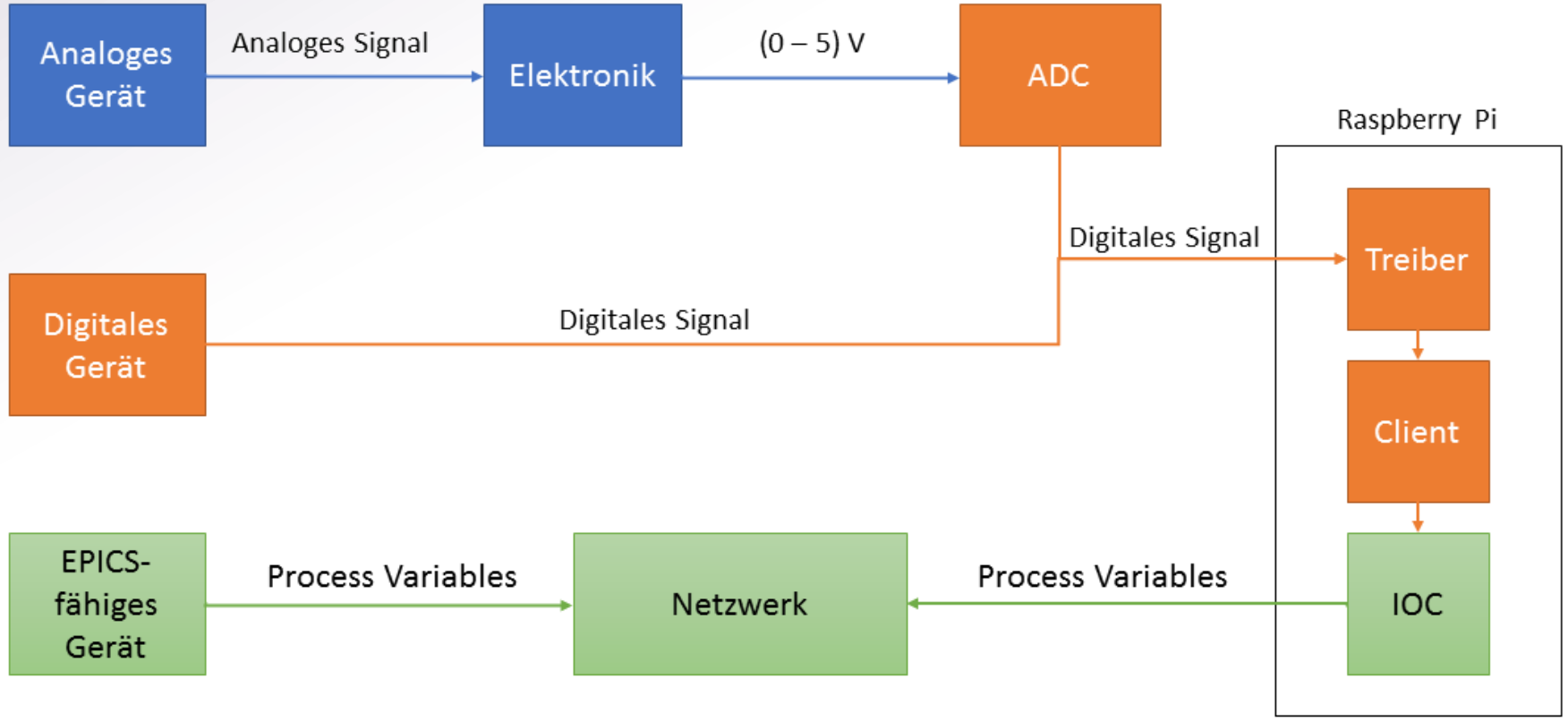
Client

- CSS, python, c++, many others
- Can get or put stuff in the PV's
- Monitoring
- Self configured

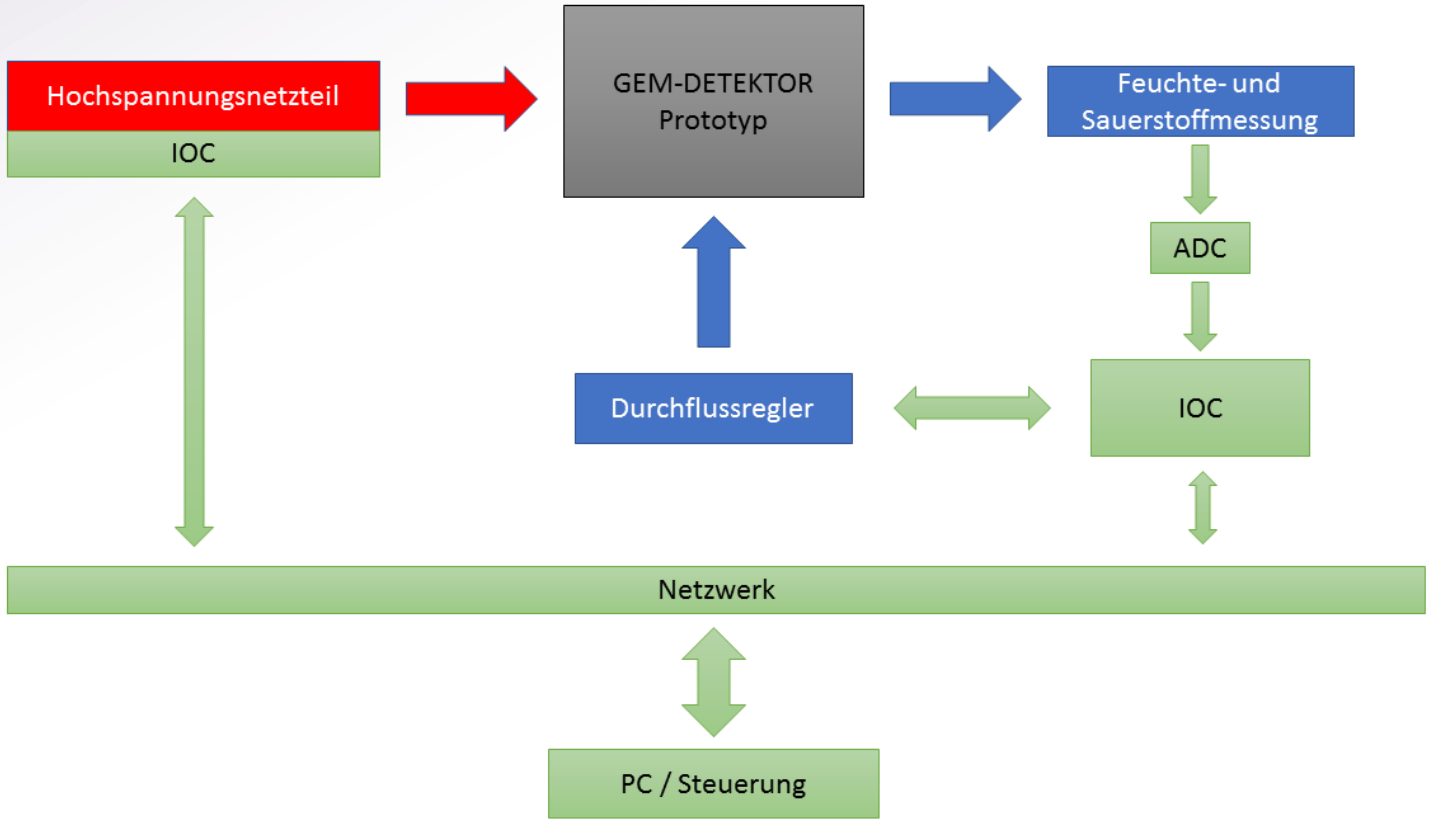
Basic device control



Basic device control



Test setup GEM-Detector

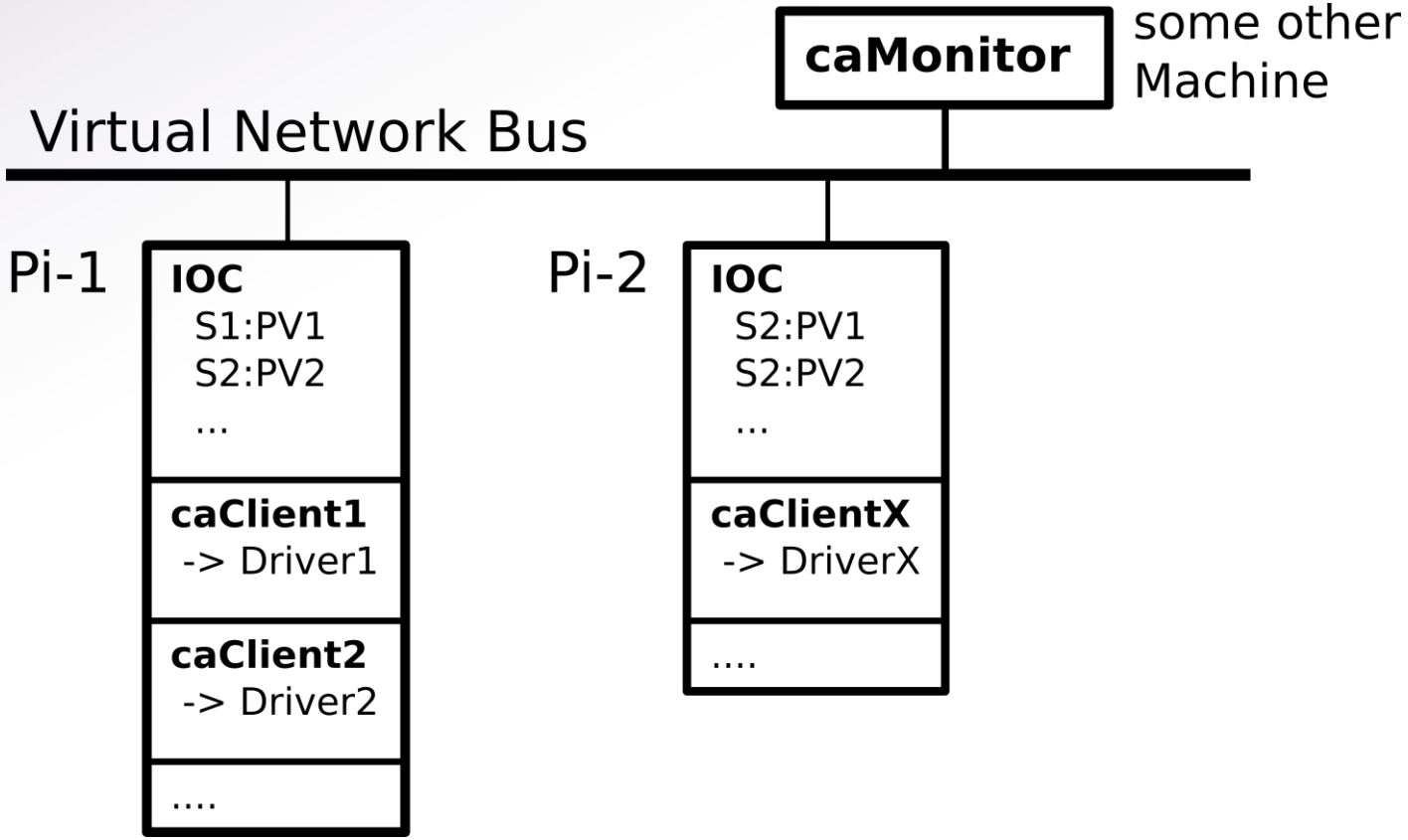


Status quo

IOC Configuration

- Basic supply of Process Variables understood
- Basic knowlegde of database structure
- Communication with IOC understood
- Control of devices via caClient (python, c++)

Structure


caMonitor
some other
Machine
Virtual Network Bus
Pi-1
IOC
S1:PV1
S2:PV2
...
caClient1
-> Driver1
caClient2
-> Driver2
....
Pi-2
IOC
S2:PV1
S2:PV2
...
caClientX
-> DriverX
....

MXcaClient

- Self made caClient in c++
  - Interface between PV‘s – drivers
- Client loads the device driver
- Clients fill / read the PV‘s in fixed time intervalls
  - Polling
  - Controlling the device
- Configuration via XML (MXWare)

Strategy / Outlook

What next?

- Learn more about EPICS
- Control devices directly with IOC
  - Streamdevice
- Improve configuration
- Build a GUI
- …

Software

- Write drivers
- Expand/Improve caClient
- Build GUI
- Build control monitor application
  - Safety aspect
  - Logicial operations

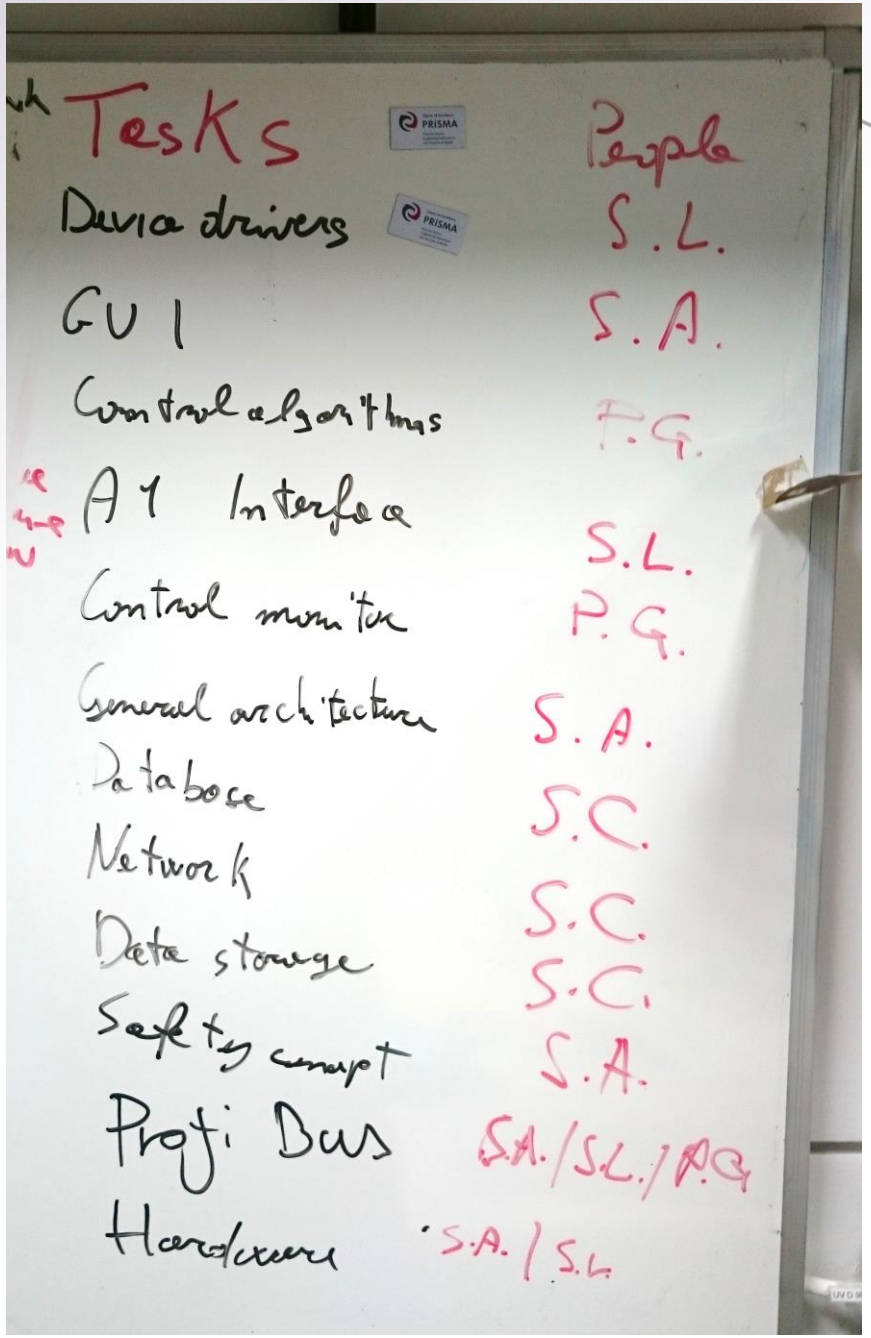
Specific work for beam time

- A1 Interface
- Data storage
- Profi Bus – pumping station
- Other Hardware

Collaboration work

- List important parameters
- Monitoring via Internet
- Discuss driver configuration individually
- Safety discussion
- Control monitor arrangement

Sharing Working



SFB 1044

PRISMA

THANK YOU FOR YOUR ATTENTION!

http://magix.kph.uni-mainz.de

Massachusetts Institute of Technology

University of Ljubljana

Westfälische Wilhelms-Universität Münster

Johannes Gutenberg Universität Mainz

JG|U

BACKUP

Example configuration

IOC Database

```
record(ai,"magix-85::debug::sinus"){
    field(SCAN,".1 second")
    field(PREC,"2")
}

record(ao,"magix-85::debug::offset"){
    field(SCAN,"Passive")
    field(VAL,"0.5")
    field(PREC,"2")
    field(DRVL,"-1.5")
    field(DRVH,"1.5")
}

record(ao,"magix-85::debug::amplitude"){
    field(SCAN,"Passive")
    field(VAL,"1")
    field(PREC,"2")
    field(DRVL,"0")
    field(DRVH,"2.5")
}

record(ao,"magix-85::debug::frequency"){
    field(SCAN,"Passive")
    field(VAL,"0.1")
    field(PREC,"2")
    field(DRVL,"0.01")
    field(DRVH,"0.5")
}
```

MXcaClient configuration file

```
<ChannelAccess>

<PV>
    <name>magix-85::debug::sinus</name>
    <channel>0</channel>
    <out>true</out>
</PV>
<PV>
    <name>magix-85::debug::offset</name>
    <channel>1</channel>
    <out>false</out>
</PV>
<PV>
    <name>magix-85::debug::amplitude</name>
    <channel>2</channel>
    <out>false</out>
</PV>
<PV>
    <name>magix-85::debug::frequency</name>
    <channel>3</channel>
    <out>false</out>
</PV>
<device type="debugDevice">
    <name>First Sinus</name>
    <description>
        This is a simple sinus:
        s(t) = a*sin(t) + b
    </description>
    <opt>Parameter</opt>
    # device specific variables / start parameter
    <offset>0.5</offset>
    <amplitude>1</amplitude>
    <frequency>0.1</frequency>
</device>

</ChannelAccess>
```