

Uncertainties in the RGE Evolution of α_s

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1 Solutions to the RGE equation

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3 Results

α_s satisfies the Renormalization Group Equation

$$\mu^2 \frac{d}{d\mu^2}(a_s) = \beta(a_s) = -\beta_0 a_s^2 (1 + b_1 a_s + b_2 a_s^2 + b_3 a_s^3 + \dots) \quad (1)$$

$$a_s \equiv \frac{\alpha_s}{\pi} = \frac{g}{4\pi^2}, \quad b_N \equiv \frac{\beta_N}{\beta_0}$$

- β_0 and β_1 are renormalization scheme independent.
- In the $\overline{\text{MS}}$ β_2 [Tarasov et al., 1980, Larin and Vermaseren, 1993] and β_3 [van Ritbergen et al., 1997] are known.

Using the n_f^4 obtained by [Gracey, 1996]

$$E_4 = -\frac{\left(\frac{4}{3}(214 + 288\zeta_3) + 3(-229 + 480\zeta_3)\right)}{995328} \approx -0.0018 \quad (2)$$

[Ellis et al., 1998] was able to predict using Padé Approximants the β_4 coefficient which we use in a conservative way $\beta_4 = 0 \pm \beta_4^{\text{WAPAP}}$

$$\beta_4^{\text{WAPAP}} = (A_4 + B_4 N_f + C_4 N_f^2 + D_4 N_f^3 + E_4 N_f^4) \quad (3)$$

$$A_4 = 476.6, \quad B_4 = -152.3, \quad C_4 = 16.02, \quad D_4 = -0.05908$$

- By truncating the beta function is possible to find iterative and analytical solutions as well ([Prosperi et al., 2007] for a review.)
- The iterative can be parametrized in terms of Λ_{QCD} or α_0 .
- We choose α_0 to avoid the redefinition at each loop of the parameter.
- The well known way of obtaining the iterative solution is summarized in an algorithm

$$K_n(x) = \beta_0 x + b_1 a_0 \ln[1 + K_{n-1}(x)] + \sum_{k=2} \frac{C_k a_0^k}{k-1} \left[1 - \left(\frac{1}{1 + K_{n-1}(x)} \right)^{k-1} \right]$$

$$n > 1$$

$$\vdots$$

$$K_1(x) = \frac{\beta_0 x}{1 + b_1 a_0}$$

$$K_0(x) = 0, \quad x = a_0 \ln(\mu^2/\mu_0^2) \quad (4)$$

where the C_k 's are easily calculated in terms of the inverse series of the beta function, or equivalently in terms of the PA

$$\begin{aligned} \frac{1}{\beta(a)} &= \frac{1}{\beta_0 a^2} (-1 + C_1 a + C_2 a^2 + C_3 a^3 + \dots + C_N a^N) \\ &= -\frac{1}{\beta_0 a^2} \frac{1}{[0/N]} \end{aligned} \quad (5)$$

$C_1 = b_1$, $C_2 = -b_1^2 + b_2$, $C_3 = b_1^3 - 2b_1 b_2 + b_3$, etc.

$$\begin{aligned} a_{\text{it}}^{(n)}(x) &= a_0 \left[1 + \beta_0 x + a_0 b_1 \ln(1 + K_{n-1}(x)) \right. \\ &\quad \left. + \sum_{k=2}^{n-1} a_0^k \frac{C_k}{k-1} \left(1 - \left(\frac{1}{1 + K_{n-1}(x)} \right)^{k-1} \right) \right]^{-1} \end{aligned} \quad (6)$$

- In order to diminish non-linear effects we evolve in N small steps with size $\delta_k = (\mu - \mu_0)/N$
- We observe that the result changes 0.052% with respect to the 1 step evolution when we evolve in $N = 100$ and 0.053% when the evolution has $N = 1000$ steps, we evolve in 200 steps.
- We can estimate in a simple way the uncertainty due to truncation of the beta function as

$$\Delta_{\beta}^1 = |\alpha_{\text{it}}^{(5)}(\delta_k) - \alpha_{\text{it}}^{(5)}|_{\beta_4=0}(\delta_k)|, \quad (7)$$

$$\Delta_{\beta}^2 = |\alpha_{\text{it}}^{(5)}(\delta_k) - \alpha_{\text{it}}^{(4)}(\delta_k)|, \quad (8)$$

where we use the β_4^{WAPAP} as an input for the 5-loop solution.

- The estimation difference when we evolve from μ_1 to μ_2 and then back from μ_2 to μ_1 should be small (less than 1%) in comparison with a single evolution.

- The one loop solution resumms the Leading Logarithms LL , the second loop resumms the NLL , and so on.
- We expand the 4-loop and 5-loop solutions in powers of a_0 to find explicitly at each order the difference between the expansions through the transformation

$$b_N \rightarrow b_N \pm a_0 \Delta b_N \quad (9)$$

with N the number of loops, in an analogous fashion as in [Erler, 2000] where it is proposed

$$\beta_3 \rightarrow \beta_3 \pm a_0 \beta_4 \quad (10)$$

- We found

$$\Delta b_1 = s_1 b_1^2 + s_2 b_2 \quad (2\text{-loop})$$

$$\Delta b_2 = t_1 b_1^3 + t_2 b_1 b_2 + t_3 b_3 \quad (3\text{-loop})$$

$$\Delta b_3 = u_1 b_1^4 + u_2 b_1^2 b_2 + u_3 b_2^2 + u_4 b_1 b_3 + u_5 b_4 \quad (4\text{-loop})$$

| a_0^n | s_1 | s_2 | t_1 | t_2 | t_3 | u_1 | u_2 | u_3 | u_4 | u_5 |
|------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| a_0^5 | -1.2 | 1.2 | 2 | -1.00 | 1 | - | - | - | - | - |
| a_0^6 | -1.44 | 1.44 | 2.67 | -1.00 | 1.17 | 1 | 2.00 | -1.00 | -1.00 | 1 |
| a_0^7 | -1.55 | 1.55 | 3.39 | -1.00 | 1.33 | 1.71 | 2.29 | -1.14 | -1.00 | 1.14 |
| a_0^8 | -1.72 | 1.72 | 4.16 | -1.00 | 1.50 | 2.50 | 2.63 | -1.29 | -1.02 | 1.29 |
| a_0^9 | -1.88 | 1.88 | 4.97 | -1.00 | 1.67 | 3.35 | 3.00 | -1.44 | -1.06 | 1.44 |
| a_0^{10} | -2.03 | 2.03 | 5.82 | -1.00 | 1.83 | 4.26 | 3.40 | -1.60 | -1.10 | 1.60 |
| a_0^{11} | -2.18 | 2.18 | 6.70 | -1.00 | 2.00 | 5.22 | 3.82 | -1.76 | -1.15 | 1.76 |
| a_0^{12} | -2.33 | 2.33 | 7.60 | -1.00 | 2.17 | 6.23 | 4.25 | -1.92 | -1.21 | 1.92 |
| a_0^{13} | -2.47 | 2.47 | 8.54 | -1.00 | 2.33 | 7.28 | 4.69 | -2.08 | -1.27 | 2.08 |
| a_0^{14} | -2.61 | 2.61 | 9.50 | -1.00 | 2.50 | 8.37 | 5.14 | -2.24 | -1.33 | 2.24 |
| a_0^{15} | -2.75 | 2.75 | 10.5 | -1.00 | 2.67 | 9.50 | 5.60 | -2.40 | -1.40 | 2.40 |

The uncertainty is obtained as follows

$$Y = b_3 \pm a_0 \sigma_\beta(Y) \quad (11)$$

so that

$$\sigma_\beta(Y) = \sum_i \eta_i \sigma(u_i), \quad (12)$$

where the η_i 's are the combinations of b_N and the $\sigma(u_i)$ are obtained using standard estimators, then

$$\Delta_\beta = \left| \frac{d\alpha_s}{dY} \sigma_\beta(Y) \right| \quad (13)$$

or in small steps

$$\Delta_\beta^3 = \left| \frac{d\alpha_s(\delta_k)}{dY} \sigma_\beta(Y) \right|. \quad (14)$$

The other ingredients to the evolution are the matching conditions at flavor thresholds...

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- The [Appelquist and Carazzone, 1975] theorem does not hold in its naive form when a mass-independent renormalization scheme is employed.
- The solution comes in the form of matching conditions obtained by explicitly decoupling using the methods of effective field theory [Weinberg, 1980], for a_s

$$a'_s = a_s \left(1 + \sum_{n=1}^{\infty} k_n(l) a_s^n \right) \quad (15)$$

- k_2 [Larin et al., 1995], k_3 [Chetyrkin et al., 1997], k_4 [Kniehl et al., 2006] (fully analytical)
- For consistency, 4-loop running is accompanied by 3-loop matching, we take the last coefficient used to match as a systematic uncertainty
- The quark masses carry another source of uncertainty

$$m_b(m_b) = 4.199 \pm 0.024 \quad \text{GeV}$$

$$m_c(m_c) = 1.274^{+0.030}_{-0.035} \quad \text{GeV}$$

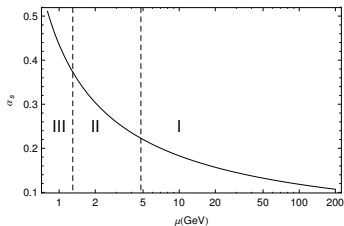
(16)

There are two main options in the literature to evolve the coupling with m_c and m_b threshold [Rodrigo et al., 1998] when the evolution goes from $m_\tau = 1.7768\text{GeV}$ [Beringer et al., 2012] to $M_Z = 91.1876\text{GeV}$ [Schael et al., 2006]

$$\alpha_3(m_\tau) \rightarrow \alpha_4(m_\tau) \rightarrow \alpha_4(m_b) \rightarrow \alpha_5(m_b) \rightarrow \alpha_5(M_Z) \quad (17)$$

or we can run to m_c , implement matching conditions and turn back to m_τ , i.e.,

$$\alpha_3(m_\tau) \rightarrow \alpha_3(m_c) \rightarrow \alpha_4(m_c) \rightarrow \alpha_4(m_\tau) \rightarrow \alpha_4(m_b) \rightarrow \alpha_5(m_b) \rightarrow \alpha_5(M_Z) \quad (18)$$



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- We evolve from m_τ to M_Z fixing $\alpha_s(m_\tau) = 0.3300$ without the uncertainties in the extraction.
- We choose the second option using one particular estimation for the beta function truncation

$$\begin{aligned} \alpha_{(nf=5)}(M_Z) = & 0.11998 \pm (1.919 \times 10^{-4})_\beta^1 \pm (0.303 \times 10^{-4})_{\text{th}}^{m_c} \\ & \pm (0.151 \times 10^{-4})_{\text{th}}^{m_b} + (\begin{matrix} +0.451 \\ -0.527 \end{matrix} \times 10^{-4})_{m_c} \\ & \pm (0.103 \times 10^{-4})_{m_b} \pm (0.317 \times 10^{-4})_{\text{it}} \end{aligned} \quad (19)$$






Using the other possibilities we get a Table the final result reads

$$\begin{aligned} \alpha_{(nf=5)}(M_Z) = & 0.11998 \pm (1.679 \times 10^{-4})_{\text{tot}} + (\begin{matrix} +0.451 \\ -0.527 \end{matrix} \times 10^{-4})_{m_c} \\ & \pm (0.103 \times 10^{-4})_{m_b} \end{aligned} \quad (20)$$

| μ | $n_f=3$ | | $n_f=4$ | | $n_f=5$ |
|-------------------------------|----------|---------|----------|---------|---------|
| | m_τ | m_c | m_τ | m_b | M_Z |
| $\alpha_s^{(n_f)}(\mu)$ | 0.33 | 0.41562 | 0.33672 | 0.23221 | 0.11998 |
| $\alpha_s^{(n_f+1)}(\mu)$ | | 0.41381 | | 0.23196 | |
| $\Delta_\beta \times 10^{-4}$ | | | | | |
| $\beta_4 = 100$ | | | | | |
| Δ_β^1 | | 5.440 | 2.854 | 4.862 | 1.919 |
| Δ_β^2 | | 5.388 | 2.950 | 3.928 | 1.575 |
| Δ_β^3 | | 1.946 | 0.756 | 3.299 | 1.260 |
| β_4^{WAPAP} | | | | | |
| Δ_β^1 | | 3.184 | 1.330 | 4.875 | 1.968 |
| Δ_β^2 | | 3.133 | 1.424 | 3.942 | 1.625 |
| Δ_β^3 | | 0.922 | 0.067 | 3.317 | 1.287 |

| | | | | | |
|--------------------------------------|---------------------------|------------------|------------------|------------------|------------------|
| $\Delta_{\text{th}} \times 10^{-4}$ | $\Delta_{\text{th}}(m_c)$ | 6.911 | 4.316 | 1.911 | 0.303 |
| | $\Delta_{\text{th}}(m_b)$ | 2.148 | 1.341 | 0.594 | 0.151 |
| $\Delta_m \times 10^{-4}$ | Δ_{m_c} | +6.422 -7.492 | +4.008 -4.676 | +1.775 -2.071 | +0.451 -0.527 |
| | Δ_{m_b} | 1.442 | 0.914 | 0.405 | 0.103 |
| $\Delta_{\text{it}} \times 10^{-4}$ | | 1.285 | 0.923 | 1.073 | 0.317 |
| $\Delta_{\text{tot}} \times 10^{-4}$ | | ± 8.009 | ± 4.853 | ± 4.675 | ± 1.679 |
| | | +6.422 -7.492 | +4.008 -4.676 | +1.775 -2.071 | +0.451 -0.527 |
| | | ± 1.442 | ± 0.914 | ± 0.405 | ± 0.317 |

Thanks!

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