

# A Riemann-Hilbert approach to rotating attractors and extremal black holes

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# Outline

- ▶ Stationary-axisymmetric solutions and 2d sigma models
- ▶ The Breitenlohner-Maison linear system
- ▶ Riemann-Hilbert problems
- ▶ Explicit factorization

Based on: M.C. Câmara, G.L. Cardoso, T.M. and S. Nampuri,  
arXiv:1703.10366.

## Motivation and Objectives

Systematic construction of solutions with non-trivial dependence on  $> 1$  coordinates (i.e. solving PDEs rather than ODEs).

Specifically: rotating black holes and their near horizon asymptotic attractor geometries.

Integrability and hidden symmetries in gravitational theories.

Specifically: Breitenlohner-Maison linear system, Geroch group.

Establish a factorization method which allows higher order poles of the monodromy matrix in the spectral parameter, and space-time geometries which are not asymptotically flat: attractors and extremal black holes. Proof of concept.

Obtain explicit matrix factorisation using 'vectorial' auxiliary problem  $\rightarrow$  explicit solution of both space-time equations of motion and of linear system.

Use hidden, infinite-dimensional symmetries to relate and generate solutions.

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## Selected earlier work

- ▶ P. Breitenlohner and D. Maison, *On the Geroch Group*, Ann. Inst. H. Poincaré Phys. Theor. **46** (1987) 215.
- ▶ H. Nicolai, *Two-dimensional gravities and supergravities as integrable systems*, in: Lect. Notes Phys. **396** (1991) 231.
- ▶ D. Katsimpouri, A. Kleinschmidt, and A. Virmani, JHEP **02** (2013) 011, JHEP **03** (2014) 101, JHEP **12** (2014) 070.
- ▶ B. Chakrabarty and A. Virmani, JHEP **11** (2014) 068.

See paper for a more complete list of references.

# Assumptions

$n$ -dimensional gravity coupled to matter.

- ▶  $n - 2$  commuting Killing vectors. (We'll take one to be time-like.)
- ▶ Resulting two-dimensional (Euclidean) theory is a generalized ('Ernst') sigma model with symmetric target space  $G/H$ .

Specifically

1. Pure 4d gravity:  $G/H = SL(2, \mathbb{R})/SO(2)$ .
2. 4d Einstein-Maxwell:  $G/H = SU(2, 1)/(SL(2, \mathbb{R}) \times SO(2))$ .
3. Pure 5d gravity:  $G/H = SL(3, \mathbb{R})/SO(2, 1)$ .

## Symmetric spaces

$G$  simple real Lie group with Lie algebra  $\mathfrak{g}$ .  $H \subset G$  maximal Lie subgroup (not necessarily compact) with Lie algebra  $\mathfrak{h}$ . Symmetric decomposition:  $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{p}$ .

- ▶ Involution automorphism:

$$\theta(Z) = Z, \forall Z \in \mathfrak{h}, \quad \theta Z = -Z, \forall Z \in \mathfrak{p}.$$

- ▶ Generalized transposition:  $Z^{\natural} = -\theta(Z)$

$$Z^{\natural} = -Z, \forall Z \in \mathfrak{h}, \quad Z^{\natural} = Z, \forall Z \in \mathfrak{p},$$

At group level:  $h^{\#} = h^{-1}, \forall h \in H, \quad g^{\#} = g, \forall g \in \exp \mathfrak{p}$ .

Note:  $\natural$  acts anti-homomorphically  $(g_1 g_2)^{\natural} = g_2^{\natural} g_1^{\natural}$ .

## $G/H$ sigma models

We take  $G$  to be given as a matrix group.  $V(x)$  is  $G$ -(matrix)-valued function on space-time  $(N, g_N)$ .

'Gauge'  $H \subset G$ :  $V(x) \simeq h(x)V(x)$ .

$G$  acts as a 'rigid' symmetry:

$$H \times G : V(x) \mapsto h(x)V(x)g^{-1} .$$

Metric on  $G/H$  induced by (right- or left-invariant) MC form on  $G$ , is pulled back to space-time to define the action:

$$S[g_N, V] = \int d^p x \sqrt{|g_N|} \left( \frac{1}{2} R[g_N] - g_N^{mn} \text{Tr}(D_m V V^{-1} D_n V V^{-1}) \right) .$$

$D$  is LC connection wrt  $g_N$  and  $H$ -covariant connection wrt target space. Trace  $\text{Tr}$  might include a numerical factor.



Explicit parametrizations:

- ▶ Impose gauge condition on  $V(x)$ , for example 'Borel gauge' using the Iwasawa decomposition,  $G = HL$ , where  $L$  triangular. (If  $H$  not compact, use triangular subgroup acting with open orbit on  $G/H$ ).
- ▶ Use  $\mathfrak{h}$ -symmetric,  $H$ -gauge invariant representative:

$$M(x) = V^{\mathfrak{h}}(x)V(x)$$

$$H \times G : M(x) \mapsto g^{\mathfrak{h}, -1} M(x) g^{-1}$$

Equation of motion = current conservation for rigid  $G$  symmetry:

$$D^m A_m = D^m (M^{-1} \partial_m M) = 0 \Leftrightarrow d \star A = 0, \quad A = M^{-1} dM.$$

## Symmetry enhancement in $d = 2$ .

Two dimensions: one-forms  $\star$ -dual to one-forms. Hidden symmetries ('Twist potentials.')

$$d \star A = 0 \Rightarrow A = \star dX_1$$

Observe:

$$\text{Define: } J_1 := (d + A)X_1 \quad \text{Find: } d \star J_1 = 0 \Rightarrow J_1 = \star dX_2 \dots$$

$$\text{Define: } J_k = (d + A)X_k \quad \text{Find: } d \star J_k = 0 \Rightarrow J_k = \star dX_{k+1} \dots$$

To derive this hierarchy of conserved currents, the only equation needed apart from previously obtained relations, is the flatness of  $A = M^{-1}dM$ ,  $dA + A \wedge A = 0$ .

Natural to introduce generating functions

$$J(\tau, x) = A\tau + \sum_{k=1}^{\infty} J_k \tau^{k+1}$$

$$X(\tau, x) = \mathbb{I} + \sum_{k=1}^{\infty} X_k \tau^k$$

The relations between currents and potentials combine into the linear system

$$J = \tau(d + A)X = \star dX$$

which has the combined conservation equations  $d \star J = 0$  as integrability condition. This includes the sigma model equation of motion  $d \star A = 0$ , which is the conservation equation for rigid  $G$ -symmetry.

Enhanced, infinite-dimensional 'rigid' symmetry group is identified as the loop group  $\tilde{G}$  associated to  $G$ , with Lie algebra  $\tilde{\mathfrak{g}}$ .

Note i.p. that  $J(x) \in \tilde{\mathfrak{g}}$ , and  $X(x) \in \tilde{G}$ .

## Generalized ('Ernst') sigma models

Reduction from four to two dimensions:

$$\begin{aligned} ds_4^2 &= -\Delta(dy + B_m dx^m) + \Delta^{-1} ds_3^2 \\ ds_3^2 &= e^\psi ds_2^2 + \rho^2 d\phi^2 \end{aligned}$$

where  $\Delta$ ,  $\psi$ ,  $\rho$ ,  $B_m$  are functions on  $(N_2, ds_2^2)$ .

Remaining two-dimensional field equations:

$$d(\rho \star A) = 0, \quad d \star d\rho = 0.$$

Field equation for  $A$  modified by  $\rho$ .

NB:  $\Delta$ ,  $B_m$  have been absorbed into  $A = M^{-1}dM$ .

NB: Equation for  $\psi$  is integrable, given  $A, \rho$ .

## The spectral curve

The modified field equation

$$d(\rho \star A) = 0$$

is still the integrability of the linear system

$$J = \tau(d + A)X = \star dX$$

provided that the ‘spectral parameter’  $\tau$  becomes a function on  $(N_2, ds_2^2)$ , and satisfies

$$\omega = i(f - \bar{f}) + \frac{f + \bar{f}}{2\tau}(1 - \tau^2),$$

where  $\omega \in \mathbb{C}$  is called the ‘constant’ (space-time independent) spectral parameter, and where  $\rho = f + \bar{f}$  is a solution of  $d \star d\rho = 0$ .

The relation between  $\omega$  and  $\tau$  defines the 'spectral curve.' Assume that we can choose Weyl coordinates  $x = (\rho, v)$ , where  $v$  is chosen such that  $f = \frac{1}{2}(\rho - iv)$  (i.e.  $\star d\rho = -dv$ ) and consequently  $ds_2^2 = d\rho^2 + dv^2$ :

$$\tau(\omega, x) = \frac{1}{\rho} \left( v - \omega \pm \sqrt{\rho^2 + (v - \omega)^2} \right), \quad \text{for } \rho \neq 0.$$

## The monodromy matrix

Given a solution  $M(x) = V^{\natural}(x)V(x)$  of the field equations, and a solution  $X(\tau, x)$  of the linear system, one can define 'spectral deformations' of  $V(x)$  and  $M(x)$ :

$$\mathcal{P}(\tau, x) = V(x)X(\tau, x), \quad \mathcal{M}(\tau, x) = \mathcal{P}^{\natural}(-1/\tau, x)\mathcal{P}(\tau, x).$$

The 'monodromy matrix' only depends on the constant spectral parameter:

$$\mathcal{M}(\tau(\omega, x), x) = \mathcal{M}(\omega)$$

If the solution  $X(\tau, x)$  satisfies  $X(0, x) = \mathbb{I}$ , then the monodromy matrix  $\mathcal{M}(\omega)$  satisfies a canonical Riemann-Hilbert factorisation problem.

Conversely, given a matrix function  $\mathcal{M}(\omega) = \mathcal{M}^{\natural}(\omega)$  which admits a canonical factorization, we obtain a solution to the linear system, and to the field equations.



# Riemann-Hilbert problems

Ingredients:

- ▶  $\Gamma$ : closed simple contour in  $\mathbb{C}$ , taken to be the unit circle.  $D_{\pm}$  interior/exterior of  $\Gamma$ .
- ▶  $n \times n$  matrix function  $\mathcal{M}$ , defined and continuous with continuous inverse  $\mathcal{M}^{-1}$  on  $\Gamma$ .

We seek a *canonical* Birkhoff decomposition (aka Wiener Hopf factorization) on  $\Gamma$ ,

$$\mathcal{M} = M_- M_+$$

where  $M_+$ ,  $M_+^{-1}$  are bounded and analytic on  $D_+$  and where  $M_-$ ,  $M_-^{-1}$  are bounded and analytic on  $D_-$ .

A general ('non-canonical') factorization takes the form

$$\mathcal{M} = M_- D M_+ , \quad D = \text{diag}(\tau^{k_j})_{j=1, \dots, n}$$

with 'partial indices'  $k_j \in \mathbb{Z}$ . For the existence of a non-canonical factorization it is sufficient that  $\mathcal{M}, \mathcal{M}^{-1}$  have Hölder continuous components.

But we must require a *canonical* factorization, where all partial indices are zero.

**Theorem:**  $\mathcal{M} \in C_\alpha^{n \times n}$  admits a canonical factorization if and only if

1.  $\det \mathcal{M}$  admits a (scalar) canonical factorization,

$$\det \mathcal{M} = \gamma_- \gamma_+, \quad \gamma_-^{\pm 1} \in C_\alpha^-, \quad \gamma_+^{\pm 1} \in C_\alpha^+.$$

2. The vectorial Riemann-Hilbert problem

$$\mathcal{M} \phi_+ = \phi_-, \quad \phi_\pm \in (C_\alpha^\pm)^{n \times 1}, \quad \phi_-(\infty) = 0$$

has only the trivial solution.

Remark: While implied by known results (and probably 'well known' to experts in Riemann-Hilbert problems), this theorem has to our knowledge not been formulated (and proved) before and in the above form.

Notation:

- ▶  $C_\alpha = C_\alpha(\Gamma)$  Hölder continuous functions.
- ▶  $C_\alpha^\pm$ : functions in  $C_\alpha$  admitting a bounded analytic extension to  $D_\pm$

Canonical factorizations are unique up to a constant matrix factor.  
Fix solution by imposing:

$$M_+(0) = \mathbb{I} .$$

Notation  $M_+ = X$  for normalized canonical factorization.

The map  $\tau \rightarrow -1/\tau$  exchanges the interior and exterior of the unit circle, and the two Riemann sheets of  $\tau(\omega, x)$ . The constant spectral parameter  $\omega$  is invariant.

Recovering solutions from monodromy matrices:

$$\mathcal{M}(\omega) = M_-(\tau, x)M_+(\tau, x) = X^{\natural}(-1/\tau, x)M(x)X(\tau, x) .$$

Note that

$$M_+(\tau, x) = X(\tau, x) , \quad M_-(\infty, x) = M(x)$$

are solutions to the linear system and to the field equations, respectively.

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In fact, any  $\mathfrak{h}$ -symmetric matrix function  $\mathcal{M}(\omega)$  which admits a canonical factorization with  $\omega$  and  $(\tau, x)$  related by the spectral curve provides a solution to the linear system and to the field equations.

Proof: see Section 6 of our paper. Important stepping stone is the equivalent form

$$dXX^{-1} = -\frac{\tau}{1+\tau^2} \star A - \frac{\tau^2}{1+\tau^2} A$$

of the linear system  $\tau(d + A)X = \star dX$ .

N.B. Breitenlohner and Maison use the corresponding expression involving  $\mathcal{P}(\tau, x) = V(x)X(\tau, x)$ :

$$d\mathcal{P}\mathcal{P}^{-1} = Q + \frac{1-\tau^2}{1+\tau^2} P - \frac{2\tau}{1+\tau^2} \star P$$

where  $A = Q + P \in \mathfrak{h} \oplus \mathfrak{p}$ .

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## Group theoretical interpretation

Here I follow Breitenlohner-Maison and Nicolai.

Extend involution  $\theta$  to  $\tilde{\mathfrak{g}} \ni \delta g(\tau)$  by

$$\tilde{\theta}(\delta g(\tau)) = \theta(\delta g)(-1/\tau)$$

Invariant subalgebra  $\tilde{\mathfrak{h}}$  defined by  $\tilde{\theta}$ -invariance,  
 $\tilde{\theta}((\delta h)(\tau)) = \theta(\delta h)(-1/\tau) = h(\tau)$ :

$$\delta h(\tau) = \delta h_0 + \sum_{n=1}^{\infty} \delta h_n \left( \tau^n + (-1)^n \frac{1}{\tau^n} \right) + \sum_{n=1}^{\infty} \delta p_n \left( \tau^n - (-1)^n \frac{1}{\tau^n} \right),$$

$$\delta h_n \in \mathfrak{h}, \delta p_n \in \mathfrak{p}.$$



Define infinitesimal action of infinite-dimensional rigid symmetry group  $\tilde{G}$  and of infinite-dimensional gauge group  $\tilde{H}$  on  $\mathcal{P}(\tau, x) = V(x)X(\tau, x)$  by

$$\mathcal{P}(\tau, x) \mapsto \delta h(\tau, x)\mathcal{P}(\tau, x) - \mathcal{P}(\tau, x)\delta g^{-1}(\omega)$$

NB: both spectral parameters occur in this construction.

Define 'infinite-dimensional coset space'  $\tilde{G}/\tilde{H}$  by

$$\mathcal{P}(\tau, x) \simeq h(\tau, x)\mathcal{P}(\tau, x), \quad h(\tau, x) \in H.$$

Breitenlohner-Maison:  $\tilde{G}/\tilde{H} =$  space of solutions of the linear system. Further explanation (Nicolai):  $d\mathcal{P}\mathcal{P}^{-1} \in \tilde{\mathfrak{h}}$  'suggests' that  $\mathcal{P} = h(\tau, x)g^{-1}(\omega)$ .

Comment: to be able to extract the space-time solution, we need to choose  $h(\tau, x)$  such that  $\mathcal{P}(\tau, x)$  is regular at  $\tau = 0$ . ('Generalized Borel gauge'). This property is not preserved under  $\tilde{H}$  gauge transformations.

The Riemann-Hilbert problem picks the unique representative out of an  $\tilde{H}$ -orbit which is regular (and normalized) at  $\tau = 0$

$$X(0, x) = M_+(0, x) = \mathbb{I}$$

and thus allows to obtain a corresponding space-time solution as

$$M(x) = M_-(\infty, x) .$$

## Our Method of explicit factorization

*Lemma:* Let  $\phi_1 = r_1\phi_+$ ,  $\phi_2 = r_2\phi_-$  where  $r_1, r_2$  are rational functions, bounded on  $\Gamma$ , and  $\phi_+, \phi_- \in C_\alpha^\pm$  do not vanish at any of the poles of  $r_1$  in  $D_+$ ,  $r_2$  in  $D_-$ , respectively. If  $\phi_1 = \phi_2$  on  $\Gamma$ , then both  $\phi_1$  and  $\phi_2$  are equal to a rational function whose poles are the poles of  $r_1$  in  $D_+$  and  $r_2$  in  $D_-$  (including  $\infty$ ), counting their multiplicity.

## Explicit canonical factorization example 1

Coset:  $G/H = SU(2, 1)/SL(2, \mathbb{R}) \times U(1)$ ,

Theory: Einstein-Maxwell.

Monodromy matrix:

$$\mathcal{M}(\omega) = \frac{1}{\omega^2} \begin{pmatrix} \frac{1}{2}|a|^2 & a\omega & \omega^2 \\ -\bar{a}\omega & -\omega^2 & 0 \\ \omega^2 & 0 & 0 \end{pmatrix}, \det \mathcal{M} = 1, \mathcal{M}^\sharp(\omega) = \mathcal{M}(\omega),$$

where  $a \in \mathbb{C}$ .

Observe: double pole at  $\omega = 0$ , bounded for  $\omega \rightarrow \infty$ , triangular structure.

Write factorization problem in the form

$$\mathcal{M}(\omega) M_+^{-1} = M_- \quad , \quad \tau \in \Gamma .$$

Start with vectorial factorization problem for the first column:

$$\frac{1}{\omega^2} \begin{pmatrix} \frac{1}{2}|a|^2 & a\omega & \omega^2 \\ -\bar{a}\omega & -\omega^2 & 0 \\ \omega^2 & 0 & 0 \end{pmatrix} \begin{pmatrix} \phi_{1+} \\ \phi_{2+} \\ \phi_{3+} \end{pmatrix} = \begin{pmatrix} \phi_{1-} \\ \phi_{2-} \\ \phi_{3-} \end{pmatrix},$$

Normalization conditions:

$$M_+^{-1}(\tau = 0) = \mathbb{I} \Rightarrow \phi_{1+}(0) = 1, \quad \phi_{2+}(0) = \phi_{3+}(0) = 0.$$

Compare third component:  $\phi_{1+} = \phi_{3-}$  for  $\tau \in \Gamma$ , with  $\phi_{1+} \in C_+^\alpha$ ,  $\phi_{3-} \in C_-^\alpha$ .

Liouville's theorem plus normalization condition:

$$\phi_{1+} = \phi_{3-} = K = 1.$$

Compare second component (using previous result):

$$-\frac{\bar{a}}{\omega} - \phi_{2+} = \phi_{2-} \quad , \quad \tau \in \Gamma .$$

Decompose  $\omega$  using the spectral curve:

$$\omega = -\frac{\rho}{2} \frac{(\tau - \tau_0^+)(\tau - \tau_0^-)}{\tau} ,$$

where  $\tau_0^\pm \in D_\pm$ . Use decomposition into partial fractions

$$\frac{\tau}{(\tau - \tau_0^+)(\tau - \tau_0^-)} = \frac{A}{(\tau - \tau_0^+)} + \frac{B}{(\tau - \tau_0^-)}$$

$$A = \frac{\tau_0^+}{\tau_0^+ - \tau_0^-} \quad , \quad B = -\frac{\tau_0^-}{\tau_0^+ - \tau_0^-} .$$

and re-arrange terms such that  $C_+^\alpha$ -functions and  $C_-^\alpha$ -functions are on different sides of the equation. Then use Liouville and normalization conditions:

$$\frac{2\bar{a}}{\rho} \frac{B}{(\tau - \tau_0^-)} - \phi_{2+} = \phi_{2-} - \frac{2\bar{a}}{\rho} \frac{A}{(\tau - \tau_0^+)} = k = -\frac{2\bar{a}}{\rho} \frac{B}{\tau_0^-} .$$

From this we obtain  $\phi_{2+}$  and  $\phi_{2-}$ . Continue until  $M_+^{-1}$  and  $M_-$  have been determined.

In this particular example we find

$$M_+^{-1}(\tau, x) = \begin{pmatrix} 1 & 0 & 0 \\ \frac{-2\bar{a}}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{\tau - \tau_0^-} & 1 & 0 \\ \frac{2|a|^2}{\rho^2(\tau_0^+ - \tau_0^-)^2} \frac{\tau^2}{(\tau - \tau_0^-)^2} & \frac{-2a}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{\tau - \tau_0^-} & 1 \end{pmatrix}$$

as well as

$$M_-(\tau, x) = \begin{pmatrix} \frac{2|a|^2}{\rho^2(\tau_0^+ - \tau_0^-)^2} \frac{\tau^2}{(\tau - \tau_0^+)^2} & \frac{-2a}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{\tau - \tau_0^+} & 1 \\ \frac{2\bar{a}}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{\tau - \tau_0^+} & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$



Extract space-time solution:

$$M(x) = M_-(\tau = \infty, x) = \begin{pmatrix} \frac{|a|^2}{2(\rho^2+v^2)} & \frac{a}{\sqrt{\rho^2+v^2}} & 1 \\ \frac{-\bar{a}}{\sqrt{\rho^2+v^2}} & -1 & 0 \\ 1 & 0 & 0 \end{pmatrix} .$$

Expression in four-dimensional coordinates  $(t, r, \theta, \phi)$ , where  $\rho = r \sin \theta$ ,  $v = r \cos \theta$ :

$$ds_4^2 = -e^{-\varphi} dt^2 + e^{\varphi} (dr^2 + r^2(d\theta^2 + \sin^2 \theta d\phi^2)) , \quad e^{-\varphi} = \frac{r^2}{|Q|^2} ,$$

where  $Q = q + ip = a/\sqrt{2}$  combines electric and magnetic charge.  
Potentials for electromagnetic field:

$$\chi_e(r) = \frac{q}{|Q|^2} r , \quad \chi_m(r) = \frac{p}{|Q|^2} r .$$

Static attractor solution  $AdS_2 \times S^2$  with covariantly constant electromagnetic field (Bertotti-Robinson).

## Explicit canonical factorization example 2

Coset:  $G/H = SL(3, \mathbb{R})/SO(2, 1)$ .

Theory: 5d gravity  $\rightarrow$  4d Einstein-Maxwell-Scalar.

Mondromy matrix:

$$\mathcal{M}(\omega) = \frac{1}{\omega^2} \begin{pmatrix} A & B\omega & C\omega^2 \\ -B\omega & D\omega^2 & 0 \\ C\omega^2 & 0 & 0 \end{pmatrix}$$

$A, B, C, D \in \mathbb{R}$ , where  $-C^2D = 1$ . Again: second order pole at  $\omega = 0$ , bounded at  $\omega \rightarrow \infty$ , triangular structure.

Factorization:

$$M_-(\tau, x) = \begin{pmatrix} m_{11} & -\frac{2B}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{(\tau - \tau_0^+)} & C \\ \frac{2B}{\rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{(\tau - \tau_0^+)} & D & 0 \\ C & 0 & 0 \end{pmatrix},$$

$$M_+^{-1}(\tau, x) = \begin{pmatrix} 1 & 0 & 0 \\ \frac{2B}{D \rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{(\tau - \tau_0^-)} & 1 & 0 \\ m_{31} & -\frac{2B}{C \rho(\tau_0^+ - \tau_0^-)} \frac{\tau}{\tau - \tau_0^-} & 1 \end{pmatrix}.$$

where  $m_{11}, m_{31}$  are given in our paper.

Space-time solution:

$$M(\rho, \nu) = \frac{1}{\rho^2 + \nu^2} \begin{pmatrix} A + \frac{(2AD+B^2)}{2D} \left( \frac{\nu}{\sqrt{\rho^2 + \nu^2}} - 1 \right) & B \sqrt{\rho^2 + \nu^2} & C(\rho^2 + \nu^2) \\ -B \sqrt{\rho^2 + \nu^2} & D(\rho^2 + \nu^2) & 0 \\ C(\rho^2 + \nu^2) & 0 & 0 \end{pmatrix}.$$

Four-dimensional coordinates  $(t, r, \theta, \phi)$ :

$$ds_4^2 = -\frac{r^2}{v_1(\theta)} \left( dt - \frac{J \sin^2 \theta}{8\pi r} d\phi \right)^2 + v_1(\theta) \left( \frac{dr^2}{r^2} + d\theta^2 + \sin^2 \theta d\phi^2 \right)$$

$$v_1(\theta) = \frac{1}{8\pi} \sqrt{P^2 Q^2 - J^2 \cos^2 \theta}.$$

$(A, B, C, D) \leftrightarrow (Q, P, J)$ , electric/magnetic charges and angular momentum.

Scalar field:

$$e^{2\phi_1/\sqrt{3}} = \left( \frac{P}{Q} \right)^{2/3} \frac{PQ - J \cos \theta}{PQ + J \cos \theta}.$$

Underrotating attractor solution.

Underrotating attractor = near horizon geometry of an extremal, underrotating black hole.

Underrotating:  $P^2 Q^2 > J^2$ , static limit  $J = 0$ , no ergoregion, scalar takes attractor values determined by  $Q, P, J$  at horizon, irrespective of its value at infinity (universal  $\theta$ -dependence).

Overrotating:  $J^2 > P^2 Q^2$ , have extremal Kerr limit  $PQ = 0$ , ergoregion, scalars do not necessarily attain fixed point values at the horizon, but entropy is still independent of values of scalars at infinity.

Rotating attractors (both under- and overrotating ones) have reduced isometry  $SL(2, \mathbb{R}) \times SO(2) \subset SL(2, \mathbb{R}) \times SO(3)$  compared to static attractors.

Reference for 'rotating attractors': D. Astefanasi, K. Goldstein, R.P. Jena, A. Sen and S.P. Trivedi, JHEP **10** (2006) 058.

Underrotating attractor = near horizon geometry of an extremal, underrotating black hole.

Underrotating:  $P^2 Q^2 > J^2$ , static limit  $J = 0$ , no ergoregion, scalar takes attractor values determined by  $Q, P, J$  at horizon, irrespective of its value at infinity (universal  $\theta$ -dependence).

Overrotating:  $J^2 > P^2 Q^2$ , have extremal Kerr limit  $PQ = 0$ , ergoregion, scalars do not necessarily attain fixed point values at the horizon, but entropy is still independent of values of scalars at infinity.

Rotating attractors (both under- and overrotating ones) have reduced isometry  $SL(2, \mathbb{R}) \times SO(2) \subset SL(2, \mathbb{R}) \times SO(3)$  compared to static attractors.

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Remark: the static attractor considered previously (though for a different  $G/H$ ) is contained as the special case where  $2AD + B^2 = 0 \Leftrightarrow J = 0$ . As far as factorization is concerned, finding underrotating attractors is as involved as finding static attractors.

Consistent with static attractors being a limiting case of the underrotating branch of extremal rotating solutions.



## Generating solutions 1. $G$ -action

$G$ -action is compatible with factorization. Given a factorization

$$\mathcal{M}_{\text{seed}} = M_-^{\text{seed}} M_+^{\text{seed}}$$

and  $g \in G$ , we obtain

$$\mathcal{M}(\omega) = M_- M_+ = (g^\sharp M_-^{\text{seed}} g)(g^{-1} M_+^{\text{seed}} g)$$

and

$$M(x) = g^\sharp M^{\text{seed}}(x) g .$$

Some  $g \in G$  just generate gauge transformations, i.p. constant shifts of scalar fields which correspond to electric or magnetic gauge potentials. NB: such gauge transformations do not preserve the 'triangular shape' we found useful in our examples.

Other  $g \in G$  correspond to Harrison-like transformations, which map near-horizon solutions to the corresponding full black holes solutions. We show this in particular for static and underrotating solutions.

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## Generating solutions 2. Full Geroch group

Action of  $g(\omega) \in \tilde{G}$  requires to solve a new factorization problem. We have studied i.p. the following deformation of an underrotating attractor

$$\mathcal{M}(\omega) = g^{\natural}(\omega) \mathcal{M}_{\text{seed}}(\omega) g(\omega) = \frac{1}{\omega^2} \begin{pmatrix} A & B\omega + \alpha & C\omega^2 \\ -B\omega - \alpha & D\omega^2 & 0 \\ C\omega^2 & 0 & 0 \end{pmatrix}$$

where

$$g(\omega) = e^{N/\omega^2}, \quad N = \begin{pmatrix} 0 & 0 & 0 \\ \beta & 0 & 0 \\ \mu & \gamma & 0 \end{pmatrix}.$$

and we have chosen  $\beta = \mu = 0$ , and  $\alpha = \gamma C$ .

This can be factorized (see paper) and yields a new space-time solution asymptotic to  $AdS_2 \times S^2$ . For a static seed solution, the new solution is regular, except at  $\rho = \nu = 0$  (where canonical factorization does not apply). Ricci scalar blows up, scalar runs away.

## How to find monodromy matrices to factorize?

How to choose  $\mathcal{M}(\omega)$  to start with? We have mostly relied on known solutions and the 'substitution rule' of Chakrabarty/Virman,

$$\mathcal{M}(\omega = \nu) = M(\rho = 0, \nu) .$$

Comment: the limit  $\rho \rightarrow 0^+$  is delicate, and the validity of the substitution rule requires that the limits

$$\lim_{\rho \rightarrow 0^+} \mathcal{M}(\omega(\tau, x)) = \left( \lim_{\rho \rightarrow 0^+} X^{\natural}(-1/\tau, x) \right) \left( \lim_{\rho \rightarrow 0^+} M(x) \right) \left( \lim_{\rho \rightarrow 0^+} X(\tau, x) \right)$$

exist individually. While it is not clear to us why this should hold in general, we have verified it to be true in all examples where  $M(x)$  itself has a limit (one example with singular limit of  $M(x)$ , where substitution rule cannot be applied, while a regular solution corresponding to the monodromy matrix does exist.)

Remark: It is known from Breitenlohner-Maison that the solution on the axis of rotation determines the solution uniquely.

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# Open Questions

- ▶ How to choose monodromy matrices that correspond to interesting space-time solutions? How are space-time properties encoded in the monodromy matrix?
- ▶ What can still be done in presence of a cosmological constant or scalar potential (gauged supergravity)?
- ▶ What can one learn about the 'stringy' Geroch group and hidden symmetries in supergravity and string theory?

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