

Precise Measurements and Shimming of Magnetic Field Gradients in the Low Field Regime

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for the MIXed collaboration

MIXed
Measurement and Investigation
of the
Xenon-129 electric dipole moment

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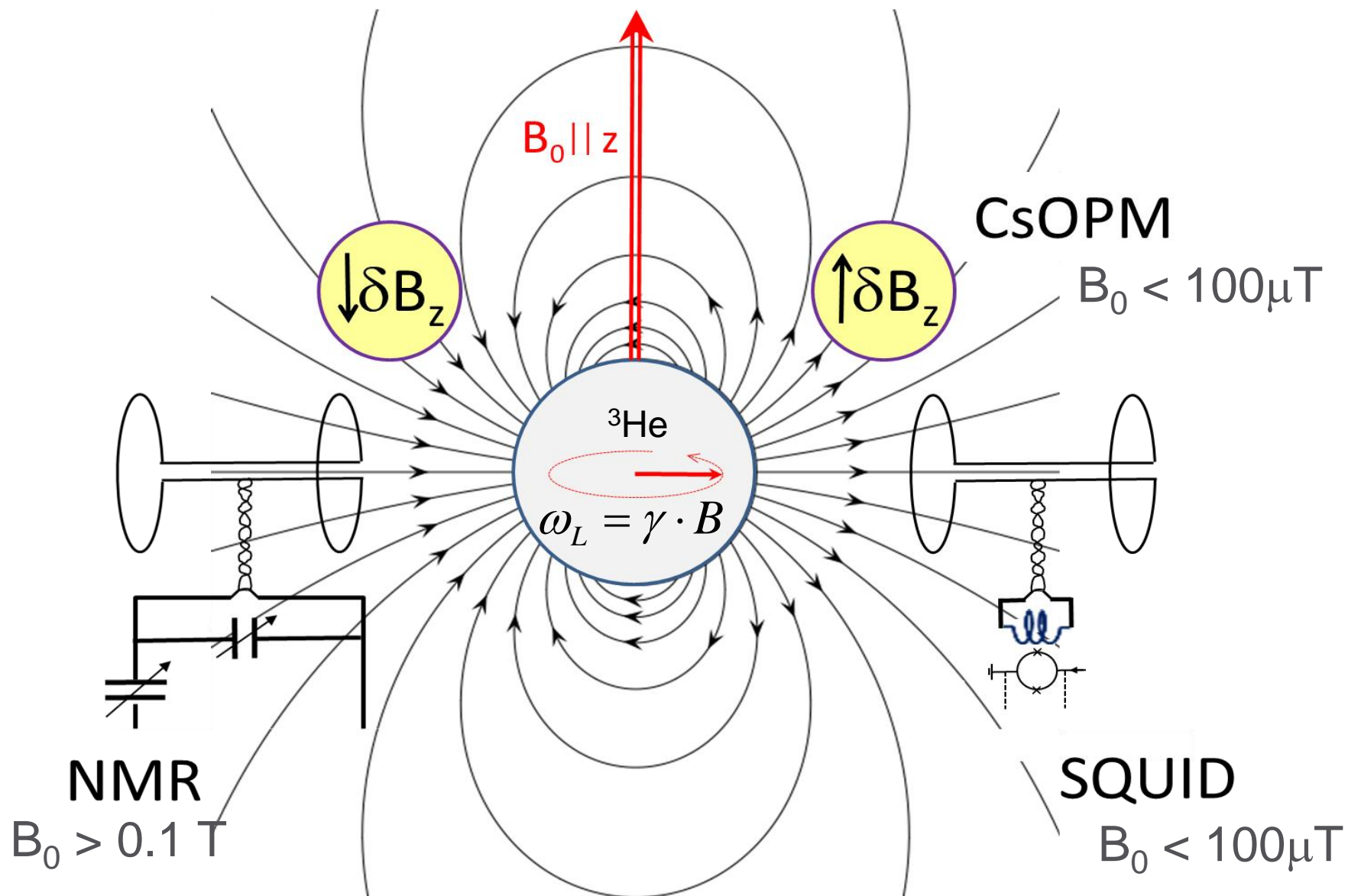
Forschungszentrum Jülich
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Motivation

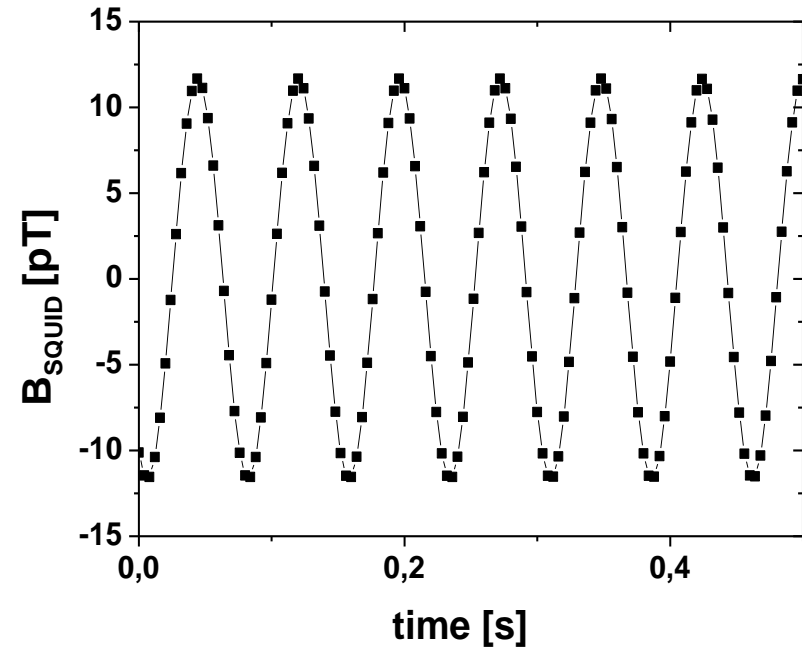
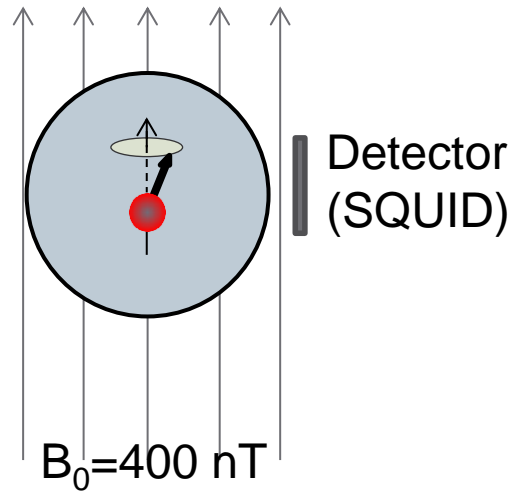
Characterization and compensation of magnetic field gradients is useful in many types of experiments:

- Fundamental physics
 - Measurement of Electric Dipole Moments (EDMs), e.g. Neutron or ^{129}Xe EDM
 - Resolution is partially limited by gradients
 - Systematic effects (false EDMs) due to gradients
- Applied physics
 - MR Imaging
 - MR Spectroscopy

Detection of free spin precession



Magnetometry with fT accuracy



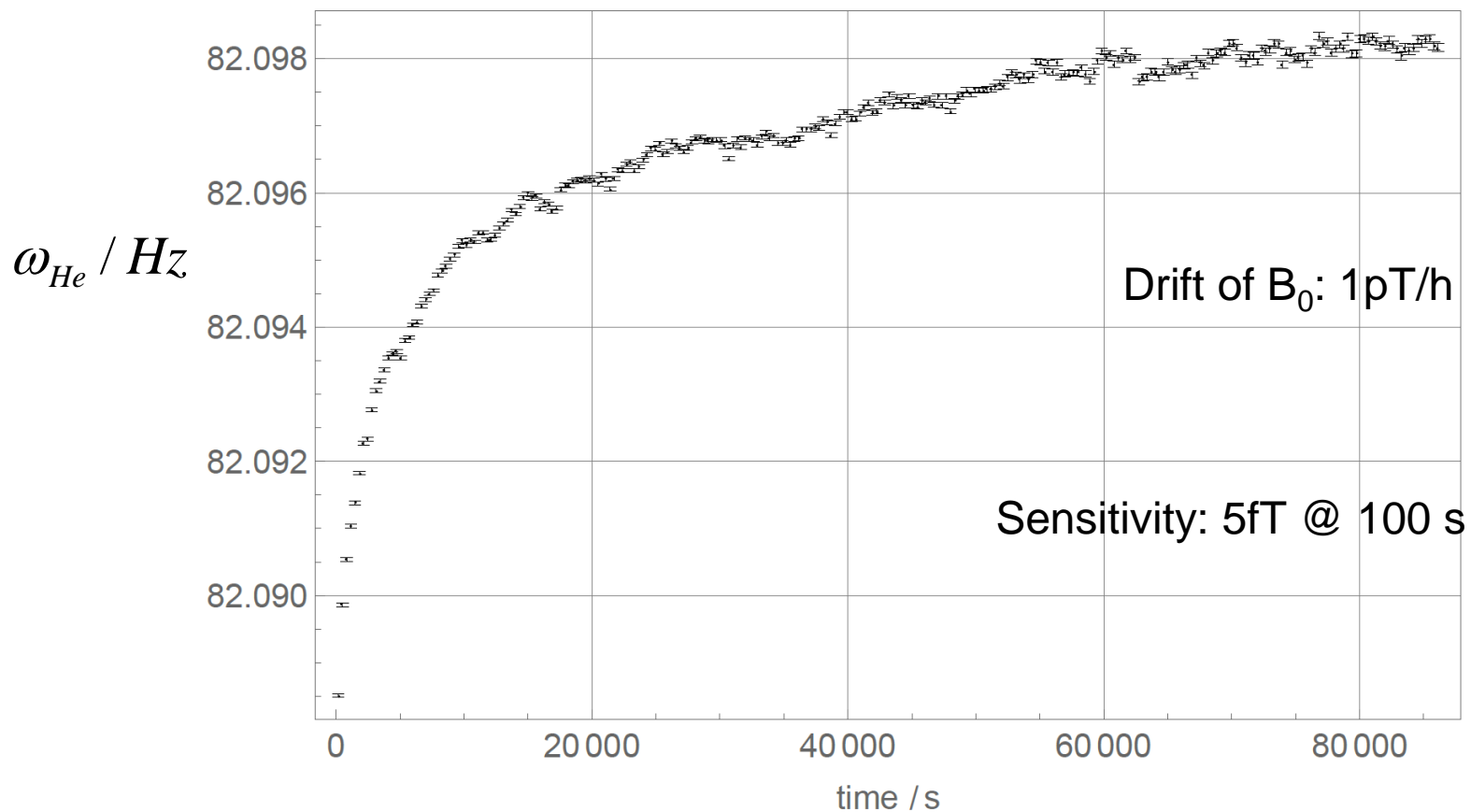
1) Monitoring of B_0 :

$$\omega_L = \gamma \cdot B_0$$

2) Monitoring of Gradients:

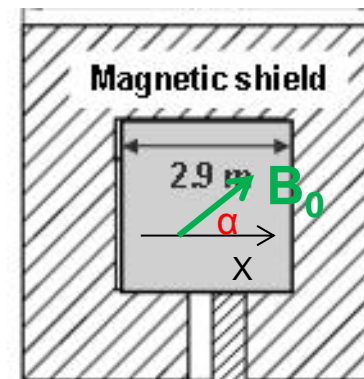
$$\frac{1}{T_2^*} = \frac{1}{T_1} + \frac{4R^4\gamma^2}{175D} \left(|\vec{\nabla} B_{1,y}|^2 + |\vec{\nabla} B_{1,z}|^2 + 2|\vec{\nabla} B_{1,x}|^2 \right)$$

1) Monitoring of B_0 over one day

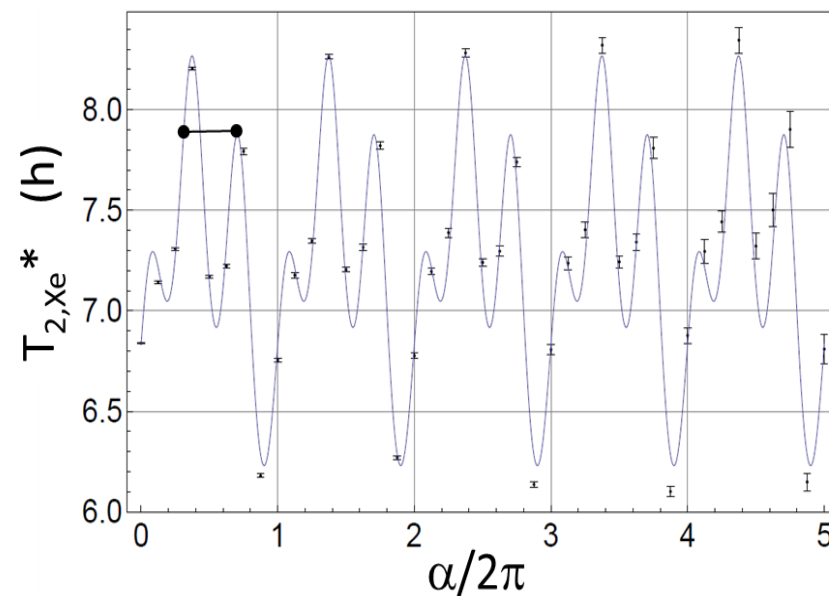
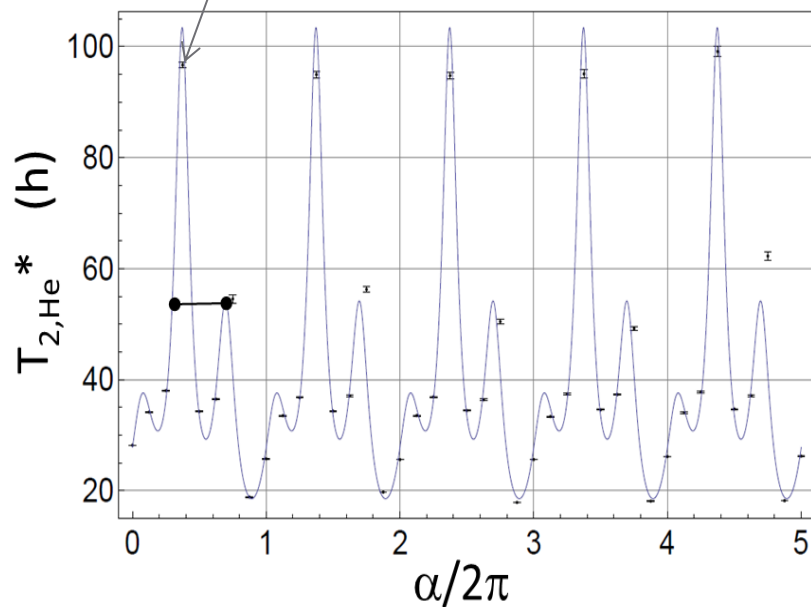


2) Sensitivity on field gradients

Setup at PTB Berlin



Gradients < 7 pT/cm



Gradient optimization for EDM experiments

- EDM resolution is determined by frequency resolution

$$d = \frac{h \Delta\omega}{2\pi 4E}$$

- Frequency resolution is determined by coherent measurement time, and thus spin coherence time

$$\sigma_f^2 \geq \frac{12}{(2\pi)^2 (A/\rho_\alpha)^2 T^3} C.$$

- Spin coherence time is (partially) determined by magnetic field gradients

$$\frac{1}{T_2^*} = \frac{1}{T_1} + \frac{4R^4\gamma^2}{175D} \left(|\vec{\nabla} B_{1,y}|^2 + |\vec{\nabla} B_{1,z}|^2 + 2 |\vec{\nabla} B_{1,x}|^2 \right)$$

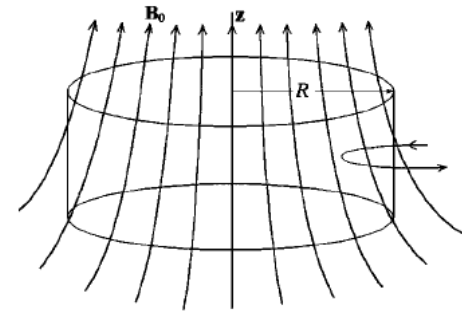
Systematic error: geometric phase

Motional (transverse) field

$$B_v = \frac{1}{c^2} \mathbf{E} \times \mathbf{v}$$

+

Magnetic transverse field



- Frequency shift correlated with electric field
- False EDM for Mercury (fast regime of GPE)

$$d_{\text{Hg}}^{\text{False}} = \frac{\hbar \gamma_{\text{Hg}}^2}{32c^2} D^2 \frac{\partial B}{\partial z}$$

Pendlebury et al,
PRA **70** 032102 (2004)

- False neutron EDM when using Hg comagnetometer

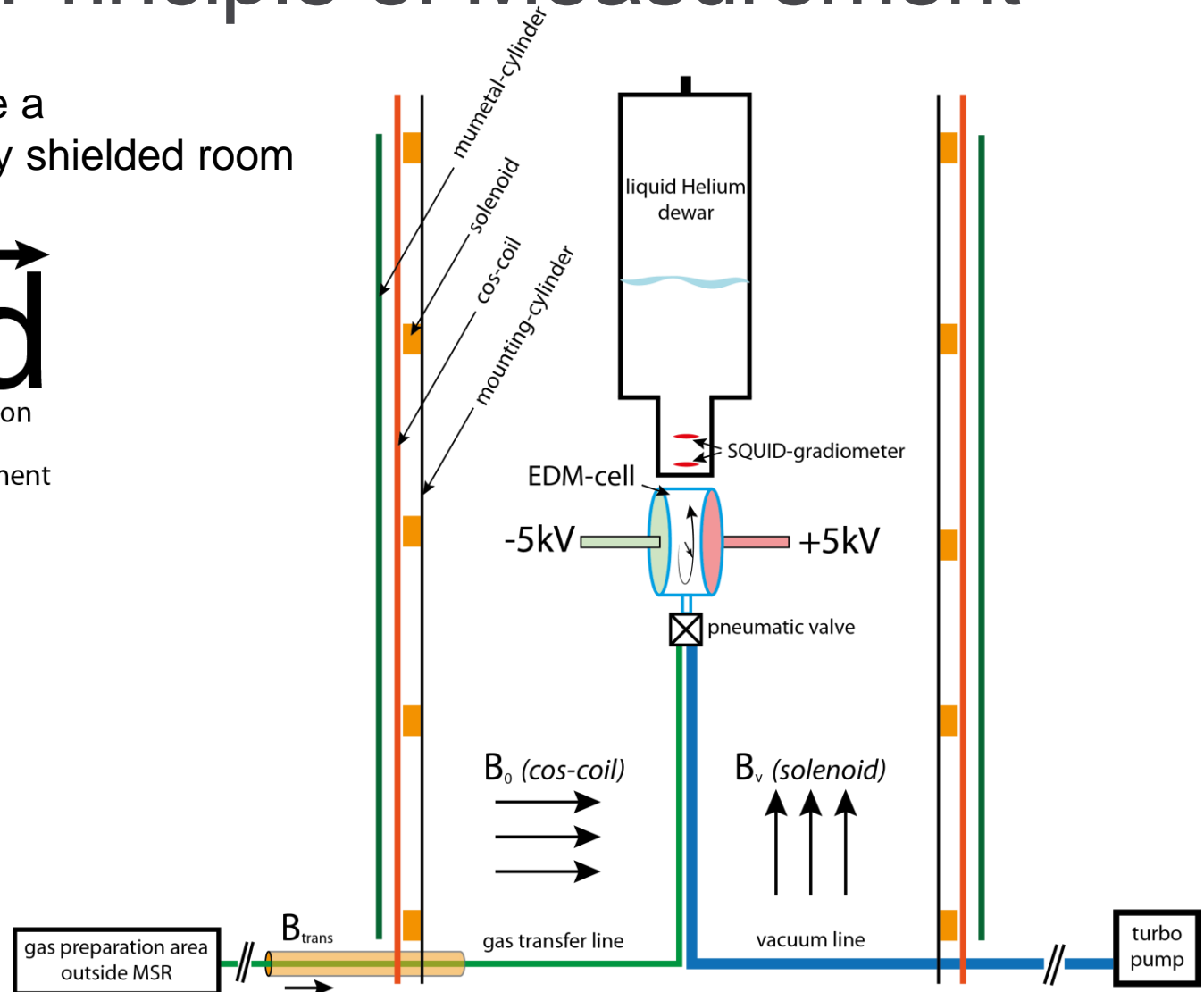
$$d_n^{\text{False}} = \frac{\gamma_n}{\gamma_{\text{Hg}}} d_{\text{Hg}}^{\text{False}}$$

Indirect systematic effect

Setup & Principle of Measurement

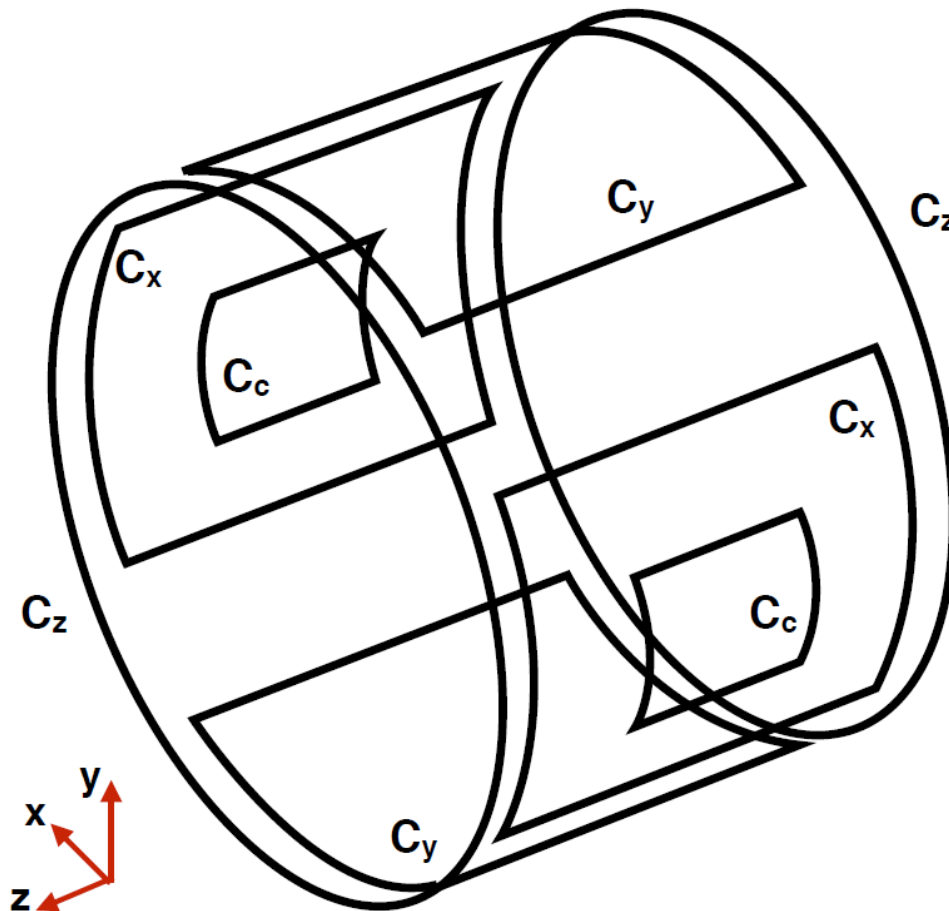
Setup placed inside a
2 layer magnetically shielded room
at FZ Jülich

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Setup & Principle of Measurement

Additional coils for gradient optimization



- Four current sources:
- 16bit resolution
 - Range: -5 ... +5 mA

Procedure for gradient optimization:

Use T_2^* to measure gradients!

- Measure T_2^* for five initial settings of the 4-channel current source
 - Repeatedly measure T_2^* and choose new settings for the current source according to a downhill-simplex algorithm (Nelder-Mead)
- This procedure is fully automated
- No need to change the setup before or after the optimization, in-situ optimization!

$$\frac{1}{T_2^*} = \frac{1}{T_1} + \frac{4R^4\gamma^2}{175D} \left(\left| \vec{\nabla} B_{1,y} \right|^2 + \left| \vec{\nabla} B_{1,z} \right|^2 + 2 \left| \vec{\nabla} B_{1,x} \right|^2 \right)$$

Results of automatic gradient optimization

Example: Spherical cell (diameter 10 cm) filled with 30 mbar of polarized ^3He

T_2^* measurement time: 10 minutes

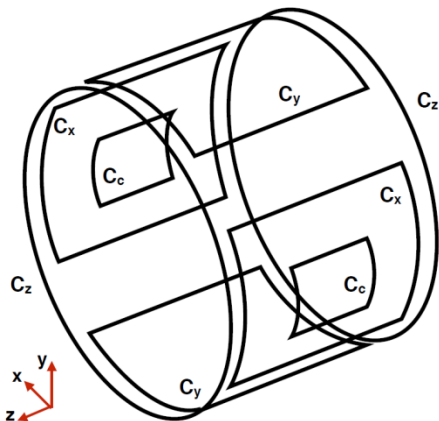
Total measurement time: 4 hours

Iteration	Ch A / mA	Ch B / mA	Ch C / mA	Ch D / mA	T_2^* / s
start	0	0	0	0	7499
0	0	0.15	0	0	9758
1	0.11	0.11	-0.30	0.11	14750
3	0.30	0.30	-0.34	0.01	26590
5	0.33	0.30	-0.60	0.02	35120
13	0.30	0.40	-0.67	0.18	37686

Results

	Ch A / mA	Ch B / mA	Ch C / mA	Ch D / mA	T_2^* / s	effective Gradients (RMS)
start	0	0	0	0	7499	50 pT/cm
end	0.30	0.40	-0.67	0.18	37686	< 10 pT/cm

$$\vec{\nabla} B_{0,x} = \begin{bmatrix} \left(\frac{\partial B_{0,x}}{\partial x} \right)_{res} + \left(\frac{\partial B_{0,x}}{\partial x} \right)_{grad} \\ \left(\frac{\partial B_{0,x}}{\partial y} \right)_{res} + \left(\frac{\partial B_{0,x}}{\partial y} \right)_{grad} \\ \left(\frac{\partial B_{0,x}}{\partial z} \right)_{res} + \left(\frac{\partial B_{0,x}}{\partial z} \right)_{grad} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$



Take currents at optimum to calculate individual gradient components at the starting point:

dominant contributions:

$$\frac{\partial B_{0,x}}{\partial x} = -24 \text{ pT/cm}$$

$$\frac{\partial B_{0,x}}{\partial z} = 35 \text{ pT/cm}$$

General gradient relaxation

$$\frac{1}{T_2^*} = \frac{1}{T_1} + \frac{4R^4\gamma^2}{175 D} \left[a \cdot \left(|\vec{\nabla} B_{0,z}|^2 + |\vec{\nabla} B_{0,y}|^2 \right) + 2|\vec{\nabla} B_{0,x}|^2 \right] \quad (\text{Cates et al.})$$

$$a = \frac{175 D^2}{4R^4 \gamma^2 B^2} \times \sum_{n=1} \frac{1}{(x_{1n}^2 - 2) \cdot (1 + D^2 x_{1n}^4 (\gamma \cdot B)^{-2} R^{-4})} \quad 0 < a \leq 1 .$$

Sensitivity to different gradient components can be selected by adjusting the partial pressures, e.g.:

1 mbar He: $a=0.94$

1 mbar He, 2 mbar Xe, 10 mbar N₂: $a=0.02$

Summary

- Magnetometry using ^3He /SQUID (or ^3He /CsOPM):
 < 5 fT (or 50 fT) accuracy can be easily reached during Ramsey cycle
- Measurement and compensation of magnetic field gradients is necessary in many types of experiments.
- gradients of order pT/cm can be measured with high accuracy
- We developed a method to measure and shim gradients in the pT/cm range by using T_2^* measurements and shim coils.
- In-situ optimization, fully automated, no need to change the setup!
- T_2^* is typically improved by a factor of 5, finally reaching several hours (for ^3He) in our experiment.

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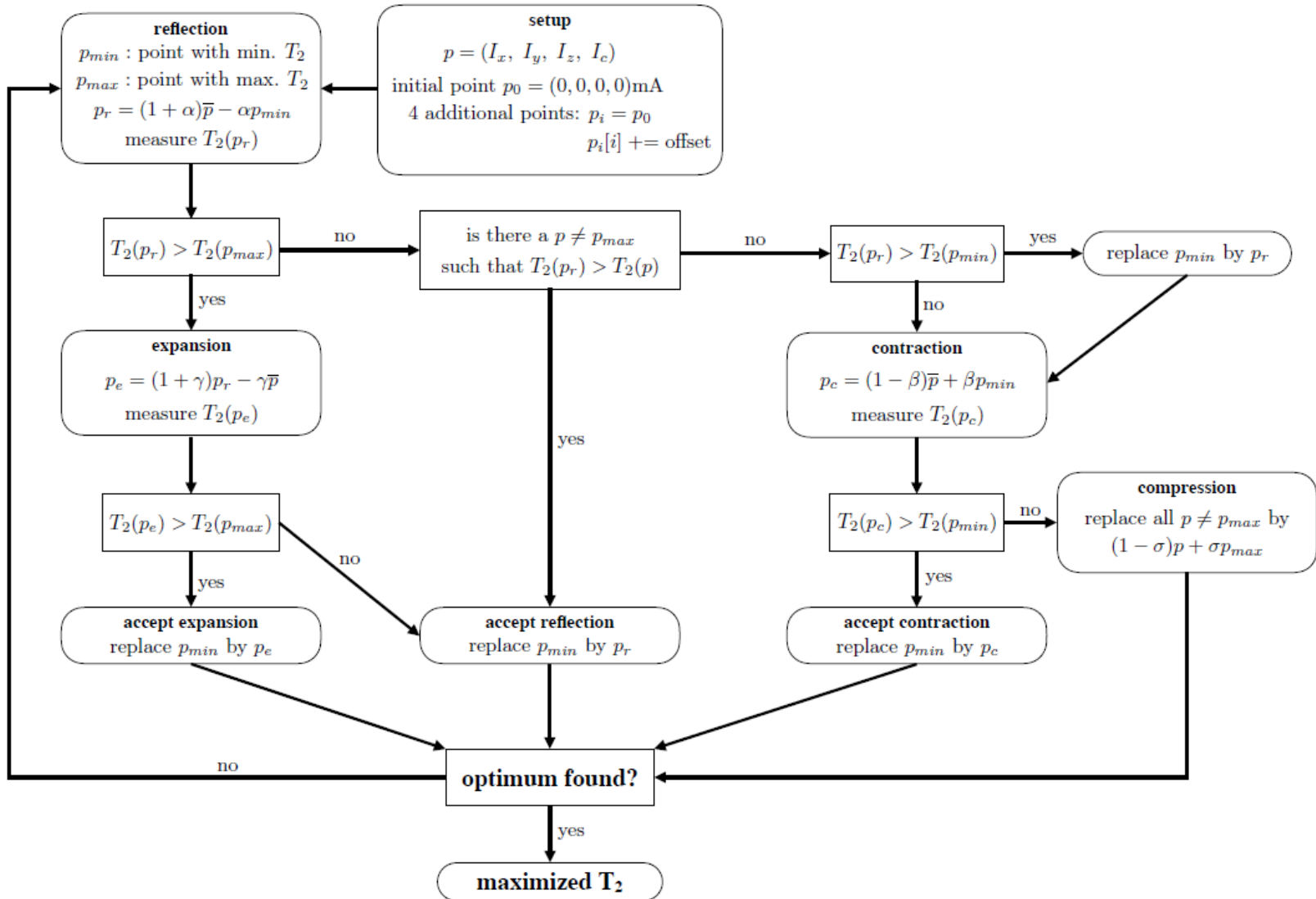
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Downhill-simplex algorithm

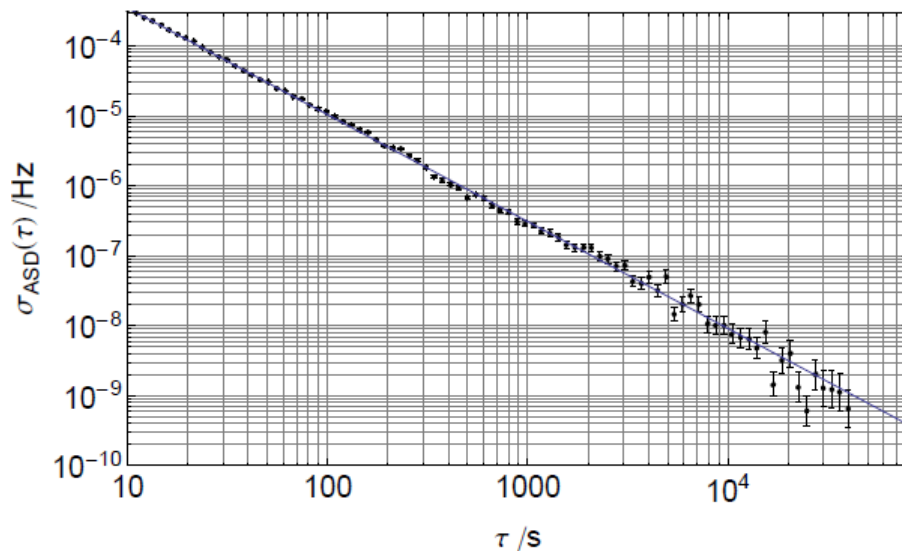


Magnetic Shielding

Requirements:

1. Low noise (about 5 fT/Sqrt(Hz) @ 10 Hz)
2. Low gradients (about 10 pT/cm)

$$\frac{1}{T_2^*} = \frac{1}{T_1} + \frac{4R^4\gamma^2}{175D} \left(|\vec{\nabla} B_{1,y}|^2 + |\vec{\nabla} B_{1,z}|^2 + 2|\vec{\nabla} B_{1,x}|^2 \right)$$



$$\sigma_f^2 \geq \frac{12}{(2\pi)^2 (A/\rho_\alpha)^2 T^3} C.$$

Basic setup

