Conclusions

# Towards an Optimized Hydrodynamic Theory for Heavy-Ion Collisions



In collaboration with D. Bazow, G. Denicol, M. Martinez, J. Noronha, M. Strickland

#### **References:**

Bazow, UH, Strickland, PRC 90 ('14) 054910; Denicol, UH, Martinez, Noronha, Strickland, PRL 113 ('14) 202301; PRD 90 ('14) 125026; Bazow, UH, Martinez, PRC 91 ('15) 064903; UH, Martinez, NPA 943 ('15) 26; Nopoush, Strickland, Ryblewski, Bazow, UH, Martinez, PRC 92 ('15) 044912; Bazow, Denicol, UH, Martinez, Noronha, PRL 116 ('16) 022301; arXiv:1607.05245.

#### Relativistic Hydrodynamics: Theory and Modern Applications, MITP, Oct. 10-14, 2016

Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

MITP, 10/10/2016 1 / 35

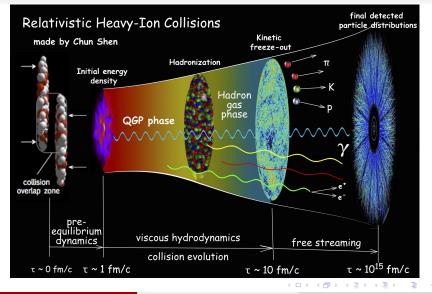
Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000	Conclusions
Overvie	W			

- 2 Kinetic theory vs. hydrodynamics
- 3 Exact solutions of the Boltzmann equation
  - Systems undergoing Bjorken flow
  - Systems undergoing Gubser flow
  - Hydrodynamics of Gubser flow
- 4 Results: Comparison of hydrodynamic approximations with exact BE
  - Bjorken flow
  - Gubser flow
- 5 Conclusions

Results

Conclusions

## The Little Bang (credit: Paul Sorensen/Chun Shen)



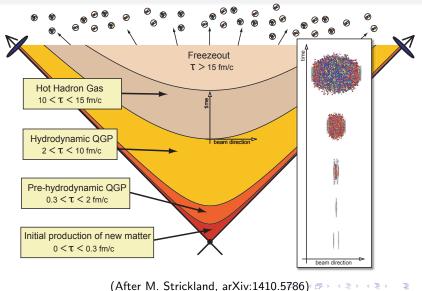
Ulrich Heinz (Ohio State)

MITP, 10/10/2016 3 / 35



Conclusions

## Prologue



Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000	Conclusions
Prologu	ie			

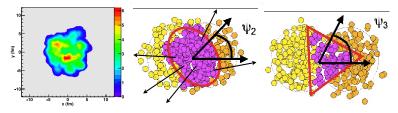
 Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions

Image: A matrix and a matrix

 
 Prologue
 Kinetic theory vs. hydrodynamics
 Exact BE solutions 000
 Results 00000000000
 Conclu-00000000000

 Event-by-event shape
 and flow fluctuations rule!

(Alver and Roland, PRC81 (2010) 054905)



- $\bullet$  Each event has a different initial shape and density distribution, characterized by different set of harmonic eccentricity coefficients  $\varepsilon_n$
- $\bullet$  Each event develops its individual hydrodynamic flow, characterized by a set of harmonic flow coefficients  $v_n$  and flow angles  $\psi_n$
- At small impact parameters fluctuations ("hot spots") dominate over geometric overlap effects (Alver & Roland, PRC81 (2010) 054905; Qin, Petersen, Bass, Müller, PRC82 (2010) 064903)

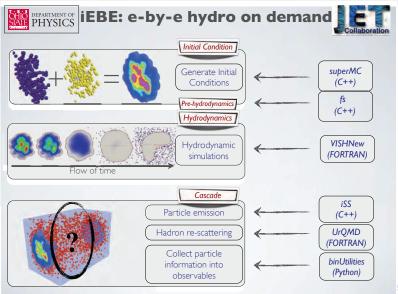
Definition of flow coefficients:

$$\frac{dN^{(i)}}{dy \, p_T dp_T \, d\phi_p}(b) = \frac{dN^{(i)}}{dy \, p_T dp_T}(b) \left( 1 + 2\sum_{n=1}^{\infty} \boldsymbol{v_n^{(i)}}(\boldsymbol{y, p_T; b}) \cos\left(n(\phi_p - \Psi_n^{(i)})\right) \right)$$

Ulrich Heinz (Ohio State)

Results 0000000000 Conclusions

#### https://u.osu.edu/vishnu: A product of the JET Collaboration



Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

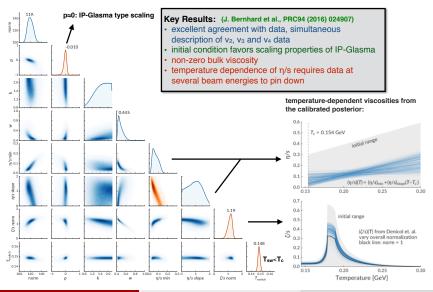
MITP, 10/10/2016

7 / 35

Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 0000000000
Prolog	ue		

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It has been successfully used in a Bayesian analysis of LHC Pb+Pb collision data for putting meaningful constraints on the initial conditions and medium properties of QGP created in heavy-ion collisions:

### **Calibrated Posterior Distribution**



Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

MITP, 10/10/2016 9

9 / 35

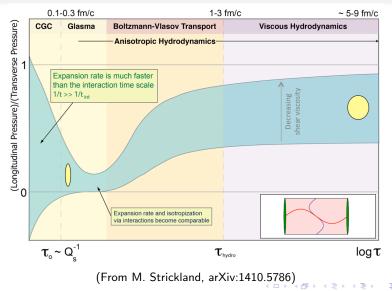
Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000	(
Prologu	e			

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- However, the kinematics of ultra-relativistic heavy-ion collisions introduces a complication that severely limits the applicability of standard viscous relativistic fluid dynamics:

large viscous stresses caused by large initial anisotropies between the longitudinal and transverse expansion rates

イロト 不得下 イヨト イヨト

## Strong initial longitudinal-transverse pressure anisotropies



Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

MITP, 10/10/2016 11 / 35

Pro	logue

## Motivation

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It is an effective macroscopic description based on coarse-graining (gradient expansion) of the microscopic dynamics

4 3 > 4 3 >

Prologue	Pro	logue
----------	-----	-------

## Motivation

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It is an effective macroscopic description based on coarse-graining (gradient expansion) of the microscopic dynamics
- Its systematic construction is still a matter of debate, complicated by the existence of a complex hierarchy of micro- and macroscopic time scales that are not well separated in relativistic heavy-ion collisions

A B A A B A

## Motivation

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It is an effective macroscopic description based on coarse-graining (gradient expansion) of the microscopic dynamics
- Its systematic construction is still a matter of debate, complicated by the existence of a complex hierarchy of micro- and macroscopic time scales that are not well separated in relativistic heavy-ion collisions
- Exact solutions of the highly nonlinear microscopic dynamics can serve as a testbed for macroscopic hydrodynamic approximation schemes, but are hard to come by.

A B F A B F

## Motivation

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It is an effective macroscopic description based on coarse-graining (gradient expansion) of the microscopic dynamics
- Its systematic construction is still a matter of debate, complicated by the existence of a complex hierarchy of micro- and macroscopic time scales that are not well separated in relativistic heavy-ion collisions
- Exact solutions of the highly nonlinear microscopic dynamics can serve as a testbed for macroscopic hydrodynamic approximation schemes, but are hard to come by.
- Exact solutions have been found for weakly interacting systems with highly symmetric flow patterns and density distributions:
   Bjorken and Gubser flow (RTA),
   FLRW universe (full Boltzmann collision term)

イロト 不得下 イヨト イヨト

## Motivation

- Relativistic viscous hydrodynamics has become the workhorse of dynamical modeling of ultra-relativistic heavy-ion collisions
- It is an effective macroscopic description based on coarse-graining (gradient expansion) of the microscopic dynamics
- Its systematic construction is still a matter of debate, complicated by the existence of a complex hierarchy of micro- and macroscopic time scales that are not well separated in relativistic heavy-ion collisions
- Exact solutions of the highly nonlinear microscopic dynamics can serve as a testbed for macroscopic hydrodynamic approximation schemes, but are hard to come by.
- Exact solutions have been found for weakly interacting systems with highly symmetric flow patterns and density distributions:
   Bjorken and Gubser flow (RTA),
   FLRW universe (full Boltzmann collision term)

■ Can be used to test different hydrodynamic expansion schemes for the Boltzmann equation Ulrich Heinz (Ohio State) Hydrodynamics for HICs MITP, 10/10/2016 12 / 35

Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000	Conclusions

#### Overview

#### 1 Prologue

#### 2 Kinetic theory vs. hydrodynamics

- **3** Exact solutions of the Boltzmann equation
  - Systems undergoing Bjorken flow
  - Systems undergoing Gubser flow
  - Hydrodynamics of Gubser flow
- 4 Results: Comparison of hydrodynamic approximations with exact BE
  - Bjorken flow
  - Gubser flow
- 5 Conclusions

- 4 @ > - 4 @ > - 4 @ >

Conclusions

## Kinetic theory vs. hydrodynamics

Both simultaneously valid if weakly coupled and small pressure gradients.

(日) (周) (三) (三)

## Kinetic theory vs. hydrodynamics

Both simultaneously valid if weakly coupled and small pressure gradients. Form of hydro equations remains unchanged for strongly coupled systems.

イロト 不得下 イヨト イヨト

Prologue Kinetic theory vs. hydrodynamics Exact BE solutions Results Conclusions

### Kinetic theory vs. hydrodynamics

Both simultaneously valid if weakly coupled and small pressure gradients. Form of hydro equations remains unchanged for strongly coupled systems.

Boltzmann Equation in Relaxation Time Approximation (RTA):

$$p^{\mu}\partial_{\mu}f(x,p) = C(x,p) = rac{p \cdot u(x)}{ au_{\mathrm{rel}}(x)} \Big(f_{\mathrm{eq}}(x,p) - f(x,p)\Big)$$

For conformal systems  $\tau_{\rm rel}(x) = c/T(x) = 5\eta/(ST) \equiv 5\bar{\eta}/T(x)$ .

Prologue Kinetic theory vs. hydrodynamics Exact BE solutions Results Conclusions

### Kinetic theory vs. hydrodynamics

Both simultaneously valid if weakly coupled and small pressure gradients. Form of hydro equations remains unchanged for strongly coupled systems.

Boltzmann Equation in Relaxation Time Approximation (RTA):

$$p^{\mu}\partial_{\mu}f(x,p) = C(x,p) = rac{p \cdot u(x)}{ au_{\mathrm{rel}}(x)} \Big( f_{\mathrm{eq}}(x,p) - f(x,p) \Big)$$

For conformal systems  $\tau_{\rm rel}(x) = c/T(x) = 5\eta/(\mathcal{S}T) \equiv 5\bar{\eta}/T(x)$ .

Macroscopic currents:

$$j^{\mu}(x) = \int_{p} p^{\mu} f(x,p) \equiv \langle p^{\mu} \rangle; \quad T^{\mu\nu}(x) = \int_{p} p^{\mu} p^{\nu} f(x,p) \equiv \langle p^{\mu} p^{\nu} \rangle$$

where 
$$\int_{p} \cdots \equiv \frac{g}{(2\pi)^3} \int \frac{d^3p}{E_p} \cdots \equiv \langle \dots \rangle$$

Results

Conclusions

## Hydrodynamics from kinetic theory (I):

Expand the solution f(x, p) of the Boltzmann equation as

$$f(x, p) = f_0(x, p) + \delta f(x, p) \qquad \left( \left| \delta f / f_0 \right| \ll 1 \right)$$

where  $f_0$  is parametrized through macroscopic observables as

$$f_0(x,p) = f_0\left(\frac{\sqrt{p_{\mu}\Xi^{\mu\nu}(x)p_{\nu}} - \tilde{\mu}(x)}{\tilde{T}(x)}\right)$$

where  $\Xi^{\mu\nu}(x) = u^{\mu}(x)u^{\nu}(x) - \Phi(x)\Delta^{\mu\nu}(x) + \xi^{\mu\nu}(x).$ 

 $u^{\mu}(x)$  defines the local fluid rest frame (LRF).  $\Delta^{\mu\nu} = g^{\mu\nu} - u^{\mu}u^{\nu}$  is the spatial projector in the LRF.  $\tilde{T}(x), \tilde{\mu}(x)$  are the effective temperature and chem. potential in the LRF.  $\Phi(x)$  partially accounts for bulk viscous effects in expanding systems.  $\xi^{\mu\nu}(x)$  describes deviations from local momentum isotropy in anisotropically expanding systems due to shear viscosity.

Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

## Hydrodynamics from kinetic theory (II):

 $u^{\mu}(x), \tilde{T}(x), \tilde{\mu}(x)$  are fixed by the Landau matching conditions:

$$T^{\mu}_{\nu}u^{\nu} = \mathcal{E}(\tilde{T}, \tilde{\mu}; \xi, \Phi)u^{\mu}; \qquad \left\langle u \cdot p \right\rangle_{\delta f} = \left\langle (u \cdot p)^2 \right\rangle_{\delta f} = 0$$

 $\mathcal{E}$  is the LRF energy density. We introduce the true local temperature  $T(\tilde{T}, \tilde{\mu}; \xi, \Phi)$  and chemical potential  $\mu(\tilde{T}, \tilde{\mu}; \xi, \Phi)$  by demanding  $\mathcal{E}(\tilde{T}, \tilde{\mu}; \xi, \Phi) = \mathcal{E}_{eq}(T, \mu)$  and  $\mathcal{N}(\tilde{T}, \tilde{\mu}; \xi, \Phi) \equiv \langle u \cdot p \rangle_{f_0} = \mathcal{R}_0(\xi, \Phi) \mathcal{N}_{eq}(T, \mu)$  (see cited literature for  $\mathcal{R}$  functions). Writing

$$T^{\mu\nu} = T_0^{\mu\nu} + \delta T^{\mu\nu} \equiv T_0^{\mu\nu} + \Pi^{\mu\nu}, \qquad j^{\mu} = j_0^{\mu} + \delta j^{\mu} \equiv j_0^{\mu} + V^{\mu},$$

the conservation laws

$$\partial_{\mu}T^{\mu\nu}(x) = 0, \qquad \partial_{\mu}j^{\mu}(x) = rac{\mathcal{N}(x) - \mathcal{N}_{\mathrm{eq}}(x)}{\tau_{\mathrm{rel}}(x)}$$

are sufficient to determine  $u^{\mu}(x)$ , T(x),  $\mu(x)$ , but not the dissipative corrections  $\xi^{\mu\nu}$ ,  $\Phi$ ,  $\Pi^{\mu\nu}$ , and  $V^{\mu}$  whose evolution is controlled by microscopic physics.

Ulrich Heinz (Ohio State)

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

• Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

- Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .
- Navier-Stokes (NS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , ignores microscopic relaxation time by postulating instantaneous constituent relations for  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

- Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .
- Navier-Stokes (NS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , ignores microscopic relaxation time by postulating instantaneous constituent relations for  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Israel-Stewart (IS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , evolves  $\Pi^{\mu\nu}$ ,  $V^{\mu}$  dynamically, keeping only terms linear in  $\text{Kn} = \lambda_{\text{mfp}}/\lambda_{\text{macro}}$

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

- Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .
- Navier-Stokes (NS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , ignores microscopic relaxation time by postulating instantaneous constituent relations for  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Israel-Stewart (IS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , evolves  $\Pi^{\mu\nu}$ ,  $V^{\mu}$  dynamically, keeping only terms linear in  $\text{Kn} = \lambda_{\text{mfp}}/\lambda_{\text{macro}}$
- Denicol-Niemi-Molnar-Rischke (DNMR) theory: improved IS theory that keeps nonlinear terms up to order  $\mathrm{Kn}^2$ ,  $\mathrm{Kn} \cdot \mathrm{Re}^{-1}$  when evolving  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .

Conclusions

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

- Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .
- Navier-Stokes (NS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , ignores microscopic relaxation time by postulating instantaneous constituent relations for  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Israel-Stewart (IS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , evolves  $\Pi^{\mu\nu}$ ,  $V^{\mu}$  dynamically, keeping only terms linear in  $\text{Kn} = \lambda_{\text{mfp}}/\lambda_{\text{macro}}$
- Denicol-Niemi-Molnar-Rischke (DNMR) theory: improved IS theory that keeps nonlinear terms up to order  $\text{Kn}^2$ ,  $\text{Kn} \cdot \text{Re}^{-1}$  when evolving  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Anisotropic hydrodynamics (aHydro): allows for leading-order local momentum anisotropy (ξ<sup>μν</sup>, Φ ≠ 0), evolved according to equations obtained from low-order moments of BE, but ignores residual dissipative flows: Π<sup>μν</sup> = V<sup>μ</sup> = 0.

## Hydrodynamics from kinetic theory (III):

Different hydrodynamic approaches can be characterized by the different assumptions they make about the dissipative corrections and/or the different approximations they use to derive their dynamics from the underlying Boltzmann equation:

- Ideal hydro: local momentum isotropy  $(\xi^{\mu\nu} = 0)$ ,  $\Phi = \Pi^{\mu\nu} = V^{\mu} = 0$ .
- Navier-Stokes (NS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , ignores microscopic relaxation time by postulating instantaneous constituent relations for  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Israel-Stewart (IS) theory: local momentum isotropy ( $\xi^{\mu\nu} = 0$ ),  $\Phi = 0$ , evolves  $\Pi^{\mu\nu}$ ,  $V^{\mu}$  dynamically, keeping only terms linear in  $\text{Kn} = \lambda_{\text{mfp}}/\lambda_{\text{macro}}$
- Denicol-Niemi-Molnar-Rischke (DNMR) theory: improved IS theory that keeps nonlinear terms up to order  $\text{Kn}^2$ ,  $\text{Kn} \cdot \text{Re}^{-1}$  when evolving  $\Pi^{\mu\nu}$ ,  $V^{\mu}$ .
- Anisotropic hydrodynamics (aHydro): allows for leading-order local momentum anisotropy (ξ<sup>μν</sup>, Φ ≠ 0), evolved according to equations obtained from low-order moments of BE, but ignores residual dissipative flows: Π<sup>μν</sup> = V<sup>μ</sup> = 0.
- Viscous anisotropic hydrodynamics (vaHydro): improved aHydro that additionally evolves residual dissipative flows  $\Pi^{\mu\nu}$ ,  $V^{\mu}$  with IS or DNMR theory.

### Overview

#### 1 Prologue

2 Kinetic theory vs. hydrodynamics

#### 3 Exact solutions of the Boltzmann equation

- Systems undergoing Bjorken flow
- Systems undergoing Gubser flow
- Hydrodynamics of Gubser flow

4 Results: Comparison of hydrodynamic approximations with exact BE

- Bjorken flow
- Gubser flow

#### 5 Conclusions

(人間) トイヨト イヨト

Prologue Kinetic theory vs. hydrodynamics Exact BE solutions Results Conclusions

Bjorken flow

BE for systems with highly symmetric flows: I. Bjorken flow

• Longitudinal boost invariance, transverse homogeneity ("physics on the light cone", no transverse flow)  $\Longrightarrow u^{\mu} = (1, 0, 0, 0)$  in Milne coordinates  $(\tau, r, \phi, \eta)$  where  $\tau = (t^2 - z^2)^{1/2}$  and  $\eta = \frac{1}{2} \ln[(t-z)/(t+z)] \Longrightarrow v_z = z/t$ 

イロト イポト イヨト イヨト 二日

Bjorken flow

BE for systems with highly symmetric flows: I. Bjorken flow

- Longitudinal boost invariance, transverse homogeneity ("physics on the light cone", no transverse flow)  $\Rightarrow u^{\mu} = (1, 0, 0, 0)$  in Milne coordinates  $(\tau, r, \phi, \eta)$  where  $\tau = (t^2 z^2)^{1/2}$  and  $\eta = \frac{1}{2} \ln[(t-z)/(t+z)] \Rightarrow v_z = z/t$
- Metric:  $ds^2 = d\tau^2 dr^2 r^2 d\phi^2 \tau^2 d\eta^2$ ,  $g_{\mu\nu} = \text{diag}(1, -1, -r^2, -\tau^2)$

Bjorken flow

### BE for systems with highly symmetric flows: I. Bjorken flow

- Longitudinal boost invariance, transverse homogeneity ("physics on the light cone", no transverse flow)  $\Rightarrow u^{\mu} = (1, 0, 0, 0)$  in Milne coordinates  $(\tau, r, \phi, \eta)$  where  $\tau = (t^2 z^2)^{1/2}$  and  $\eta = \frac{1}{2} \ln[(t-z)/(t+z)] \Rightarrow v_z = z/t$
- Metric:  $ds^2 = d\tau^2 dr^2 r^2 d\phi^2 \tau^2 d\eta^2$ ,  $g_{\mu\nu} = \text{diag}(1, -1, -r^2, -\tau^2)$
- Symmetry restricts possible dependence of distribution function f(x, p) (Baym '84, Florkowski et al. '13, '14):

 $f(x, p) = f(\tau; p_{\perp}, w)$  where  $w = tp_z - zE = \tau m_{\perp} \sinh(y-\eta)$ .

Bjorken flow

## BE for systems with highly symmetric flows: I. Bjorken flow

- Longitudinal boost invariance, transverse homogeneity ("physics on the light cone", no transverse flow)  $\Rightarrow u^{\mu} = (1, 0, 0, 0)$  in Milne coordinates  $(\tau, r, \phi, \eta)$  where  $\tau = (t^2 z^2)^{1/2}$  and  $\eta = \frac{1}{2} \ln[(t-z)/(t+z)] \Rightarrow v_z = z/t$
- Metric:  $ds^2 = d\tau^2 dr^2 r^2 d\phi^2 \tau^2 d\eta^2$ ,  $g_{\mu\nu} = \text{diag}(1, -1, -r^2, -\tau^2)$
- Symmetry restricts possible dependence of distribution function f(x, p) (Baym '84, Florkowski et al. '13, '14):

 $f(x, p) = f(\tau; p_{\perp}, w)$  where  $w = tp_z - zE = \tau m_{\perp} \sinh(y-\eta)$ .

RTA BE simplifies to ordinary differential equation

$$\partial_{\tau} f(\tau; \mathbf{p}_{\perp}, \mathbf{w}) = -rac{f(\tau; \mathbf{p}_{\perp}, \mathbf{w}) - f_{\mathrm{eq}}(\tau; \mathbf{p}_{\perp}, \mathbf{w})}{ au_{\mathrm{rel}}( au)}.$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ = ののの

Bjorken flow

### BE for systems with highly symmetric flows: I. Bjorken flow

- Longitudinal boost invariance, transverse homogeneity ("physics on the light cone", no transverse flow)  $\Rightarrow u^{\mu} = (1, 0, 0, 0)$  in Milne coordinates  $(\tau, r, \phi, \eta)$  where  $\tau = (t^2 z^2)^{1/2}$  and  $\eta = \frac{1}{2} \ln[(t-z)/(t+z)] \Rightarrow v_z = z/t$
- Metric:  $ds^2 = d\tau^2 dr^2 r^2 d\phi^2 \tau^2 d\eta^2$ ,  $g_{\mu\nu} = \text{diag}(1, -1, -r^2, -\tau^2)$
- Symmetry restricts possible dependence of distribution function f(x, p) (Baym '84, Florkowski et al. '13, '14):

 $f(x, p) = f(\tau; p_{\perp}, w)$  where  $w = tp_z - zE = \tau m_{\perp} \sinh(y-\eta)$ .

RTA BE simplifies to ordinary differential equation

$$\partial_{\tau}f(\tau; \mathbf{p}_{\perp}, \mathbf{w}) = -rac{f(\tau; \mathbf{p}_{\perp}, \mathbf{w}) - f_{\mathrm{eq}}(\tau; \mathbf{p}_{\perp}, \mathbf{w})}{ au_{\mathrm{rel}}( au)}.$$

Solution:

$$egin{aligned} f( au; oldsymbol{p}_{ot}, w) &= D( au, au_0) f_0(oldsymbol{p}_{ot}, w) + \int_{ au_0}^{ au} rac{d au'}{ au_{ ext{rel}}( au')} \, D( au, au') \, f_{ ext{eq}}( au'; oldsymbol{p}_{ot}, w) \ D( au_2, au_1) &= \expigg( - \int_{ au_0}^{ au_2} rac{d au''}{ au_{ ext{rel}}( au'')} igg). \end{aligned}$$

where

イロト 不得下 イヨト イヨト 二日

#### Gubser flow

## BE for systems with highly symmetric flows: II. Gubser flow

• Longitudinal boost invariance, azimuthally symmetric radial dependence ("physics on the light cone" with azimuthally symmetric transverse flow) (Gubser '10, Gubser & Yarom '11)  $\Rightarrow u^{\mu} = (1,0,0,0)$  in de Sitter coordinates  $(\rho, \theta, \phi, \eta)$  where  $\rho(\tau, r) = -\sinh^{-1}\left(\frac{1-q^2\tau^2+q^2r^2}{2q\tau}\right)$  and  $\theta(\tau, r) = \tan^{-1}\left(\frac{2qr}{1+q^2\tau^2-q^2r^2}\right)$ .  $\Rightarrow v_z = z/t$  and  $v_r = \frac{2q^2\tau r}{1+q^2\tau^2+q^2r^2}$  where q is an arbitrary scale parameter.

イロト イポト イヨト イヨト 二日

### Gubser flow

## BE for systems with highly symmetric flows: II. Gubser flow

Longitudinal boost invariance, azimuthally symmetric radial dependence ("physics on the light cone" with azimuthally symmetric transverse flow) (Gubser '10, Gubser & Yarom '11)
 ⇒ u<sup>μ</sup> = (1,0,0,0) in de Sitter coordinates (ρ, θ, φ, η) where ρ(τ, r) = -sinh<sup>-1</sup> (1-q<sup>2</sup>τ<sup>2</sup>+q<sup>2</sup>r<sup>2</sup>/2ητ) and θ(τ, r) = tan<sup>-1</sup> (2qr/(1+q<sup>2</sup>τ<sup>2</sup>-q<sup>2</sup>r<sup>2</sup>)).
 ⇒ v<sub>z</sub> = z/t and v<sub>r</sub> = 2q<sup>2</sup>τr/(1+q<sup>2</sup>τ<sup>2</sup>+q<sup>2</sup>r<sup>2</sup>) where q is an arbitrary scale parameter.
 Metric: ds<sup>2</sup> = ds<sup>2</sup>/τ<sup>2</sup> = dρ<sup>2</sup> - cosh<sup>2</sup>ρ (dθ<sup>2</sup> + sin<sup>2</sup> θ dφ<sup>2</sup>) - dη<sup>2</sup>, g<sub>μν</sub> = diag(1, - cosh<sup>2</sup> ρ, - cosh<sup>2</sup> ρ sin<sup>2</sup> θ, -1)

イロト イポト イヨト イヨト 二日

#### Gubser flow

## BE for systems with highly symmetric flows: II. Gubser flow

- Longitudinal boost invariance, azimuthally symmetric radial dependence ("physics on the light cone" with azimuthally symmetric transverse flow) (Gubser '10, Gubser & Yarom '11)
   ⇒ u<sup>μ</sup> = (1,0,0,0) in de Sitter coordinates (ρ, θ, φ, η) where ρ(τ, r) = -sinh<sup>-1</sup> ((1-q<sup>2</sup>τ<sup>2</sup>+q<sup>2</sup>r<sup>2</sup>)/(2qτ) and θ(τ, r) = tan<sup>-1</sup> ((2qr)/(1+q<sup>2</sup>τ<sup>2</sup>-q<sup>2</sup>r<sup>2</sup>)).
   ⇒ v<sub>z</sub> = z/t and v<sub>r</sub> = (2q<sup>2</sup>τr)/(1+q<sup>2</sup>τ<sup>2</sup>+q<sup>2</sup>r<sup>2</sup>)/(1+q<sup>2</sup>τ<sup>2</sup>+q<sup>2</sup>r<sup>2</sup>) where q is an arbitrary scale parameter.
   Metric: ds<sup>2</sup> = ds<sup>2</sup>/τ<sup>2</sup> = dρ<sup>2</sup> cosh<sup>2</sup>ρ (dθ<sup>2</sup> + sin<sup>2</sup> θ dφ<sup>2</sup>) dη<sup>2</sup>, g<sub>μν</sub> = diag(1, cosh<sup>2</sup> ρ, cosh<sup>2</sup> ρ sin<sup>2</sup> θ, -1)
- Symmetry restricts possible dependence of distribution function f(x, p)

$$f(x,p) = f(\rho; \hat{p}_{\Omega}^2, \hat{p}_{\eta})$$
 where  $\hat{p}_{\Omega}^2 = \hat{p}_{\theta}^2 + \frac{\hat{p}_{\phi}^2}{\sin^2 \theta}$  and  $\hat{p}_{\eta} = w$ .

20 / 35

イロト イポト イヨト イヨト 二日

#### Gubser flow

## BE for systems with highly symmetric flows: II. Gubser flow

- Longitudinal boost invariance, azimuthally symmetric radial dependence ("physics on the light cone" with azimuthally symmetric transverse flow) (Gubser '10, Gubser & Yarom '11)  $\Rightarrow u^{\mu} = (1, 0, 0, 0)$  in de Sitter coordinates  $(\rho, \theta, \phi, \eta)$  where  $\rho(\tau,r) = -\sinh^{-1}\left(\tfrac{1-q^2\tau^2+q^2r^2}{2q\tau}\right) \text{ and } \theta(\tau,r) = \tan^{-1}\left(\tfrac{2qr}{1+q^2\tau^2-a^2r^2}\right).$  $\implies$   $v_z = z/t$  and  $v_r = \frac{2q^2\tau r}{1+a^2\tau^2+a^2r^2}$  where q is an arbitrary scale parameter. • Metric:  $d\hat{s}^2 = ds^2/\tau^2 = d\rho^2 - \cosh^2\rho (d\theta^2 + \sin^2\theta d\phi^2) - d\eta^2$ ,  $g_{\mu\nu} = \operatorname{diag}(1, -\cosh^2 \rho, -\cosh^2 \rho \sin^2 \theta, -1)$
- Symmetry restricts possible dependence of distribution function f(x, p)

 $f(x, p) = f(\rho; \hat{\rho}_{\Omega}^2, \hat{\rho}_{\eta})$  where  $\hat{\rho}_{\Omega}^2 = \hat{\rho}_{\theta}^2 + \frac{\hat{p}_{\phi}^2}{\sin^2 \theta}$  and  $\hat{\rho}_{\eta} = w$ .

• With  $T(\tau, r) = \hat{T}(\rho(\tau, r))/\tau$  RTA BE simplifies to the ODE

$$\frac{\partial}{\partial \rho} f(\rho; \hat{p}_{\Omega}^{2}, \hat{\rho}_{\varsigma}) = -\frac{\hat{T}(\rho)}{c} \left[ f\left(\rho; \hat{p}_{\Omega}^{2}, \hat{\rho}_{\varsigma}\right) - f_{\mathrm{eq}}\left(\hat{p}^{\rho}/\hat{T}(\rho)\right) \right].$$

#### Gubser flow

## BE for systems with highly symmetric flows: II. Gubser flow

- Longitudinal boost invariance, azimuthally symmetric radial dependence ("physics on the light cone" with azimuthally symmetric transverse flow) (Gubser '10, Gubser & Yarom '11)  $\implies u^{\mu} = (1,0,0,0) \text{ in de Sitter coordinates } (\rho, \theta, \phi, \eta) \text{ where } \rho(\tau, r) = -\sinh^{-1}\left(\frac{1-q^2\tau^2+q^2r^2}{2q\tau}\right) \text{ and } \theta(\tau, r) = \tan^{-1}\left(\frac{2qr}{1+q^2\tau^2-q^2r^2}\right).$   $\implies v_z = z/t \text{ and } v_r = \frac{2q^2rr}{1+q^2\tau^2+q^2r^2} \text{ where } q \text{ is an arbitrary scale parameter.}$   $= \text{Metric: } d\hat{s}^2 = ds^2/\tau^2 = d\rho^2 \cosh^2\rho (d\theta^2 + \sin^2\theta d\phi^2) d\eta^2,$   $g_{\mu\nu} = \text{diag}(1, -\cosh^2\rho, -\cosh^2\rho \sin^2\theta, -1)$
- Symmetry restricts possible dependence of distribution function f(x, p)

$$f(x,p) = f(\rho; \hat{p}_{\Omega}^2, \hat{p}_{\eta})$$
 where  $\hat{p}_{\Omega}^2 = \hat{p}_{\theta}^2 + \frac{\hat{p}_{\phi}^2}{\sin^2 \theta}$  and  $\hat{p}_{\eta} = w$ .

• With  $T(\tau, r) = \hat{T}(\rho(\tau, r))/\tau$  RTA BE simplifies to the ODE

$$rac{\partial}{\partial 
ho} f(
ho; \hat{
ho}_{\Omega}^2, \hat{
ho}_{\varsigma}) = -rac{\hat{T}(
ho)}{c} \left[ f\left(
ho; \hat{
ho}_{\Omega}^2, \hat{
ho}_{\varsigma}
ight) - f_{
m eq} \left( \hat{
ho}^{
ho} / \hat{T}(
ho) 
ight) 
ight].$$

### Solution:

 $f(\rho; \hat{\rho}_{\Omega}^{2}, w) = D(\rho, \rho_{0})f_{0}(\hat{\rho}_{\Omega}^{2}, w) + \frac{1}{c}\int_{\rho_{0}}^{\rho} d\rho' \hat{T}(\rho') D(\rho, \rho') f_{eq}(\rho'; \hat{\rho}_{\Omega}^{2}, w)$ 

Gubser hydro

## Hydrodynamic equations for systems with Gubser flow\*:

The exact solution for f can be worked out for any "initial" condition  $f_0(\hat{\rho}_{\Omega}^2, w) \equiv f(\rho_0; \hat{\rho}_{\Omega}^2, w)$ . We here use equilibrium initial conditions,  $f_0 = f_{eq}$ .

\*For Bjorken flow, including (0+1)-d vaHydro, see UH@QM14

Gubser hydro

## Hydrodynamic equations for systems with Gubser flow\*:

- The exact solution for f can be worked out for any "initial" condition  $f_0(\hat{\rho}_{\Omega}^2, w) \equiv f(\rho_0; \hat{\rho}_{\Omega}^2, w)$ . We here use equilibrium initial conditions,  $f_0 = f_{eq}$ .
- By taking hydrodynamic moments, the exact f yields the exact evolution of all components of  $T^{\mu\nu}$ . Here,  $\Pi^{\mu\nu}$  has only one independent component,  $\pi^{\eta\eta}$ .

\*For Bjorken flow, including (0+1)-d vaHydro, see UH@QM14

Gubser hydro

## Hydrodynamic equations for systems with Gubser flow\*:

- The exact solution for f can be worked out for any "initial" condition  $f_0(\hat{\rho}_{\Omega}^2, w) \equiv f(\rho_0; \hat{\rho}_{\Omega}^2, w)$ . We here use equilibrium initial conditions,  $f_0 = f_{eq}$ .
- By taking hydrodynamic moments, the exact f yields the exact evolution of all components of  $T^{\mu\nu}$ . Here,  $\Pi^{\mu\nu}$  has only one independent component,  $\pi^{\eta\eta}$ .
- This exact solution of the BE can be compared to solutions of the various hydrodynamic equations in de Sitter coordinates, using identical initial conditions.
  - Ideal:  $\hat{T}_{\text{ideal}}(\rho) = \frac{\hat{T}_0}{\cosh^{2/3}(\rho)}$
  - **NS:**  $\frac{1}{\hat{T}} \frac{d\hat{T}}{d\rho} + \frac{2}{3} \tanh \rho = \frac{1}{3} \bar{\pi}_{\eta}^{\eta}(\rho) \tanh \rho$  (viscous *T*-evolution) with  $\bar{\pi}_{\eta}^{\eta} \equiv \hat{\pi}_{\eta}^{\eta}/(\hat{T}\hat{S})$  and  $\hat{\pi}_{NS}^{\eta\eta} = \frac{4}{3}\hat{\eta} \tanh \rho$  where  $\frac{\hat{\eta}}{\hat{S}} \equiv \bar{\eta} = \frac{1}{5}\hat{T}\hat{\tau}_{rel}$
  - **IS:**  $\frac{d\bar{\pi}_{\eta}^{\eta}}{d\rho} + \frac{4}{3} \left(\bar{\pi}_{\eta}^{\eta}\right)^2 \tanh \rho + \frac{\bar{\pi}_{\eta}^{\eta}}{\hat{\tau}_{\text{rel}}} = \frac{4}{15} \tanh \rho$
  - **DNMR:**  $\frac{d\bar{\pi}^{\eta}_{\eta}}{d\rho} + \frac{4}{3} \left(\bar{\pi}^{\eta}_{\eta}\right)^2 \tanh \rho + \frac{\bar{\pi}^{\bar{\eta}}_{\eta}}{\bar{\tau}_{rel}} = \frac{4}{15} \tanh \rho + \frac{10}{21} \bar{\pi}^{\eta}_{\eta} \tanh \rho$
  - aHydro: see M. Nopoush et al., PRD 91 (2015) 045007
  - vaHydro: in preparation stay tuned!

\*For Bjorken flow, including (0+1)-d vaHydro, see UH@QM14

Prologue Kinetic theory vs. hydrodynamics	
---	--

## Overview

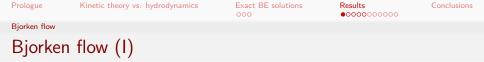
### 1 Prologue

- 2 Kinetic theory vs. hydrodynamics
- 3 Exact solutions of the Boltzmann equation
  - Systems undergoing Bjorken flow
  - Systems undergoing Gubser flow
  - Hydrodynamics of Gubser flow

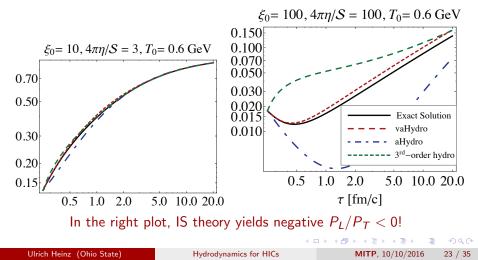
4 Results: Comparison of hydrodynamic approximations with exact BE

- Bjorken flow
- Gubser flow

### 5 Conclusions







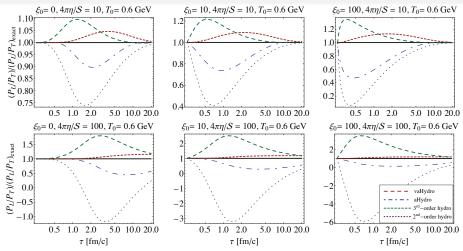
Exact BE solutions

Results

00000000000

Bjorken flow

## Bjorken flow (II)



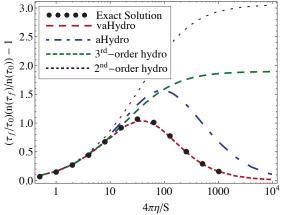
vaHydro agrees within a few % with exact result, even for very large  $\eta/S!$ 

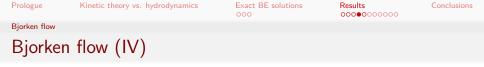
 Prologue
 Kinetic theory vs. hydrodynamics
 Exact BE solutions
 Results
 Conclusions

 Bjorken flow

 Bjorken flow (III)

 Total entropy (particle) production  $\frac{n(\tau_f) \cdot \tau_f}{n(\tau_0) \cdot \tau_0} - 1$ 





**Note:** The analysis just presented (from Bazow, UH, Strickland, PRC 90 ('14) 054910) used the zeroth moment of the BE to close the set of equations, and did not enforce the dynamical matching condition for  $\mathcal{P}_L - \mathcal{P}_T$  to be fully captured by the dynamical evolution of  $\xi$ . As a result of this weakness, a  $\delta \tilde{f}$  correction  $\tilde{\pi}^{\eta\eta}$  needed to be propagated dynamically to achieve agreement with the exact solution of the BE.

This flaw of Bazow, UH, Strickland, PRC 90 ('14) 054910 was recently fixed in Molnar, Niemi, Rischke, arXiv:1606.09019. If  $\xi$  is properly matched to  $\mathcal{P}_L - \mathcal{P}_T$ , for Bjorken flow **vaHydro exactly reduces to aHydro**, i.e. there are no  $\delta \tilde{f}$  correction at all! aHydro then reproduces the hydrodynamic moments of the exact BE solution f.a.p.p. exactly.

26 / 35

イロト 不得下 イヨト イヨト 二日

Exact BE solutions

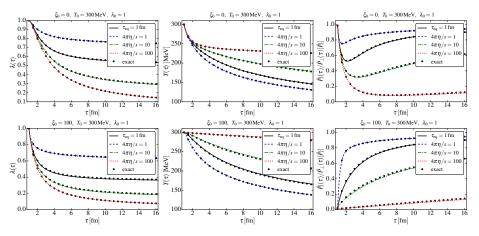
Results

Conclusions

#### Bjorken flow

# Bjorken flow (V)

## Molnar, Niemi, Rischke, arXiv:1606.09019

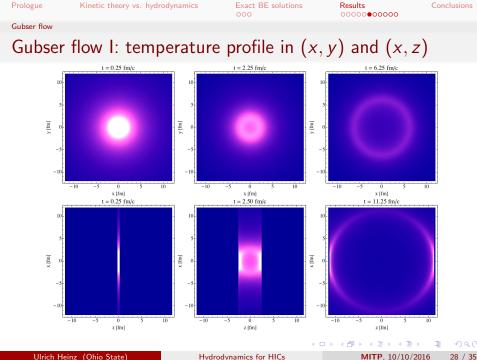


Ulrich Heinz (Ohio State)

MITP, 10/10/2016

Image: A math a math

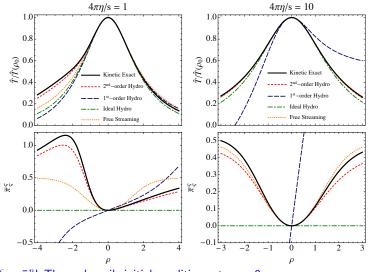
27 / 35



MITP, 10/10/2016

Gubser flow

Gubser flow II:  $\rho$ -evolution of temperature and shear stress



Note:  $\bar{\pi}_{s}^{\varsigma} \equiv \bar{\pi}_{\eta}^{\eta}!$  Thermal equil. initial conditions at  $\rho_{0} = 0$ .

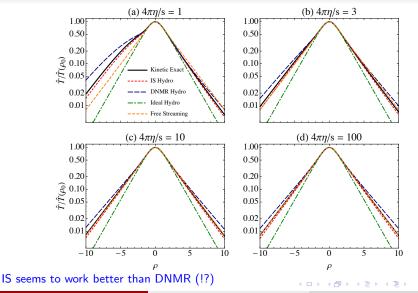
Ulrich Heinz (Ohio State)

29 / 35

Exact BE solutions

Gubser flow

Gubser flow III: temperature evolution in de Sitter time  $\rho$ 



Ulrich Heinz (Ohio State)

Hydrodynamics for HICs

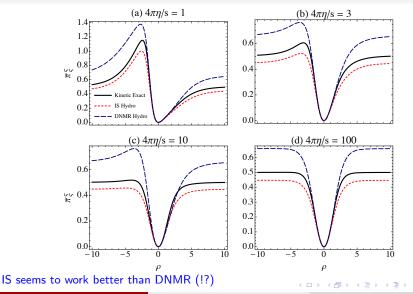
MITP, 10/10/2016 30 / 35

Exact BE solutions

Conclusions

Gubser flow

Gubser flow IV: shear stress evolution in de Sitter time  $\rho$ 



Ulrich Heinz (Ohio State)

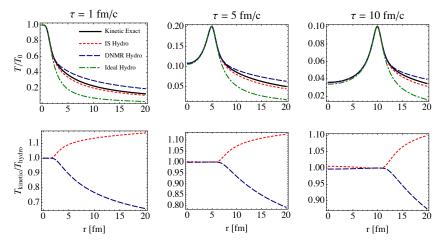
Hydrodynamics for HICs

MITP, 10/10/2016 31 / 35

Exact BE solutions

#### Gubser flow

## Gubser flow V: temperature evolution in Minkowski space



IS seems to work better than DNMR (!?)

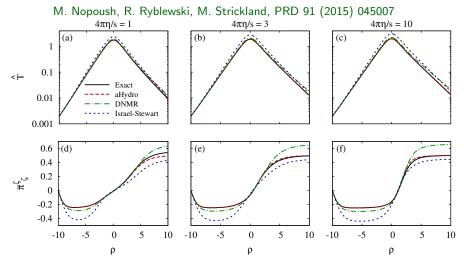
Both seem to have problems at large  $r\leftrightarrow$  large negative  $\rho$ 

Ulrich Heinz (Ohio State)

Exact BE solutions

Gubser flow

## Gubser flow in aHydro: $\rho$ -evolution of T and shear stress



Thermal equil. initial conditions at  $\rho_0 \rightarrow -\infty$ . aHydro works better than IS & DNMR<sub>DQQ</sub>

Ulrich Heinz (Ohio State)	Hydrodynamics for HICs	MITP, 10/10/2016	33 / 35

Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000

## Overview

### 1 Prologue

- 2 Kinetic theory vs. hydrodynamics
- 3 Exact solutions of the Boltzmann equation
  - Systems undergoing Bjorken flow
  - Systems undergoing Gubser flow
  - Hydrodynamics of Gubser flow
- 4 Results: Comparison of hydrodynamic approximations with exact BE
  - Bjorken flow
  - Gubser flow

### 5 Conclusions

Conclusions

Prologue	Kinetic theory vs. hydrodynamics	Exact BE solutions	Results 00000000000	Conclusions
Conclus	ions			

- Exact solutions of the Boltzmann equation with a relaxation time collision term for systems undergoing Bjorken or Gubser flow enable precise tests of hydrodynamic approximation schemes.
- The new Gubser flow solution of the BE extends these tests to a situation that resembles heavy-ion collisions where the created matter undergoes simultaneous longitudinal and transverse expansion.
- When compared with the exact solution, second-order viscous hydrodynamics (IS and DNMR) works better than NS theory, anisotropic hydrodynamics (aHydro) works better than hydrodynamic schemes based on an expansion around local mometum isotropy (IS and DNMR), and viscous anisotropic hydrodynamic (vaHydro) (which treats small viscous corrections as IS or DNMR but resums the largest viscous terms) outperforms aHydro.

Performance hierarchy: vaHydro > aHydro > DNMR  $\sim$  IS > NS > ideal fluid.

イロト 不得下 イヨト イヨト 二日