

The geometric bookkeeping guide to Feynman integral reduction and ε -factorised differential equations

MPA Retreat

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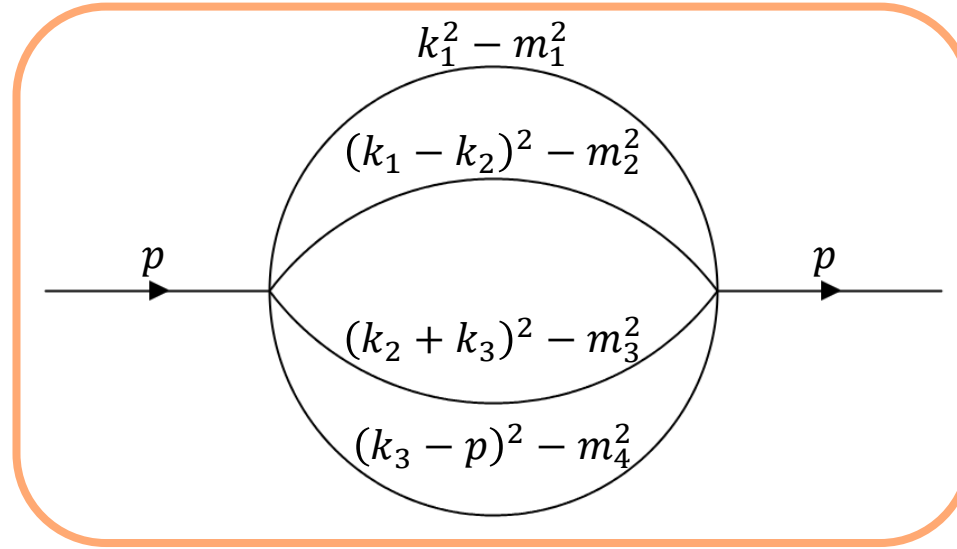
based on work with I.Bree, F.Gasparotto, A.Matijašić, P.Mazloui, S.Pögel, T.Teschke, X.Wang, S.Weinzierl, K.Wu, X.Xu

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Introduction

Feynman Integrals

Feynman Diagram:



Integral Family:

$$I_{n_1, \dots, n_N} \equiv e^{l\epsilon\gamma_E} (\mu^2)^{n - \frac{lD}{2}} \int \frac{d^D k_1}{(i\pi)^{D/2}} \cdots \frac{d^D k_l}{(i\pi)^{D/2}} \frac{1}{\sigma_1^{n_1} \cdots \sigma_N^{n_N}}$$

loop momenta
propagators

$$D = D_{\text{int}} - 2\epsilon$$

$$\sigma_j = q_j^2 - m_j^2$$

Integration-by-Parts Identities

$$I_{n_1, \dots, n_N} \propto \int \prod_{j=1}^{j=l} \frac{d^D k_j}{(i \pi)^{D/2}} \prod_{r=1}^{r=N} \frac{1}{\sigma_r^{n_r}}$$

$$\int \prod_{j=1}^{j=l} \frac{d^D k_j}{(i \pi)^{D/2}} \frac{\partial}{\partial k_{q, \mu}} \left\{ v_\mu \prod_{r=1}^{r=N} \frac{1}{\sigma_r^{n_r}} \right\} = 0 \quad \partial_{k_q}$$

loop momentum any momentum

Laporta Algorithm

Solve **complicated** integrals through **simple** integrals

$$\begin{aligned} J_1 - J_2 + 8 n^2 J_3 - 2 n J_4 - 2 n J_5 - 4 n J_6 &= 0 \\ -8 n J_3 + 2 J_4 - 2 J_5 + J_6 + J_7 &= 0 \\ J_2 - 8 n J_3 - 2 J_4 + 2 J_5 + \left(1 + \frac{1}{\text{eps}}\right) J_8 &= 0 \\ -2 n J_3 + J_8 - J_9 + 2 n^2 J_{10} - 2 n J_{11} - 4 n J_{12} &= 0 \\ -2 J_3 - 2 n J_{10} + 2 J_{11} + J_{12} + J_{13} &= 0 \\ 2 J_3 + J_9 - 2 n J_{10} - 2 J_{11} + J_{14} &= 0 \\ J_2 - J_{15} + 2 n^2 J_{16} - 2 n J_{17} - 2 n J_{18} - 4 n J_{19} &= 0 \\ -2 n J_{16} + 2 J_{17} - 2 J_{18} + J_{19} + J_{20} &= 0 \end{aligned}$$

Gauss
Elimination

Ordering?

Minimal set of **unknown** J

=

Master Integrals

Differential Equations

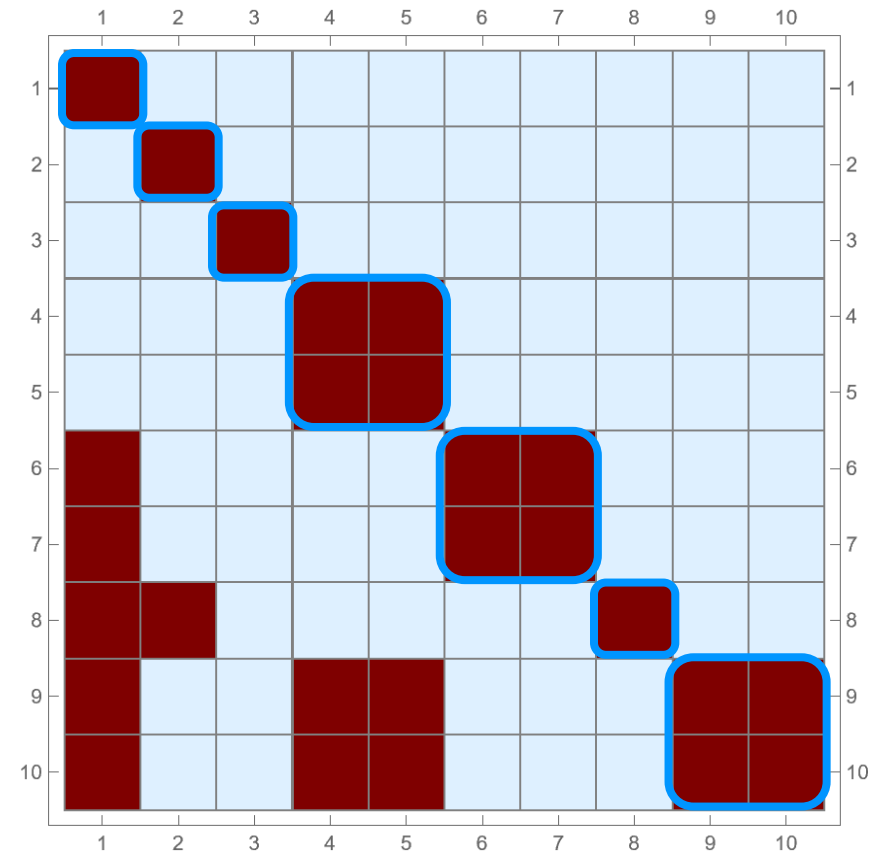
$$\begin{aligned} \frac{d}{dx} I_1 &= \tilde{I}_1 = c_1^1(x, \varepsilon) I_1 + \dots + c_{N_F}^1(x, \varepsilon) I_{N_F} \\ \vdots & \quad \quad \quad \text{IBPs} \quad \quad \quad \vdots \quad \quad \quad \vdots \\ \frac{d}{dx} I_{N_F} &= \tilde{I}_{N_F} = c_1^{N_F}(x, \varepsilon) I_1 + \dots + c_{N_F}^{N_F}(x, \varepsilon) I_{N_F} \end{aligned}$$

$$\frac{d}{dx} \vec{I} = \tilde{A}(x, \varepsilon) \vec{I}$$

Integration



Solving DEQs



Homogeneous Parts

ε -Factorized Form

“Rotate” the basis $\vec{K} = R^{-1}(\varepsilon, x) \vec{I}$:

Ansatz $\vec{K} = \sum_{n=0} \varepsilon^n \vec{K}^{(n)}(x)$:

LHS: $\frac{d}{dx} \sum_{n=0} \varepsilon^n \vec{K}^{(n)}(x)$

RHS: $\varepsilon A(x) \sum_{n=0} \varepsilon^n \vec{K}^{(n)}(x)$

$$R^{-1} \tilde{A}(\varepsilon, x) R - R^{-1} \frac{d}{dx} R$$

$$\frac{d}{dx} \vec{K} = \varepsilon A(x) \vec{K}$$

Iterative solution:

$$O(\varepsilon^0): \frac{d}{dx} \vec{K}^{(0)} = 0$$

$$O(\varepsilon^1): \frac{d}{dx} \vec{K}^{(1)} = A(x) \vec{K}^{(0)}$$

$\vdots$

$$O(\varepsilon^n): \frac{d}{dx} \vec{K}^{(n)} = A(x) \vec{K}^{(n-1)}$$

Algorithm

Steps

1. Preliminary $\vec{J}$ -basis using *clever ordering*

$$\frac{d}{dx} \vec{J} = \sum_{k=k_{\min}}^{k=1} \varepsilon^k A^{(k)}(x) \vec{J}$$

$$\vec{K} = R^{-1}(\varepsilon, x) \vec{J}$$

2. *Rotate* into ε -factorized $\vec{K}$ -basis

$$\frac{d}{dx} \vec{K} = \varepsilon A(x) \vec{K}$$

Building Blocks

Feynman Integrand
(in Baikov representation)

$\int$

$$\Psi_{\mu_0 \dots \mu_{N_D}}[Q] = C_\varepsilon U(z) \hat{\Phi}_{\mu_0 \dots \mu_{N_D}}[Q] \eta$$

$$\propto I_{n_1, \dots, n_N}$$

Objects

- Appropriate pre-factor C_ε
- Twist $U(z)$
- Rational polynomials P_i
- Differential form $\hat{\Phi}$

$$U(z_0, \dots, z_n) = \prod_{i, \text{odd}} P_i^{-\frac{1}{2} + \frac{1}{2} b_i \varepsilon} \prod_{j, \text{even}} P_j^{\frac{1}{2} b_j \varepsilon}$$

$$\hat{\Phi}_{\mu_0 \dots \mu_{N_D}}[Q] = \frac{Q}{\prod_i P_i^{\mu_i}}$$

$$\eta = \sum_{j=0}^n (-1)^j z_j dz_0 \wedge \dots \wedge \cancel{dz_j} \wedge \dots dz_n$$

Ordering!

$$(a, r, o, |\mu|, \dots)$$

Number of residues of $\Psi_{\mu_0 \dots \mu_{N_D}}^0 [Q]$

$\varepsilon \rightarrow 0$

Pole order of $\Psi_{\mu_0 \dots \mu_{N_D}}^0 [Q]$

Denominator power of $\Psi_{\mu_0 \dots \mu_{N_D}}^0 [Q]$

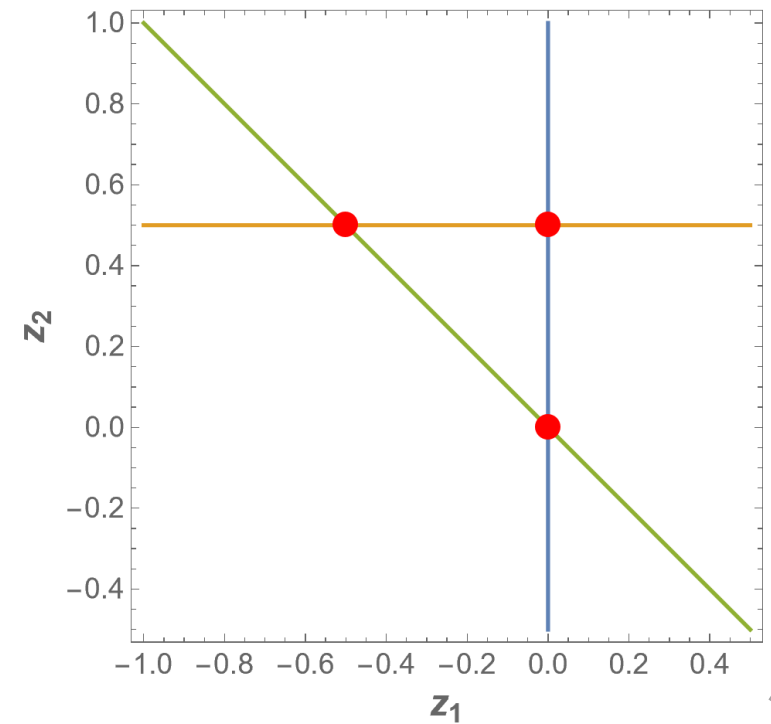
Example

$$\frac{\eta}{z_1(z_2 - x)(z_1 + z_2)}$$

2 consecutive residues at
 $(z_1, z_2) = \{(0,0), (0, x), (-x, 0)\}$

PO 2 at
 $(z_1, z_2) = \{(0,0), (0, x), (-x, 0)\}$

$$|\mu| = 1 + 1 + 1 = 3$$



Ordering!

Number of residues of $\Psi_{\mu_0 \dots \mu_{N_D}}^0[Q]$

Pole order of $\Psi_{\mu_0 \dots \mu_{N_D}}^0[Q]$

Denominator power of $\Psi_{\mu_0 \dots \mu_{N_D}}^0[Q]$

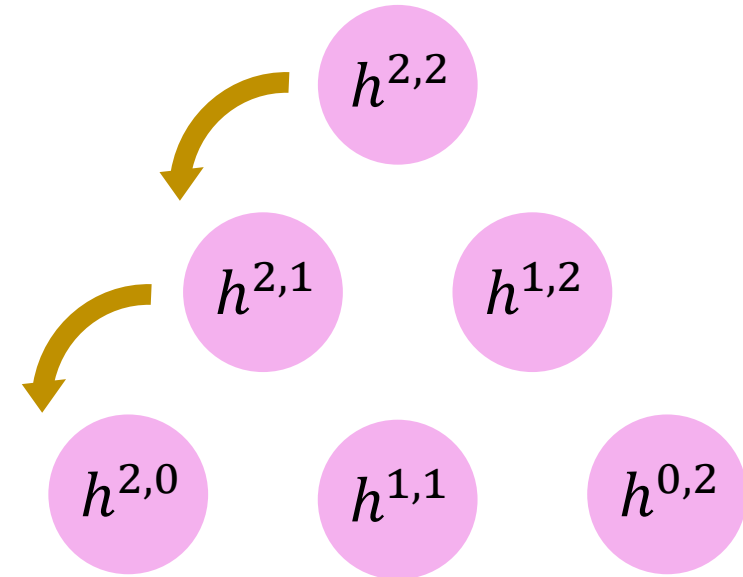
Localization level of $\Psi_{\mu_0 \dots \mu_{N_D}}^0[Q]$

$\vec{J}$ -basis

$(a, r, o, |\mu|, \dots)$

Example

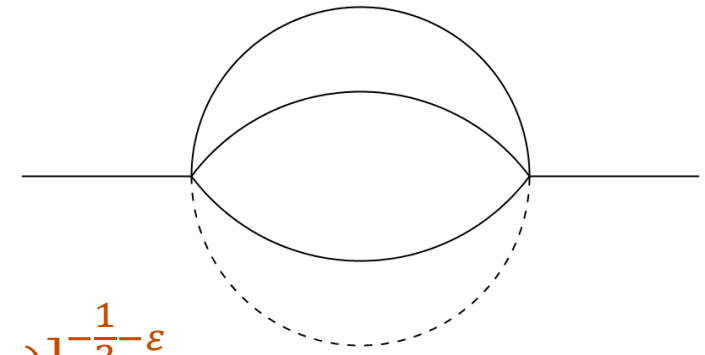
Find basis of
subsystems



Step 1



Example: Electron Self-Energy



$$U^0 = \underbrace{z_0^{4\varepsilon} z_2^\varepsilon (z_0 - z_2)^{-2\varepsilon}}_{P_{\text{even}}} \underbrace{z^{-\frac{1}{2}} (z_1 - 4xz_0)^{-\frac{1}{2}-\varepsilon} [x^2 z_0^2 + (z_1 - z_2)^2 - 2xz_0(z_1 + z_2)]^{-\frac{1}{2}-\varepsilon}}_{P_{\text{odd}}}$$

$$\Phi_1 = \frac{1}{z_2}$$

$$r = 2, o = 2, |\mu| = 1$$

$$\Phi_2 = \frac{z_1}{z_0(z_0 - z_2)}$$

$$r = 2, o = 2, |\mu| = 2$$

$$\Phi_3 = \frac{1}{z_0}$$

$$r = 2, o = 2, |\mu| = 1$$

$$\Phi_4 = \frac{1}{z_0 - z_2}$$

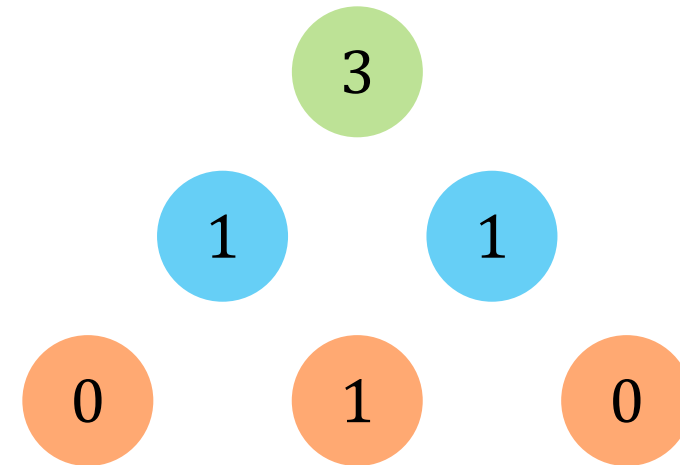
$$r = 1, o = 1, |\mu| = 1$$

$$\Phi_5 = \frac{z_0}{(z_1 - 4xz_0)(z_0 - z_2)}$$

$$r = 1, o = 2, |\mu| = 1$$

$$\Phi_6 = \frac{1}{z_1 - 4xz_0}$$

$$r = 0, o = 1, |\mu| = 0$$



6 Forms



3 Integrals

Example: Electron Self-Energy

$$I_{n_1, \dots, n_N} \propto \int \prod_{j=1}^{j=l} \frac{d^D k_j}{(i \pi)^{D/2}} \prod_{r=1}^{r=N} \frac{1}{\sigma_r^{n_N}}$$

$$\vec{J} \propto \{I_{1,1,1,1,\vec{0}}, I_{1,2,1,1,\vec{0}}, I_{1,1,1,1,-1,\vec{0}}\}$$

$$d_x \vec{J} = \left(\begin{array}{c|c} 0 & 6\epsilon \\ \hline \frac{1-3x}{2F(x)} \frac{1}{\epsilon} + \frac{5-21x}{2F(x)} + \frac{1+9x-18x^2}{xF(x)} \epsilon & -\frac{1-20x+27x^2}{F(x)} + \frac{1+30x-63x^2}{F(x)} \epsilon \\ -4 - \frac{8(1+6x)}{3x} \epsilon & -8(1+3x)\epsilon \end{array} \right) \vec{J}$$

$$\frac{1}{\epsilon} \left(\begin{array}{c|c} & \\ \hline \text{red box} & \end{array} \right) + \epsilon^0 \left(\begin{array}{c|c} \text{blue box} & \\ \hline \text{blue box} & \text{blue box} \end{array} \right) + \epsilon \left(\begin{array}{c|c} \text{green box} & \text{green box} \\ \hline \text{green box} & \text{green box} \end{array} \right)$$

“Rotation”

$$\vec{K} = R^{-1}(\varepsilon, x)\vec{J} = \left[\boxed{R^{(-1)}(\varepsilon, x)} \boxed{R^{(0)}(\varepsilon, x)} \right] \vec{J}$$

remove ε^{-1}

remove ε^0

$$\left(\begin{array}{c|cc} \varepsilon^0 g_1 & & \\ \hline \varepsilon^{-1} g_2 & \varepsilon^0 g_4 & \varepsilon^0 g_6 \\ \varepsilon^{-1} g_3 & \varepsilon^0 g_5 & \varepsilon^0 g_7 \end{array} \right)$$

$$\left(\begin{array}{c|c} 1 & \\ \hline \varepsilon^0 f_1 & 1 \\ \varepsilon^0 f_2 & 1 \end{array} \right)$$



Functions g_j, f_j depend only on kinematics x

Integration Kernels

$$F(x) = x(x-1)(x-9)$$

Applied to the example:

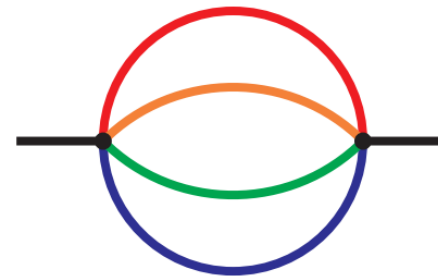
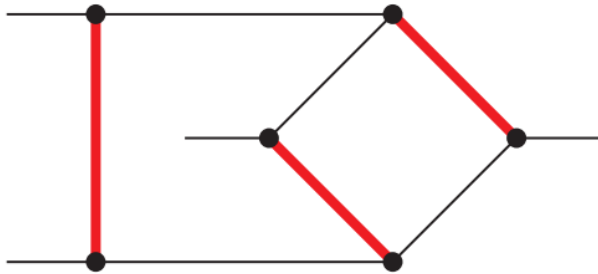
$$d_x \vec{K} = \varepsilon \begin{pmatrix} \frac{1 + 30x - 63x^2}{2F(x)} & \frac{6}{xF(x)\psi^2(x)} & 0 \\ \dots & \frac{1 + 30x - 63x^2}{2F(x)} & \frac{3\psi(x)}{2x} \\ \frac{24F(x)}{8\psi(x)} & 0 & -\frac{4}{x} \end{pmatrix} \vec{K}$$

Period of an elliptic curve

Summary

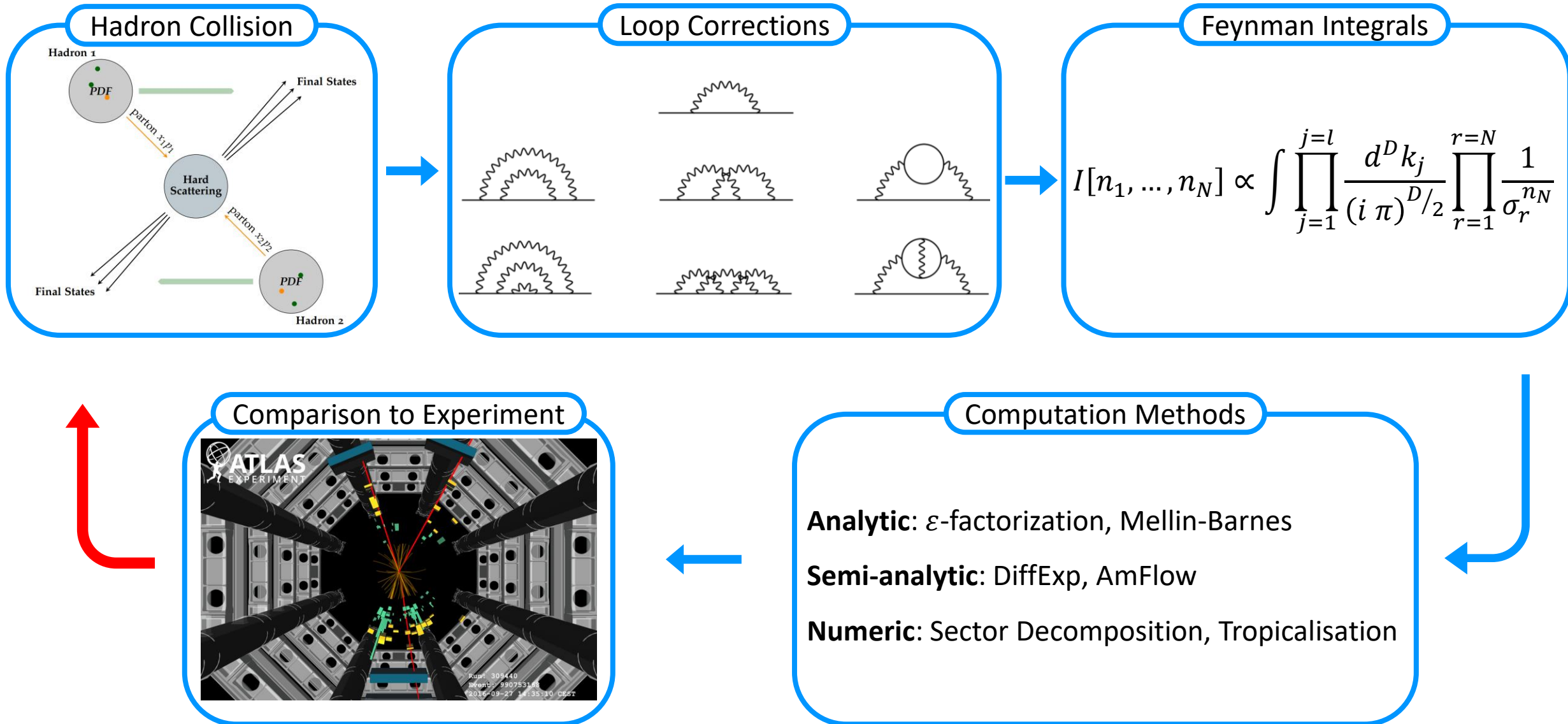
- Feynman Integrals are **building blocks** of scattering amplitudes
- Their analytic computation can be achieved using **DEQ and ε -factorization**
- Proposed approach constructs this transformation **algorithmically**

More examples to follow!



Back-Up Slides

Motivation



Motivation IBPs

$$I_n(\alpha) = \int_0^\infty e^{-\alpha x^2} x^n dx$$

n even $\rightarrow I_n = (-\partial_\alpha)^{\frac{n}{2}} I_0$

n odd $\rightarrow I_n = (-\partial_\alpha)^{\frac{n-1}{2}} I_1$

- “Master Integrals”:

$$\left\{ I_0(\alpha) = \frac{1}{2} \sqrt{\frac{\pi}{\alpha}}, I_1(\alpha) = \frac{1}{2\alpha} \right\}$$

Baikov Representation

$$I_{n_1, \dots, n_N} \propto \int \prod_{j=1}^{j=l} \frac{d^D k_j}{(i\pi)^{D/2}} \prod_{r=1}^{r=N} \frac{1}{\sigma_r^{n_N}}$$

Momentum Rep

Integrate in loop momenta k_j



Baikov Rep

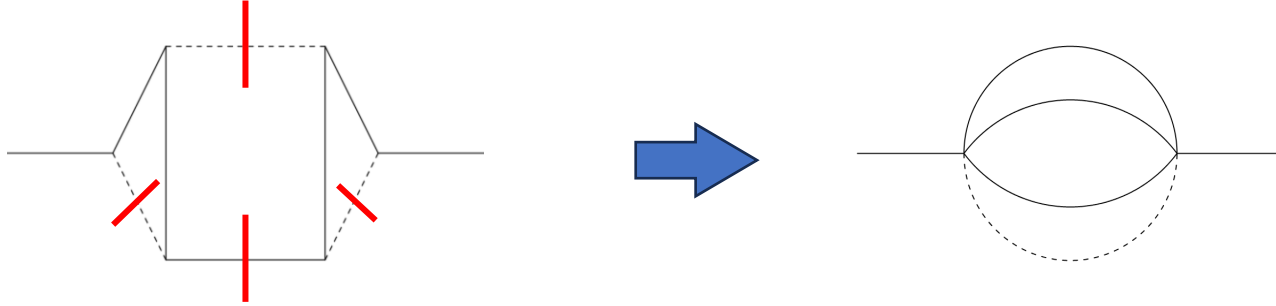
Integrate in propagators σ_j

$$I_{n_1, \dots, n_N} \propto \int_{\mathcal{C}} \frac{B(\sigma)^\beta d^n \sigma}{\prod_j \sigma_j^{a_j}}$$

$$\mathcal{B} = \text{Gram}(k_1, \dots, k_L, p_1, \dots, p_E)$$

$$\beta = (d - E - L - 1)/2$$

Self-Energy Sectors



Scaleless Integrals

- To show the above expectation is too generous, consider an example of a *Scaleless Integral*:

$$\begin{aligned}
 I &\equiv \int_{k_1, k_2} \frac{1}{[k_1 \cdot p_i]^m [k_2 \cdot p_i]^n \cdots} \xrightarrow[k_j \rightarrow \lambda k_j]{k_i \rightarrow \lambda k_i} \int_{k_1, k_2} \frac{1}{[k_1 \cdot \lambda p_j]^m [k_2 \cdot \lambda(p_i + p_j)]^n \cdots} \\
 &\quad \begin{array}{l} \text{rescale back } k_1, k_2 \\ \downarrow \qquad \qquad \qquad \downarrow \\ = I \qquad \qquad \qquad = \underbrace{\lambda^{-m-n+\cdots}}_{\equiv \lambda^\alpha} I \end{array}
 \end{aligned}$$

- $\alpha \neq 0$ in dimensional regularization, hence:

$$(\lambda^\alpha - 1)I = 0 \quad \Rightarrow \quad I = 0$$

scaleless integrals
vanish in dimreg



fully reducible
sectors

More on Differential Equations

- Instead of computing **integrals**, we will solve a system of **differential equations**!

Main idea:

1. Derivative of a Master Integral will give a different integral within the same family
 2. This integral can again be reduced to a linear combination of Master Integrals
 3. We obtain a relation between a derivative of an MI and a linear combination of MIs
- Integrals depend on scalar values (e.g. u, s, t), it makes sense to take derivatives with respect to them

to be reduced using IBPs

vector of Master Integrals

$$p_{j,\mu} \frac{\partial \vec{I}}{\partial p_{k,\mu}} = \sum_{\alpha=1}^N \left(p_{j,\mu} \cdot \frac{\partial s_{\alpha}}{\partial p_{k,\mu}} \right) \frac{\partial \vec{I}}{\partial s_{\alpha}}$$

with $p_j, p_k \in \{p_i, p_j\}$

scalar variable