

Optimal Quantum Control for Precision Frequency Measurement

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Optimal control work (not my own!):

Pang and Jordan, Nature Communications 8:14695 (2017)

Naghiloo, Jordan, Murch, PRL 119, 180801 (2017)

Schmitt et al., Science 356 832-837 (2017)

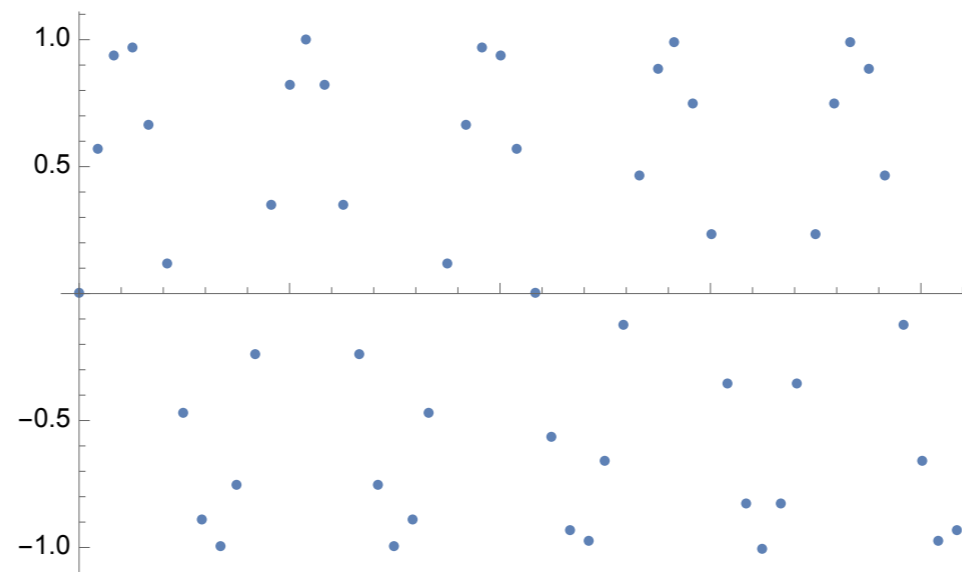
Application to axion detection:

Foster, Gao, Halperin, YK, Mande, Nguyen, Schütte-Engel, Scott, arXiv:2310.07791



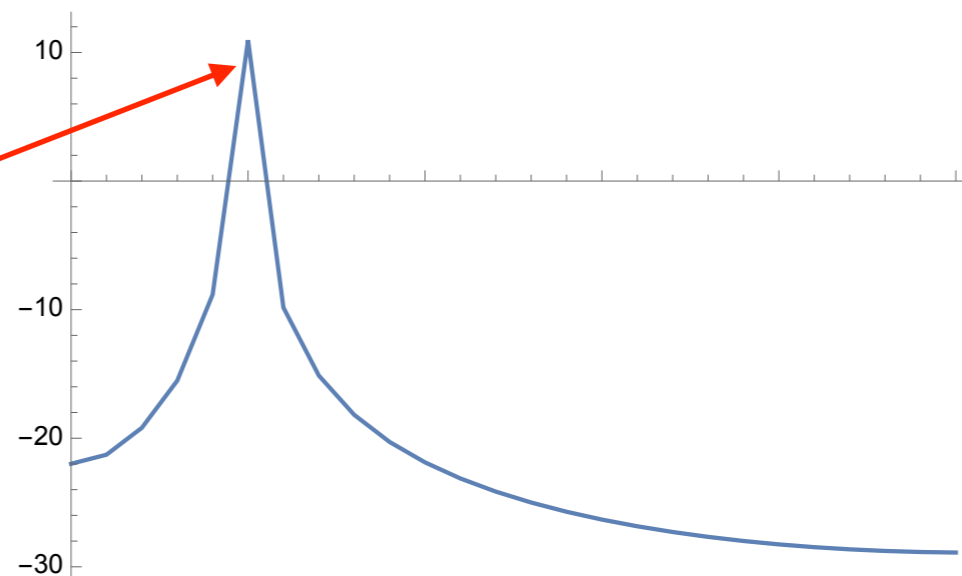
Frequency estimation

You have some time-series data. You think it's described by an oscillation at a single frequency ω . How do you estimate ω ?



The obvious solution: discrete Fourier transform

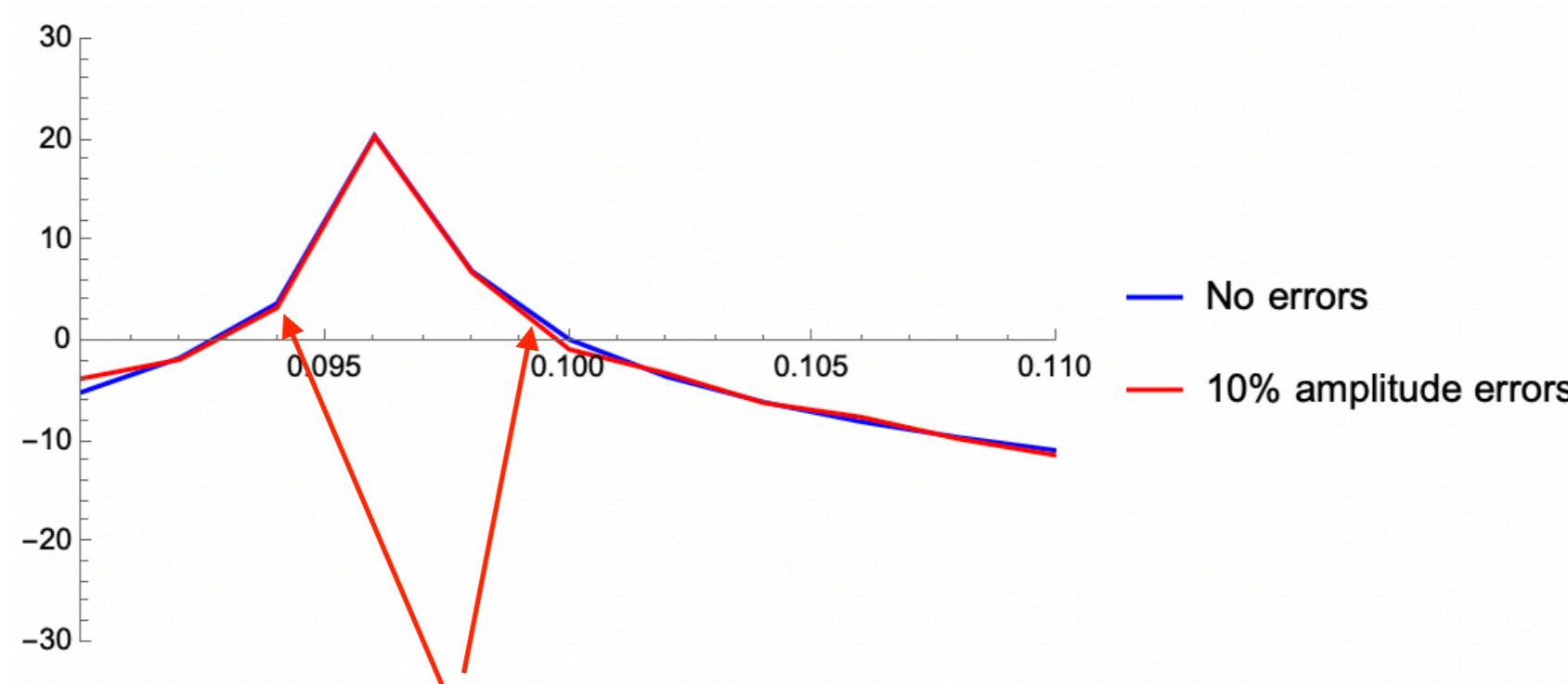
how precise
is that peak
location?
what about the
width?



Problems with the classical approach

Even with perfect data, Nyquist's theorem says $\Delta\omega \sim 1/T$

But what if your data is polluted by amplitude noise?



width of peak shifts: small, but it's there!

Quantum lets us do better

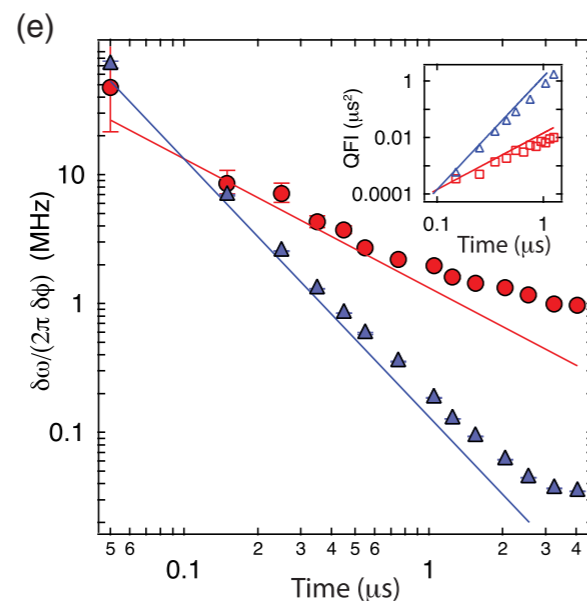
With optimal quantum control, we can gain a factor of T:

$$\Delta\omega \sim 1/T \rightarrow 1/T^2$$

classical, or SQL optimal control

Even better for a frequency drift: $\Delta\dot{\omega} \sim 1/T^3$

The trick is to let ω modulate the level splitting of a qubit, and use a **time-dependent** control Hamiltonian to poke the system at judiciously-chosen intervals. Amplitude noise never enters!

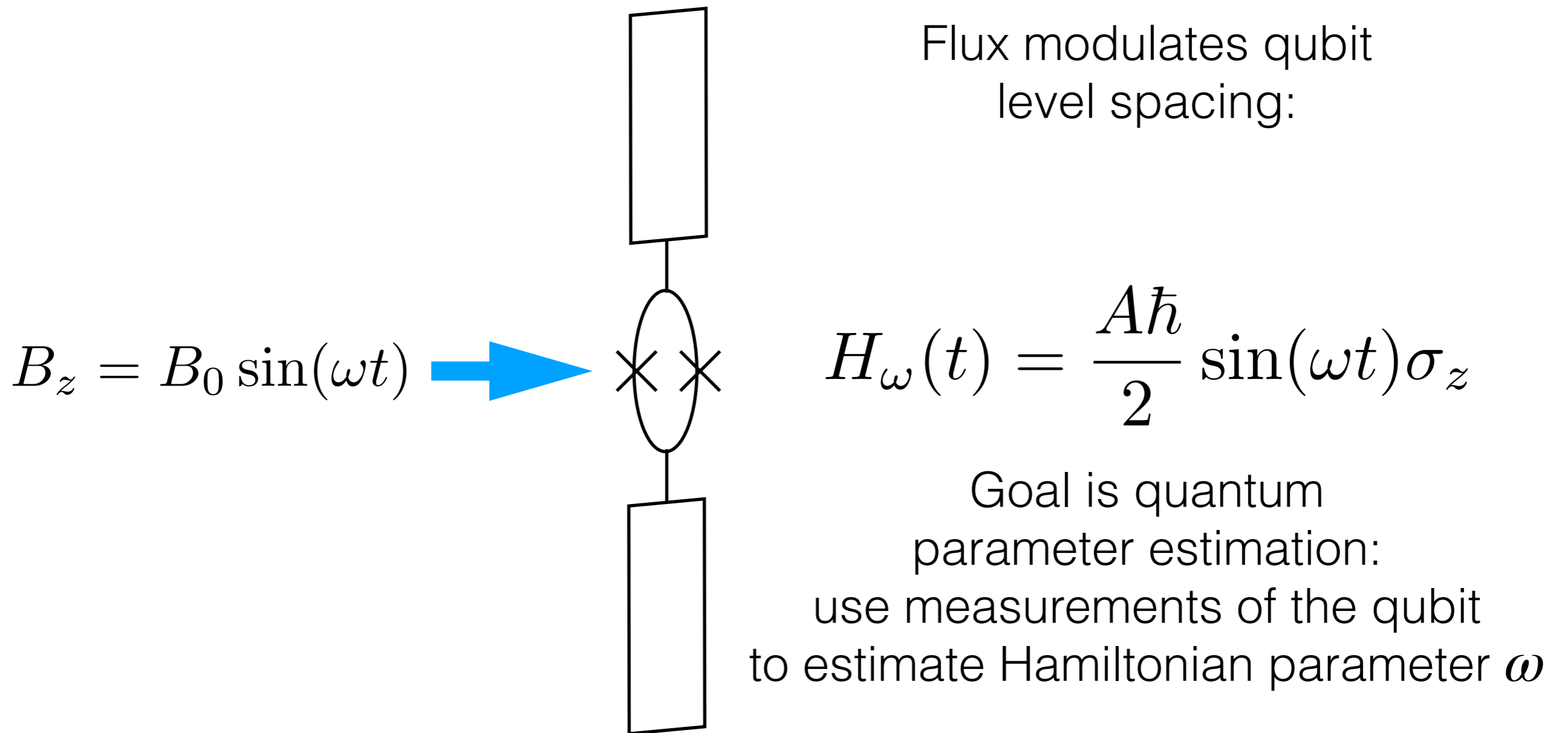


This actually works!! Let's see how.

no control

control

Setup: B-field and superconducting qubit



Metrology and Fisher Information

Suppose we are trying to measure g , which is a parameter controlling the probability distribution of an observable X : $X \sim p_g(X)$

Cramér-Rao bound tells us the best we can do:

$$\langle \delta^2 \hat{g} \rangle \geq \frac{1}{v I_g}$$

mean squared deviation unbiased estimator amount of data Fisher information:

$$I_g = \int p_g(X) [\partial_g \ln p_g(X)]^2 dX$$

Quantum metrology

In a quantum measurement, $p_g(X)$ comes from measurements on quantum states parameterized by g , i.e. $|\psi_g\rangle$

The relevant quantity is the quantum Fisher information:

$$I_g^{(Q)} = 4 \left[\langle \partial_g \psi_g | \partial_g \psi_g \rangle - \left| \langle \psi_g | \partial_g \psi_g \rangle \right|^2 \right]$$

Measures distinguishability of two states under small variations of g

$$\text{SQL: } I_g^{(Q)} \propto N$$

$$\text{Heisenberg: } I_g^{(Q)} \propto N^2$$

What about scaling with measurement time?

Time-dependent metrology

Suppose our parameter multiplies a time-independent Hamiltonian,

$$H_g = gH_0$$

If we let the system evolve for time T , we have $|\psi_g\rangle = e^{-igH_0T} |\psi_0\rangle$

Easy to show that
$$I_g^{(Q)} = 4T^2 \left[\langle H_0^2 \rangle_g - \langle H_0 \rangle_g^2 \right]$$

Lessons: we don't want to measure in an eigenstate of H_0 where the variance vanishes, but no matter what, $\sigma_g \propto 1/T$

But we can let the system evolve with a time-dependent Hamiltonian!

$$I_g^{(Q)} = 4 \text{Var}[h_g(T)]_{|\psi_0\rangle}$$

$$h_g(T) = iU_g^\dagger(0 \rightarrow T) \partial_g U_g(0 \rightarrow T)$$

unitary evolution (time-ordered exponential)
under $H_g(t)$

Optimal control for frequency

Let's go back to our original problem:

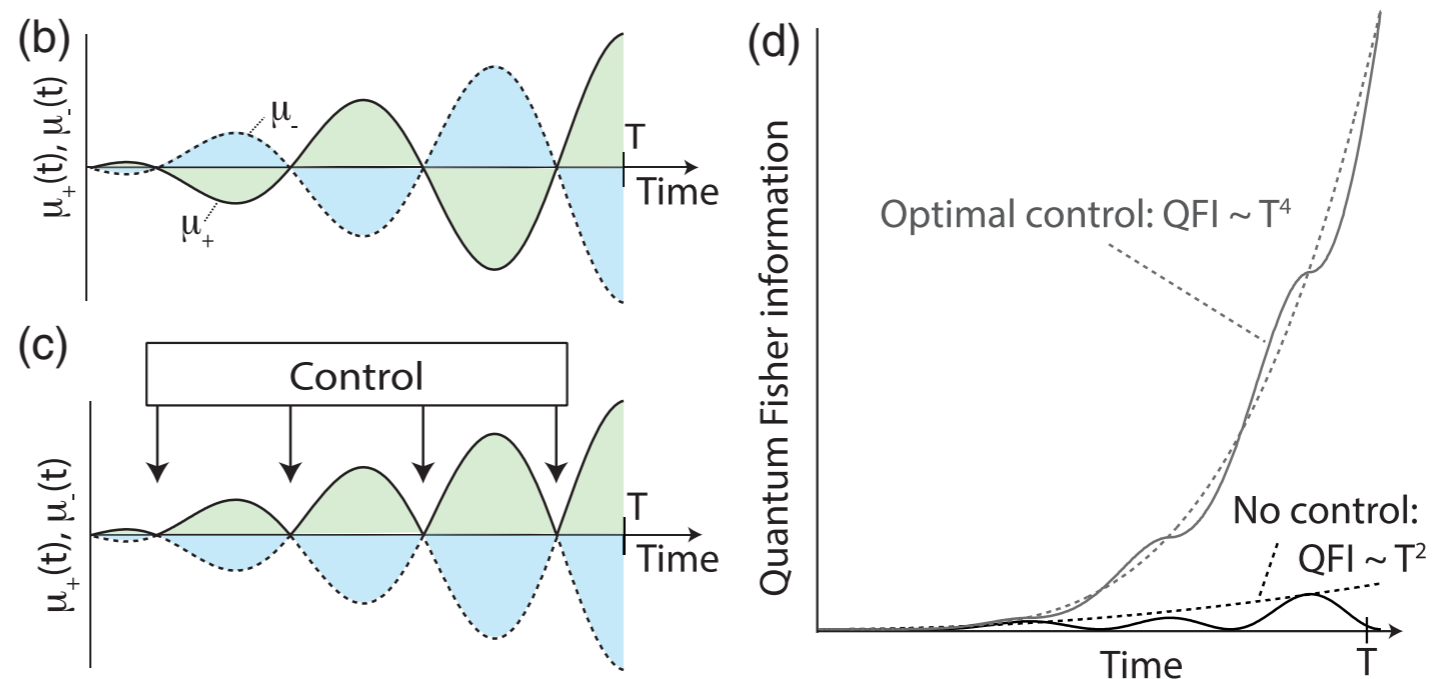
$$H_\omega(t) = \frac{A\hbar}{2} \sin(\omega t) \sigma_z \implies h_\omega(t) = \frac{A\hbar}{2} t \cos(\omega t) \sigma_z$$

H commutes with itself at different times, no time-ordering necessary

Eigenvalues: $\mu_\pm = \pm \frac{A\hbar}{2} t \cos(\omega t) \implies I_\omega^{(Q)} = \left(\int_0^T [\mu_+(t) - \mu_-(t)] dt \right)^2$

The control step is best explained in pictures:

(Time-dependent) control maximally separates eigenvalues to maximize QFI



Optimal frequency estimation

Prepare qubit in a superposition of H_ω eigenstates, which maximizes QFI:

$$|\psi_\omega\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$$

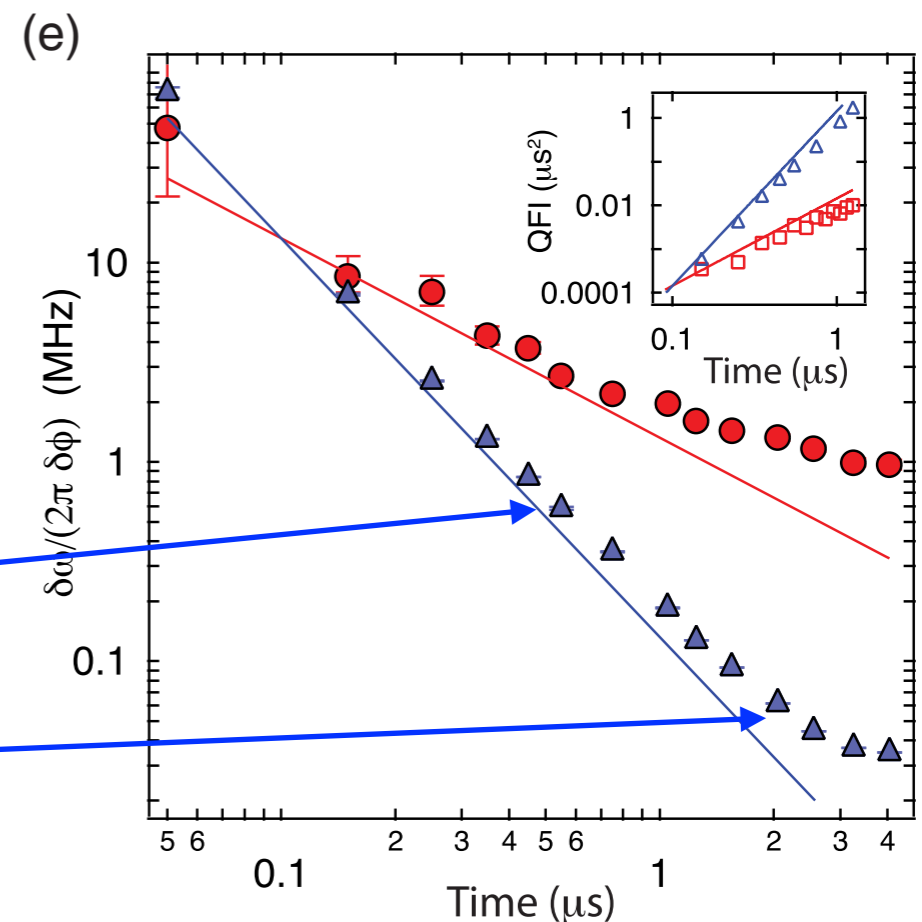
Evolution under H_ω and control will make the two eigenstates acquire a relative phase ϕ . Measure ϕ (ideally, non-destructively):

$$\frac{\delta\omega}{\omega} = \frac{\pi}{\omega AT^2} \delta\phi = \frac{\pi}{\omega AT^2 \sqrt{4Nq}}$$

This is a true quantum advantage!
(Up to the qubit coherence time)

$$\omega T \gtrsim \pi$$

$$T > T_2^*$$

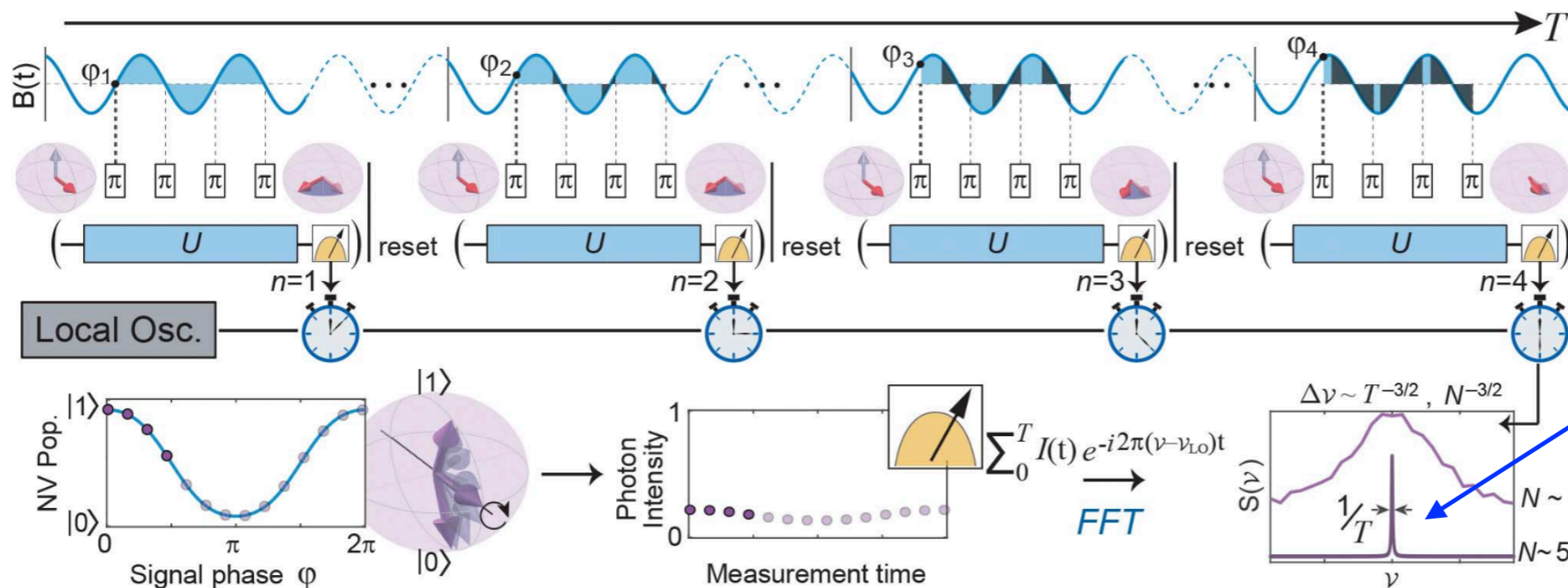


What about longer times?

If the signal is very coherent, just time-stamp the measurements at intervals of Δt with the best clock you can find!

$$I_{\omega}^{(Q)} = \frac{4A^2}{\omega^2} \sum_{j=1}^{T/\Delta t} (\Delta t)^2 \left[\sin(\omega j \Delta t) - \sin(\omega(j-1)\Delta t) \right] \sim \frac{A^2}{\omega^2} T^3$$

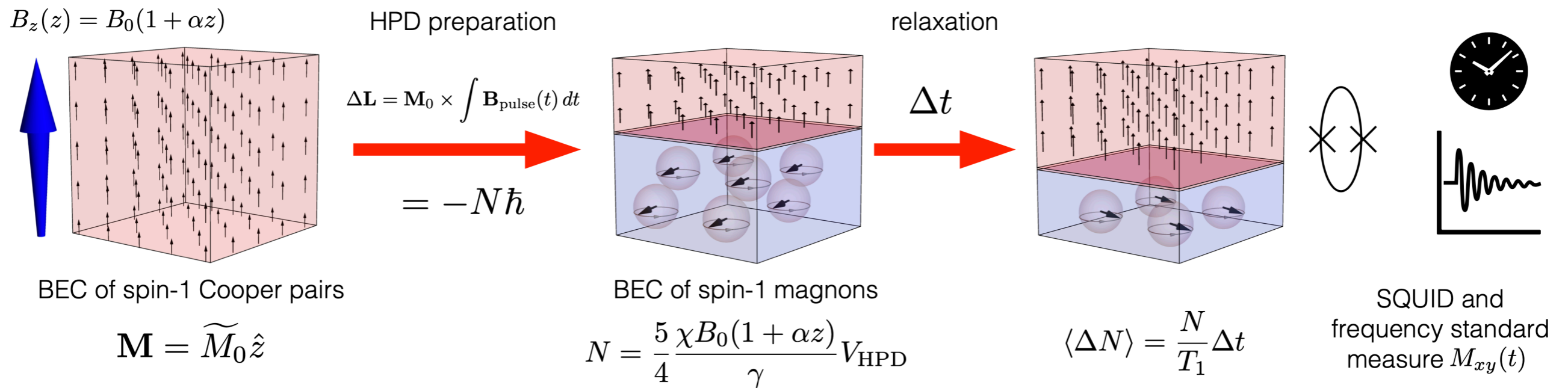
This lets you beat the qubit coherence time limit:



$$\frac{\delta\omega}{\omega} \sim \frac{1}{\omega A T^{3/2} \sqrt{T_2^*}}$$

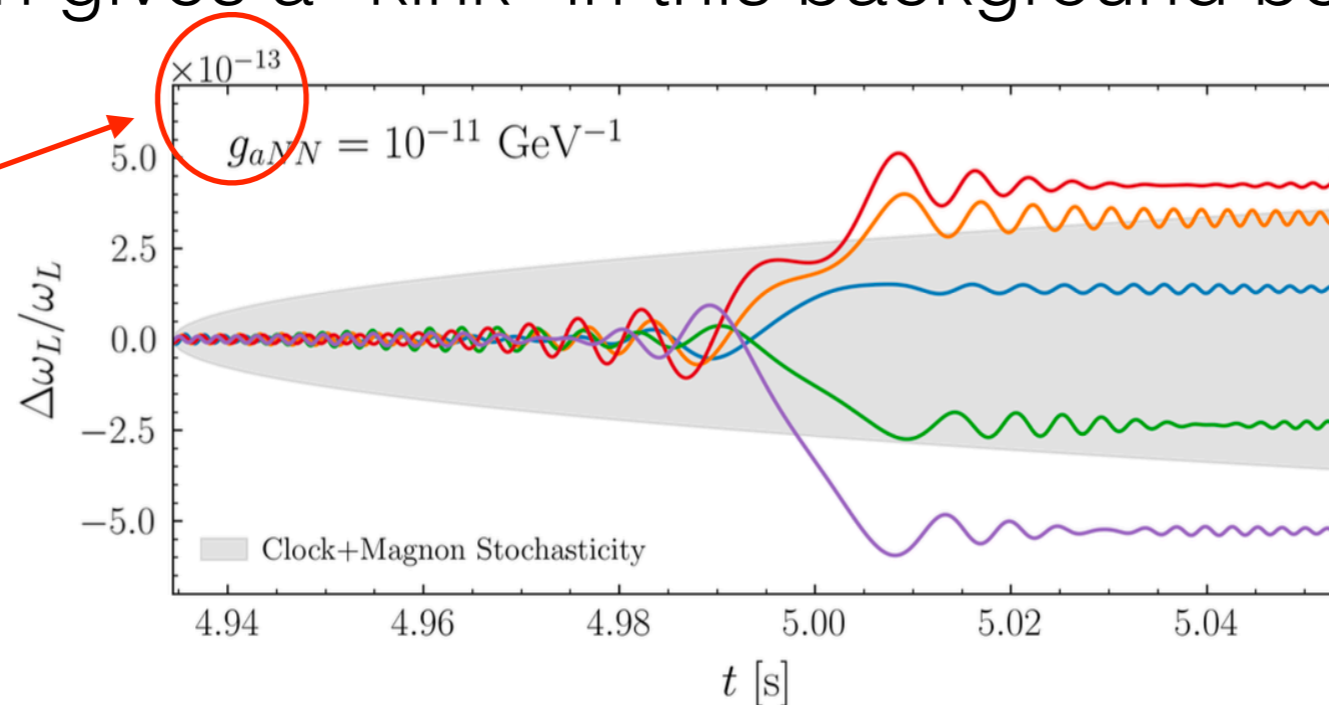
Application: axions + HPD

HPD review in one slide:



In absence of an axion, slowly drifting precession frequency.
 Axion gives a “kink” in this background behavior

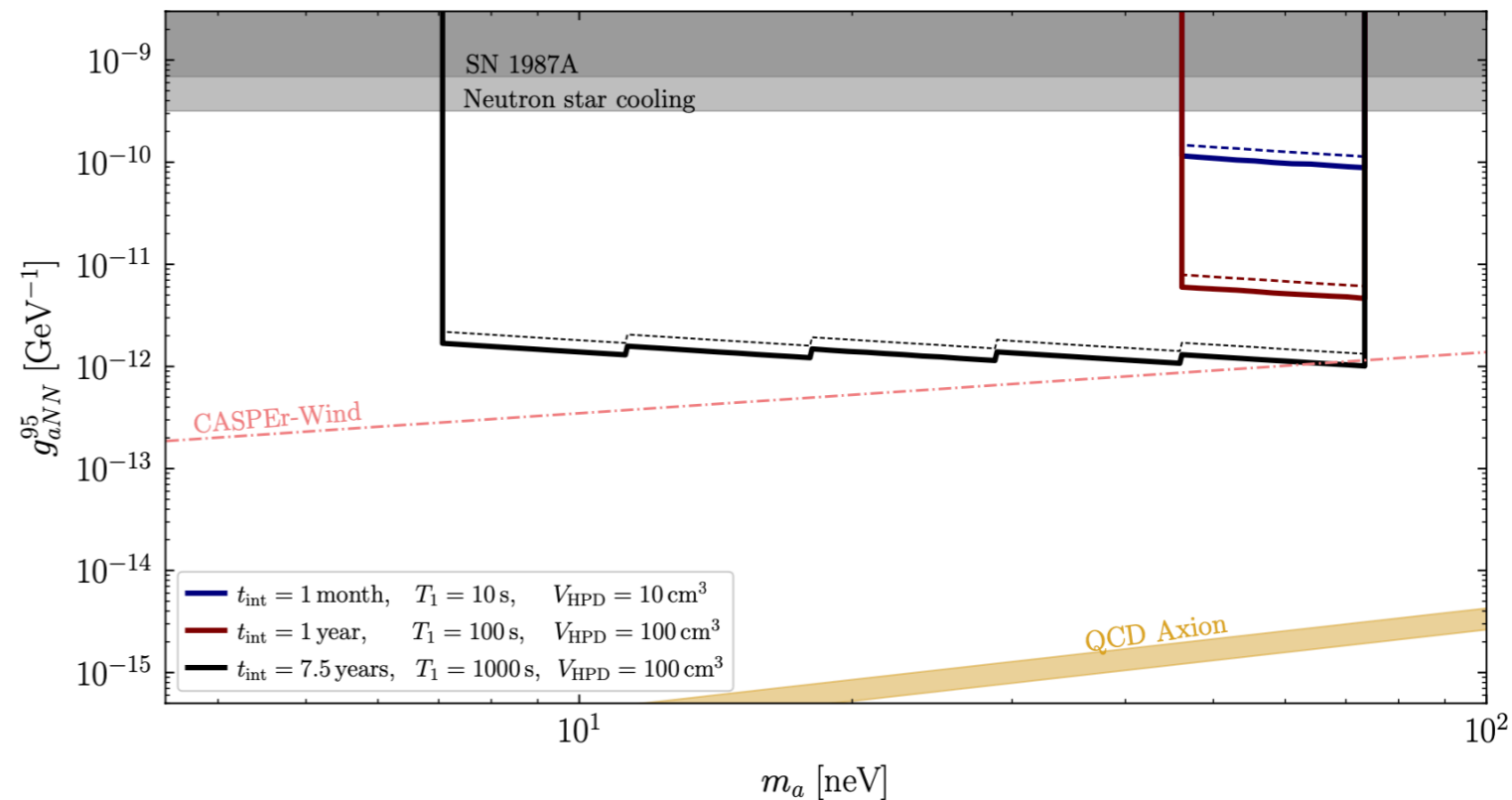
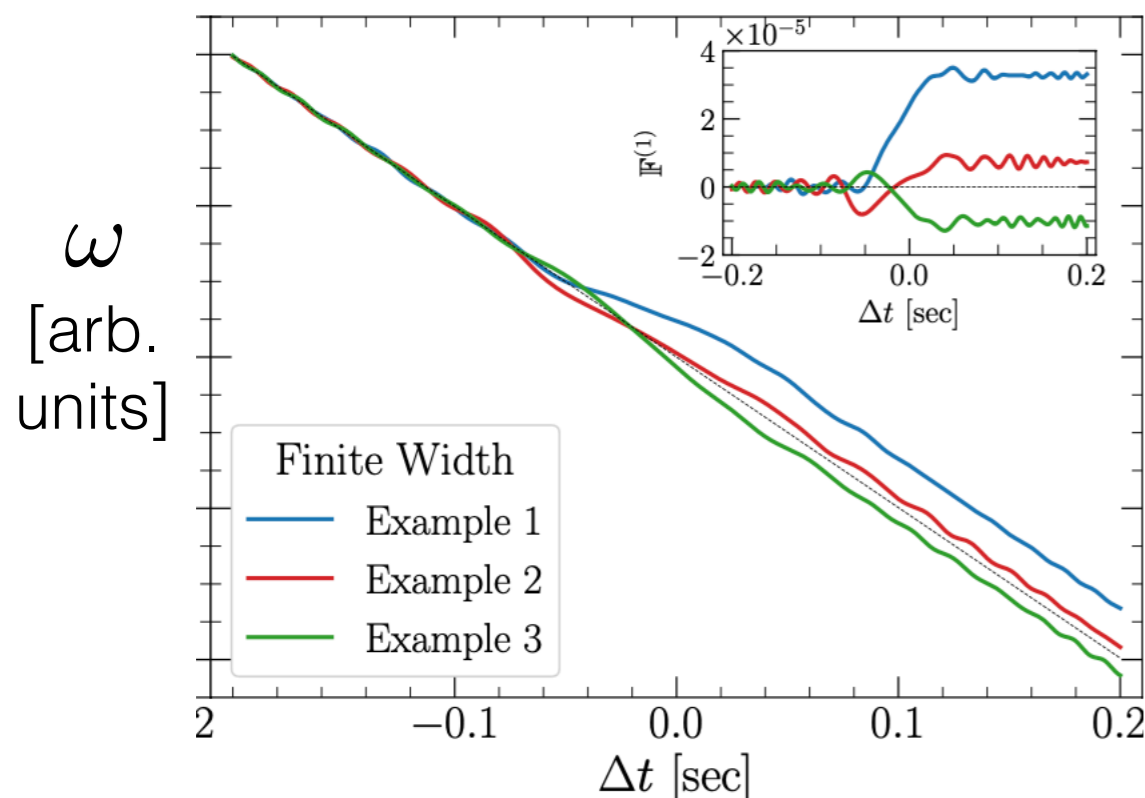
need incredible precision!



Application: axions + HPD

Use same optimal control scheme to measure a frequency drift:

$$H_{\dot{\omega}}(t) = A \sin(\omega t + \dot{\omega} t^2 / 2) \frac{\sigma_z}{2} \quad \longrightarrow \quad \delta\dot{\omega} \approx \frac{\sqrt{5}\pi}{2AT^{5/2}\sqrt{T_q N_q}}$$



Frequency drift proportional to axion coupling: no information in the amplitude A , which only appears as an overall scale.

Robust to amplitude noise!