

Intersecting companion matrices for Feynman integrals

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Theory and Phenomenology
of Fundamental Interactions
UNIVERSITY AND INFN - BOLOGNA



Istituto Nazionale di Fisica Nucleare



Based on joined work with:

Giacomo Brunello, Giulio Crisanti, Hjalte Frellesvig,
Federico Gasparotto, Manoj Mandal, Pierpaolo Mastrolia
+ Andrzej Pokraka

[2401.01897] [2408.16668] + ongoing

Loop the Loop
November 12, 2024

1 Introduction

2 Intersection numbers with tensors

3 Conclusion

Introduction

Feynman twisted period integrals

- Amplitude at fixed loop order = sum of families. Each family = sum of master integrals

$$\mathcal{A} = \sum_i c_i \mathcal{I}_i$$

- Master decomposition formula (abusing notation)

[Mastrolia
Mizera '18] [FGLMMMM '19]

$$\langle \mathcal{A} | = \sum_{ij} \langle \mathcal{A} | \mathcal{I}_j^\vee \rangle (C^{-1})_{ji} \langle \mathcal{I}_i |$$

of a vector $\langle \mathcal{A} |$ into a basis $\langle \mathcal{I}_i |$ using metric

$$C_{ij} := \langle \mathcal{I}_i | \mathcal{I}_j^\vee \rangle$$

- The scalar product $\langle \bullet | \bullet \rangle$ is called the **intersection number**
- Decomposition agrees with traditional IBP-based methods
- Also used to study differential equations!

[Cho '95
Matsumoto]

[Tkachov '81] [Chetyrkin
Tkachov '81] [Laporta '00]

[Duhr, Porkert '24
Semper, Stawinski] [Duhr, Porkert '24
Semper, Stawinski] [Franziska's talk next]

Baikov representation

Parametric representation of Feynman integrals:

[Baikov '96] [Frellesvig '17
Papadopoulos]

$$\mathcal{I}(x) = \int d^d k \frac{1}{\mathcal{D}_1^{a_1} \dots \mathcal{D}_n^{a_n}} \implies \mathcal{I}(x) = \int_{C_R} (\mathcal{B}(z; x))^\gamma \frac{d^n z}{z_1^{a_1} \dots z_n^{a_n}} = \int_{C_R} u \varphi$$

Features:

1. Holomorphic measure $d^n z := dz_1 \wedge \dots \wedge dz_n$
2. Baikov polynomial $\mathcal{B}(z; x) \in \mathbb{C}[z, x]$ with $x = \{p_i \cdot p_j, m^2, \dots\}$
3. $\gamma = (d - \#\text{loops} - \#\text{legs} - 1)/2 \in \mathbb{C} \implies \mathcal{B}^\gamma$ is multivalued!
4. Integration contour $C_R \subset \mathbb{C}^n$ such that $\mathcal{B}(\partial C_R) = 0$
5. Compute it with Hjalte's `BaikovPackage.m`

[repo @ 

Twisted cohomology

- Twist, connection, and covariant derivative

[Mastrolia
Mizera '18]

$$u := \prod_i (\mathcal{B}_i(z))^{\gamma_i}, \quad \omega := d \log(u), \quad \text{and} \quad \nabla \psi := d\psi + \omega \psi$$

- Intersection number integral

$$\langle \varphi | \varphi^\vee \rangle = \int_{\mathbb{C}} \text{reg}(\varphi) \wedge \varphi^\vee$$

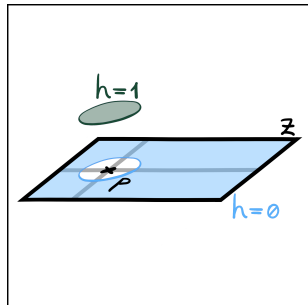
- Regularization in subtraction scheme ...

[Cho '95
Matsumoto]

$$\text{reg}(\varphi) = \varphi - \sum_p \nabla(h_p \psi_p), \quad \nabla \psi_p = \varphi \quad \text{near } z = p$$

- ... localizes on singularities of $\omega = \text{zeroes of } \mathcal{B}(z)$

$$\langle \varphi | \varphi^\vee \rangle = \sum_p \text{Res}_{z=p} (\psi_p \varphi^\vee)$$



Polynomial reduction and $p(z)$ -adic expansion

- Ansatz for $p(z)$ -adic expansion and the β -deformation

[Fontana '22] [Fontana
Peraro '23]

$$\psi = \sum_{n \in \mathbb{Z}} \sum_{i=0}^{\deg \mathcal{B} - 1} (\mathcal{B}(z))^n z^i \psi_{ni} \rightsquigarrow \psi(\beta, z) = \sum_{n \in \mathbb{Z}} \sum_{i=0}^{\deg \mathcal{B} - 1} \beta^n z^i \psi_{ni}$$

- Differential equation with polynomial reduction

$$(\mathcal{B}'(z) \partial_\beta + \partial_z + \omega) \psi - \varphi = 0 \quad \text{modulo} \quad \mathcal{B}(z) - \beta = 0$$

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- Sum over poles via the global residue $\text{Res}_{\langle \mathcal{B} \rangle}$

[Weinzierl '20]

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Polynomial reduction and $p(z)$ -adic expansion

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[Weinzierl '20]

$$\langle \varphi | \varphi^\vee \rangle = \text{Res}_{\langle \mathcal{B} \rangle} (\psi \varphi^\vee) = c_{-1, \deg \mathcal{B}-1}, \quad \psi \varphi^\vee = \sum_{ni} (\mathcal{B}(z))^n z^i c_{ni}$$

- Ansatz issues: many variables and expressions \Rightarrow replace everything with matrices!

Intersection numbers with tensors

Running example

- Consider a family of integrals with quadratic twist

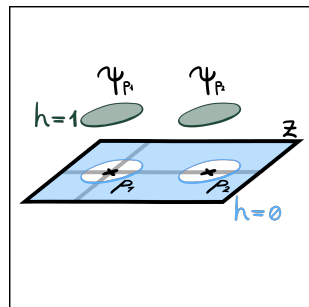
$$\mathcal{I} = \int u \varphi, \quad u = z^\rho \mathcal{B}(z)^\gamma, \quad \varphi = \frac{dz}{z^n \mathcal{B}(z)^m}, \quad \mathcal{B}(z) := b_0 + b_1 z + z^2, \quad \omega = \frac{\rho}{z} + \gamma \frac{\mathcal{B}'}{\mathcal{B}}$$

- And let's compute

$$\langle \varphi | \varphi^\vee \rangle = \langle 1/\mathcal{B} | 1/\mathcal{B}^2 \rangle$$

$$\langle \varphi | \varphi^\vee \rangle = \text{Res}_{z=p_1}(\psi_{p_1} \varphi^\vee) + \text{Res}_{z=p_2}(\psi_{p_2} \varphi^\vee)$$

$$(\partial_z + \omega)\psi_p = \varphi \quad \text{near roots } p_1 \text{ and } p_2 \text{ of } \mathcal{B}(z)$$



Running example

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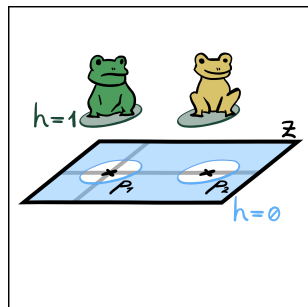
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$$\langle \varphi | \varphi^\vee \rangle = \langle 1/\mathcal{B} | 1/\mathcal{B}^2 \rangle$$

$$\langle \varphi | \varphi^\vee \rangle = \text{Res}_{z=p_1} \left(\text{green frog} \varphi^\vee \right) + \text{Res}_{z=p_2} \left(\text{yellow frog} \varphi^\vee \right)$$



$$\begin{pmatrix} \text{green frog} \\ \text{yellow frog} \end{pmatrix} (\partial_z + \omega) = \varphi \quad \text{near roots } p_1 \text{ and } p_2 \text{ of } \mathcal{B}(z)$$





Changes of variables and gauges

- Want to work simultaneously near the roots \implies new variable β

$$\mathcal{B}(z) - \beta = 0$$

-  and  correspond to $z^\pm(\beta) = -b_1/2 \pm \sqrt{b_1^2 - 4b_0 + 4\beta}/2$
- How to remove square roots from differential equation? Gauge transform!

$$\begin{bmatrix} \text{green frog} \\ \text{yellow frog} \end{bmatrix} = \begin{bmatrix} 1 & z^+(\beta) \\ 1 & z^-(\beta) \end{bmatrix} \cdot \begin{bmatrix} \text{green frog} \\ \text{yellow frog} \end{bmatrix}$$

-  and  correspond to irreducible monomials 1 and z

$$\psi(z, \beta) = \psi_0(\beta) + z \psi_1(\beta) \equiv \begin{bmatrix} 1 & z \end{bmatrix} \cdot \begin{bmatrix} \psi_0(\beta) \\ \psi_1(\beta) \end{bmatrix} = \begin{bmatrix} 1 & z \end{bmatrix} \cdot \begin{bmatrix} \text{green frog} \\ \text{yellow frog} \end{bmatrix}$$

Companion matrix dictionary

- Basic building blocks from $\mathcal{B}(z) - \beta = 0 \implies$ rule $z^2 \mapsto -b_0 + \beta - b_1 z$

$$\begin{bmatrix} z & z^2 \end{bmatrix} = \begin{bmatrix} 1 & z \end{bmatrix} \cdot \begin{bmatrix} 0 & -b_0 + \beta \\ 1 & -b_1 \end{bmatrix} =: \begin{bmatrix} 1 & z \end{bmatrix} \cdot Q_z$$

Companion matrix dictionary

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$$Q_z = \begin{bmatrix} 0 & -b_0 + \beta \\ 1 & -b_1 \end{bmatrix}, \quad Q_{\partial_z} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

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- Algebra works: division is matrix inversion

$$Q_{1/z} \equiv Q_z^{-1} = \frac{1}{-b_0 + \beta} \begin{bmatrix} b_1 & -b_0 + \beta \\ 1 & 0 \end{bmatrix}$$
$$Q_{\mathcal{B}'} \equiv b_1 \mathbb{1} + 2 Q_z = \begin{bmatrix} b_1 & 2(-b_0 + \beta) \\ 2 & -b_1 \end{bmatrix}, \quad \mathcal{B}' = b_1 + 2z$$

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- System of differential equations becomes rational!

$$\left(\partial_\beta - \frac{\gamma}{\beta} - \rho Q_{\mathcal{B}'}^{-1} \cdot Q_{1/z} + Q_{\mathcal{B}'}^{-1} \cdot Q_{\partial_z} \right) \cdot \begin{bmatrix} \psi_0(\beta) \\ \psi_1(\beta) \end{bmatrix} - Q_{\mathcal{B}'}^{-1} \cdot \begin{bmatrix} \beta^{-1} \\ 0 \end{bmatrix} = 0$$

Series expansion

- Only need $\beta \rightarrow 0$ behavior \implies Laurent expand

$$\psi(z, \beta) \Big|_{\beta \rightarrow 0} = \sum_{a=0}^1 \sum_{n \in \mathbb{Z}} z^a \psi_{an} \beta^n \equiv \begin{bmatrix} 1 & z \end{bmatrix} \cdot \begin{bmatrix} \cdots \psi_{0-1} & \psi_{00} & \psi_{01} & \cdots \\ \cdots \psi_{1-1} & \psi_{10} & \psi_{11} & \cdots \end{bmatrix} \cdot \begin{bmatrix} \vdots \\ \beta^{-1} \\ 1 \\ \beta \\ \vdots \end{bmatrix}$$

Series expansion

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- Corresponding blocks of differential equation

$$\left(\partial_\beta - \frac{\gamma}{\beta} + \frac{-\rho}{\Delta} \begin{bmatrix} \frac{2b_0 - b_1^2}{b_0} & b_1 \\ -\frac{b_1}{b_0} & 2 \end{bmatrix} + \frac{1}{\Delta} \begin{bmatrix} 0 & b_1 \\ 0 & 2 \end{bmatrix} + \dots \right) \cdot \left(0 + \begin{bmatrix} \psi_{00} \\ \psi_{10} \end{bmatrix} + \begin{bmatrix} \psi_{01} \\ \psi_{11} \end{bmatrix} \beta \right) - \left(\frac{1}{\beta \Delta} + \frac{-4}{\Delta^2} + \dots \right) \begin{bmatrix} b_1 \\ 2 \end{bmatrix} = 0$$

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- Convert expressions into tensors!

A quick reminder about tensor product

$$\begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{2} \end{bmatrix} \otimes \begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix} = \begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix}$$

The diagram illustrates the tensor product of a 2x2 matrix and a 2x2 matrix. The first matrix is $\begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{2} \end{bmatrix}$ and the second matrix is $\begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix}$. The result is a 2x2 matrix $\begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix}$.

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A quick reminder about tensor product

$$\begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{2} \end{bmatrix} \otimes \begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix} = \begin{bmatrix} \text{frog} & 0 & 0 & 0 \\ 0 & \text{fish} & 0 & 0 \\ 0 & 0 & \text{frog} & 0 \\ 0 & 0 & 0 & \text{fish} \end{bmatrix}$$

The diagram illustrates the tensor product of a 2x2 matrix and a 2x2 matrix. The first matrix is $\begin{bmatrix} 1 & 0 \\ 0 & \frac{3}{2} \end{bmatrix}$ and the second matrix is $\begin{bmatrix} \text{frog} & 0 \\ 0 & \text{fish} \end{bmatrix}$. The result is a 4x4 matrix where the elements are the tensor products of the elements of the two matrices, arranged in a block-diagonal pattern. The elements are: frog , 0 , 0 , 0 in the first row; 0 , fish , 0 , 0 in the second row; 0 , 0 , frog , 0 in the third row; and 0 , 0 , 0 , fish in the fourth row.

Tensor algebra for series expansion

- Dictionary for ∂_β and β^{-1} terms

$$L_{\partial_\beta} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{and} \quad L_{\beta^{-1}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

- Leading term of differential equation

$$\partial_\beta \otimes \mathbb{1} - \frac{\gamma}{\beta} \otimes \mathbb{1}$$

\rightsquigarrow

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \otimes \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \otimes \begin{bmatrix} -\gamma & 0 \\ 0 & -\gamma \end{bmatrix}$$

Full system of differential equations

$$\begin{bmatrix}
 * & * & -\gamma & 0 & 0 & 0 \\
 * & * & 0 & -\gamma & 0 & 0 \\
 * & * & \frac{-\rho}{\Delta} \frac{2b_0 - b_1^2}{b_0} & \frac{1-\rho}{\Delta} b_1 & -\gamma + 1 & 0 \\
 * & * & \frac{\rho}{\Delta} \frac{b_1}{b_0} & \frac{2(1-\rho)}{\Delta} & 0 & -\gamma + 1 \\
 * & * & * & * & * & * \\
 * & * & * & * & * & *
 \end{bmatrix} \cdot \begin{bmatrix} 0 \\ 0 \\ \psi_{00} \\ \psi_{10} \\ \psi_{01} \\ \psi_{11} \end{bmatrix} - \begin{bmatrix} \frac{b_1}{\Delta} \\ \frac{2}{\Delta} \\ \frac{-4b_1}{\Delta^2} \\ \frac{-8}{\Delta^2} \\ * \\ * \end{bmatrix} = 0,$$

Global residue as covector

$$\begin{aligned}\langle \varphi | \varphi^\vee \rangle &= - \text{Res}_{\langle \mathcal{B} \rangle}(\varphi \psi) \\ &= - \left[0 \quad 1 \mid 0 \quad 0 \mid 0 \quad 0 \right] \cdot \left[\begin{array}{cc|cc|cc} 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \cdot \left[\begin{array}{c} 0 \\ 0 \\ \hline \psi_{00} \\ \psi_{10} \\ \hline \psi_{01} \\ \psi_{11} \end{array} \right]\end{aligned}$$

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Putting all pieces together

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & -\gamma & 0 & 0 & 0 \\ 0 & 0 & -\gamma & 0 & 0 \\ 0 & \frac{-\rho}{\Delta} \frac{2b_0 - b_1^2}{b_0} & \frac{1-\rho}{\Delta} b_1 & -\gamma + 1 & 0 \\ 0 & \frac{\rho}{\Delta} \frac{b_1}{b_0} & \frac{2(1-\rho)}{\Delta} & 0 & -\gamma + 1 \end{bmatrix} \cdot \begin{bmatrix} \langle \varphi | \varphi^\vee \rangle \\ \psi_{00} \\ \psi_{10} \\ \psi_{01} \\ \psi_{11} \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{b_1}{\Delta} \\ \frac{2}{\Delta} \\ \frac{-4b_1}{\Delta^2} \\ \frac{-8}{\Delta^2} \end{bmatrix}$$

$$\langle \varphi | \varphi^\vee \rangle = -\psi_{11} = \frac{8}{\Delta^2(\gamma - 1)} + \frac{-4b_0 + \Delta\rho}{b_0\Delta^2(\gamma - 1)\gamma}$$

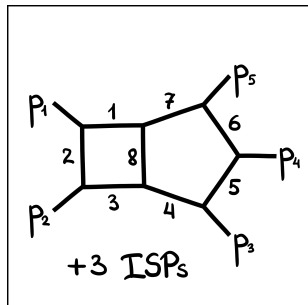
In agreement with the awesome analytic formula of [\[Crisanti Smith '24\]](#) [\[Giulio's talk later\]](#)

Application to 2-loop 5-point reduction

- Result of recent efforts [2401.01897] [2408.16668] [repo @ GitHub]
- Numerical decomposition into 62 masters (no symmetry)

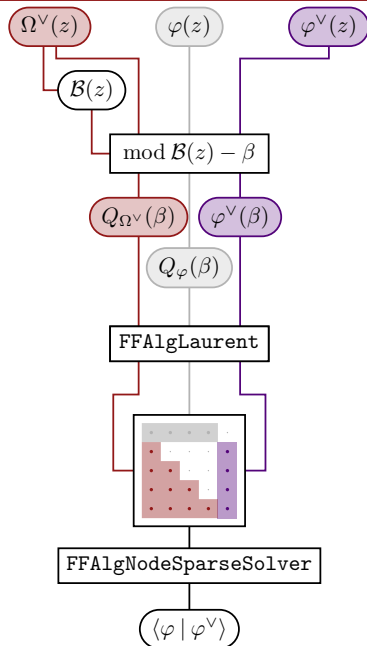
$$\mathcal{I} = \int u \frac{z_9^2}{z_1 z_2 z_3 z_4 z_5 z_6 z_7 z_8} dz \equiv \mathcal{I}_{11111111-200}$$

- 11-variate intersections using spanning cuts
- Automatic intermediate (candidate) bases generation `GetBasis.m` [GitHub]
- Extensive usage of tensors in FINITEFLOW [Peraro '19] [FiniteFlow]



rank	$\times 10^4$ sec
5	2.04
10	4.19
15	6.97
20	10.82

The FiniteFlow data graph



Conclusion

Conclusion

- **Twisted cohomology** describes multivariate integrals of multivalued functions, which are commonly encountered in theoretical physics.
- **Intersection number** is a scalar product on the space of twisted periods, allowing for the direct decomposition of Feynman integrals via the master decomposition formula.
- Today we explored **tensor structures** of intersection numbers that arise from the companion matrix representation.
- This new formulation enabled the full numerical reduction to master integrals of the massless 5-point 2-loop Feynman integral family.