# SPQR: A new Package for Polynomial Division and Elimination Theory via Finite Fields

#### Giulio Crisanti

MathemAmplitudes, Mainz, 23/09/25

Based on upcoming work with Vsevolod Chestnov





### Introduction and Motivation (1/2)

Talk Outline and Goal

Explore technology behind SPQR as well as various applications

# Introduction and Motivation (1/2)

Talk Outline and Goal

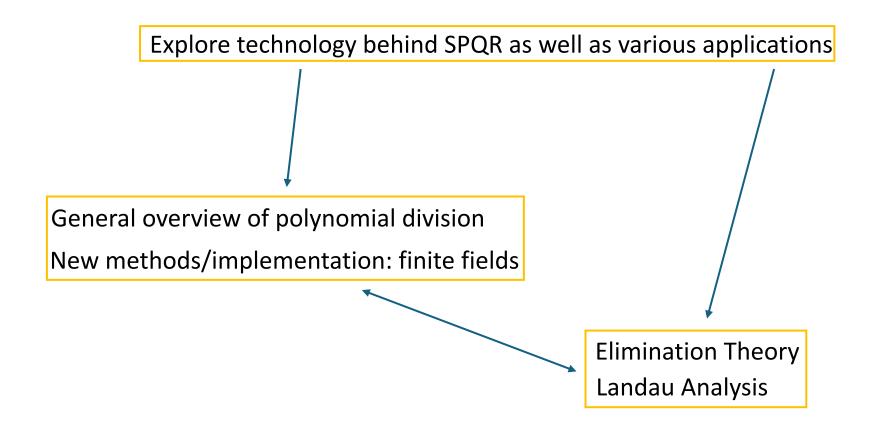
Explore technology behind SPQR as well as various applications

General overview of polynomial division

New methods/implementation: finite fields

# Introduction and Motivation (1/2)

#### Talk Outline and Goal



#### Univariate Polynomial Division

Polynomial division allows us to decompose functions as

$$f(x) = q(x)p(x) + r(x)$$

$$f(x) = r(x) \mod p(x)$$

#### Univariate Polynomial Division

Polynomial division allows us to decompose functions as

$$f(x) = q(x)p(x) + r(x)$$

$$deg(r) < deg(p)$$

$$f(x) = r(x) \mod p(x)$$

#### Univariate Polynomial Division

Polynomial division allows us to decompose functions as

$$f(x) = q(x)p(x) + r(x)$$

$$deg(r) < deg(p)$$

$$f(x) = r(x) \mod p(x)$$

Can always be done — best seen by example!

$$f(x) = x^3 + ax^2 - (4+2a)x + 1$$
  $p(x) = x^2 - 2x - 1 \longrightarrow x^2 = p(x) + 2x + 1$ 

#### Univariate Polynomial Division

Polynomial division allows us to decompose functions as

$$f(x) = q(x)p(x) + r(x)$$

$$deg(r) < deg(p)$$

$$f(x) = r(x) \mod p(x)$$

Can always be done — best seen by example!

$$f(x) = x^{3} + ax^{2} - (4+2a)x + 1 \qquad p(x) = x^{2} - 2x - 1 \longrightarrow x^{2} = p(x) + 2x + 1$$

$$f(x) = x (p(x) + 2x + 1) + a (p(x) + 2x + 1) - (4+2a)x + 1$$

$$= p(x)(x+a) + 2x^{2} + a - 3x + 1$$

$$= p(x)(x+a) + 2(p(x) + 2x + 1) + a - 3x + 1$$

$$= p(x)(x+a+2) + x + a + 3$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$
$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$

$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

$$\vdots$$

$$f(x) - x^{3} - ax^{2} + (5 + 2a)x + 1 = 0 \mod p(x)$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$

$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

$$\vdots$$

$$f(x) - x^{3} - ax^{2} + (5 + 2a)x + 1 = 0 \mod p(x)$$

Cast in (Macaulay) matrix form:

$$\begin{bmatrix} -1 & 1 & a & -(4+2a) & 1 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ 1 \end{bmatrix} = \mathbf{0}$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$

$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

$$\vdots$$

$$f(x) - x^{3} - ax^{2} + (5 + 2a)x + 1 = 0 \mod p(x)$$

Cast in (Macaulay) matrix form:

$$\begin{bmatrix} -1 & 1 & a & -(4+2a) & 1 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0} \xrightarrow{\mathsf{RowRed}} \begin{bmatrix} 1 & 0 & 0 & -1 & -3 - a \\ 0 & 1 & 0 & -5 & -2 \\ 0 & 0 & 1 & -2 & -1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0}$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$

$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

$$\vdots$$

$$f(x) - x^3 - ax^2 + (5+2a)x + 1 = 0 \mod p(x)$$

 $f(x) - 3 - a - x = 0 \mod p(x)$ 

Cast in (Macaulay) matrix form:

ast in (Macaulay) matrix form: 
$$\begin{bmatrix} -1 & 1 & a & -(4+2a) & 1 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0} \xrightarrow{\text{RowRed}} \begin{bmatrix} 1 & 0 & 0 & -1 & -3-a \\ 0 & 1 & 0 & -5 & -2 \\ 0 & 0 & 1 & -2 & -1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0}$$

#### Polynomial division as row reduction

If all we care about is the remainder, we can reformulate polynomial division as a row reduction problem

$$p(x) = 0 \mod p(x) \longrightarrow x^n p(x) = 0 \mod p(x)$$

Can generate a linear system of equations this way

$$x^{2} - 2x - 1 = 0 \mod p(x)$$

$$x^{3} - 2x^{2} - x = 0 \mod p(x)$$

$$\vdots$$

$$f(x) - x^3 - ax^2 + (5+2a)x + 1 = 0 \mod p(x)$$

 $f(x) - 3 - a - x = 0 \mod p(x)$ 

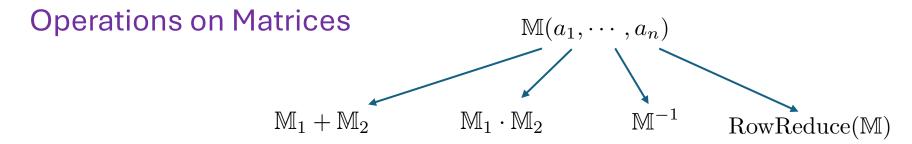
Cast in (Macaulay) matrix form:

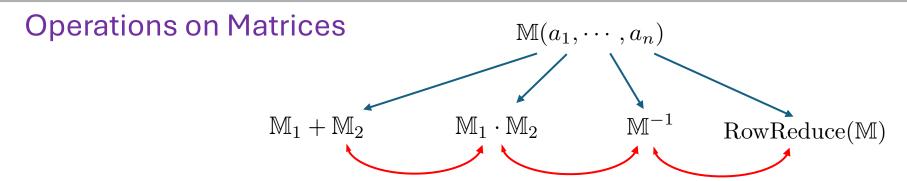
est in (Macaulay) matrix form: 
$$\begin{bmatrix} -1 & 1 & a & -(4+2a) & 1 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0} \xrightarrow{\text{RowRed}} \begin{bmatrix} 1 & 0 & 0 & -1 & -3-a \\ 0 & 1 & 0 & -5 & -2 \\ 0 & 0 & 1 & -2 & -1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \\ 1 \end{bmatrix} = \mathbf{0}$$

Useful because there exist very quick ways to do row reduction: Sample over finite fields and reconstruct output

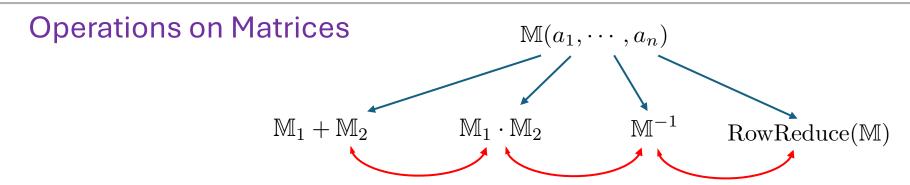
Operations on Matrices

 $\mathbb{M}(a_1,\cdots,a_n)$ 





Algebraic post processing simplification — can become very intensive!

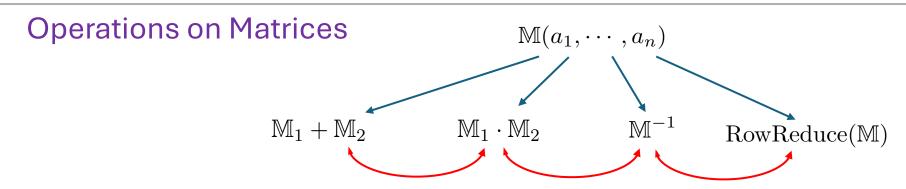


Algebraic post processing simplification — can become very intensive!

#### Finite Fields Approach

Substitute numerical values for parameters

Perform all operations Reconstruct functional output from numerical sampling



Algebraic post processing simplification — can become very intensive!

#### Finite Fields Approach

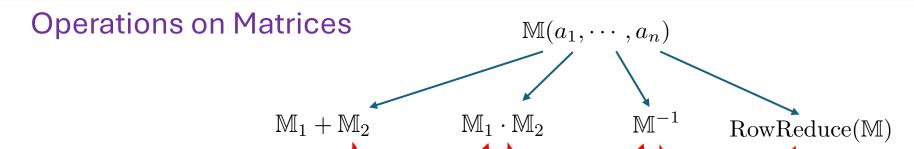
Substitute numerical values for parameters

Perform all operations numerically mod primes

Reconstruct functional output from numerical sampling

Complicated cancellations will happen numerically — final reconstructed output already "simplified"

All operations over finite fields handled by the C++/Mathematica package FiniteFlow [FiniteFlow, Peraro, 2019]



Algebraic post processing simplification — can become very intensive!

#### Finite Fields Approach

Substitute numerical Perform all operations rumerically mod primes fr

Reconstruct functional output from numerical sampling

Complicated cancellations will happen numerically — final reconstructed output already "simplified"

All operations over finite fields handled by the C++/Mathematica package FiniteFlow

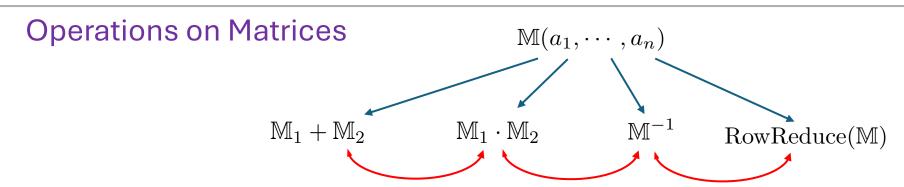
[FiniteFlow, Peraro, 2019]

#### What is reconstructed?

$$f(x) = x^{3} + ax^{2} - (5+2a)x + 1$$

$$p(x) = x^{2} - 2x - 1$$

$$\begin{bmatrix}
-1 & 1 & a & -(4+2a) & 1 \\
0 & -1 & 2 & 1 & 0 \\
0 & 0 & -1 & 2 & 1
\end{bmatrix} \begin{bmatrix}
f(x) \\
x^{3} \\
x^{2} \\
x \\
1
\end{bmatrix} = \mathbf{0}$$



Algebraic post processing simplification — can become very intensive!

#### Finite Fields Approach

Substitute numerical values for parameters

Perform all operations numerically mod primes Reconstruct functional output from numerical sampling

Complicated cancellations will happen numerically — final reconstructed output already "simplified"

All operations over finite fields handled by the C++/Mathematica package *FiniteFlow* 

[FiniteFlow, Peraro, 2019]

#### What is reconstructed?

$$f(x) = x^3 + ax^2 - (5+2a)x + 1$$
$$p(x) = x^2 - 2x - 1$$

What is reconstructed? 
$$f(x) = x^3 + ax^2 - (5+2a)x + 1$$
 
$$p(x) = x^2 - 2x - 1$$
 
$$\begin{bmatrix} -1 & 1 & a & -(4+2a) & 1 \\ 0 & -1 & 2 & 1 & 0 \\ 0 & 0 & -1 & 2 & 1 \end{bmatrix} \begin{bmatrix} f(x) \\ x^3 \\ x^2 \\ x \end{bmatrix} = \mathbf{0}$$
 R =  $\mathbb{Q}(a)[x]$  variables

Only need to reconstruct parameters!

#### **Monomial Orderings**

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

#### Monomial Orderings

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take

#### Monomial Orderings

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take

Lexicographic: 
$$\cdots > x^2 > xy^{\infty} > xy > x > y^{\infty} > \cdots > y > 1$$

#### Monomial Orderings

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take

Lexicographic: 
$$\cdots > x^2 > xy^\infty > xy > x > y^\infty > \cdots > y > 1$$

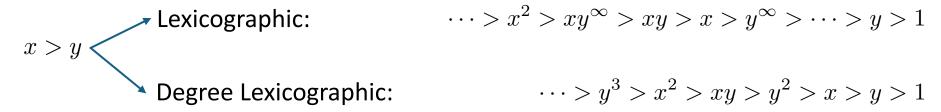
$$x > y$$
Degree Lexicographic:  $\cdots > y^3 > x^2 > xy > y^2 > x > y > 1$ 

#### Monomial Orderings

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take



#### Is the division unique?

Unfortunately, this is not enough to uniquely determine a multivariate polynomial division

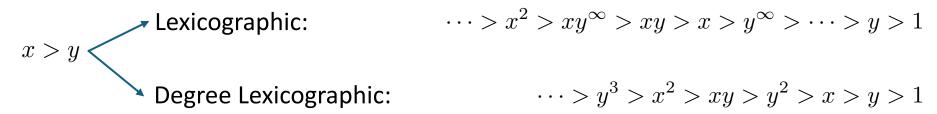
Consider  $I = \langle xy - x, xy - y - 1 \rangle$ . What is  $xy = ? \mod I$ 

#### **Monomial Orderings**

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take



#### Is the division unique?

Unfortunately, this is not enough to uniquely determine a multivariate polynomial division

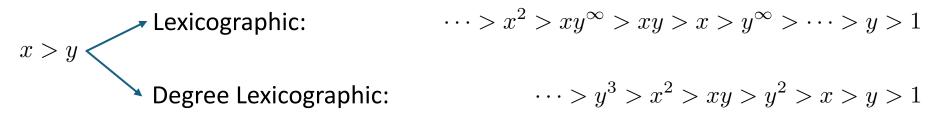
Consider 
$$I=\langle xy-x, xy-y-1 \rangle$$
. What is  $x\,y=\pmod{I}$   $xy=x \mod{I}$ 

#### **Monomial Orderings**

For one variable, sorting the monomials from "worst" to "best" is unambiguous

$$x^n > x^{n-1} > \dots > x^3 > x^2 > x > 1$$

For more than one variable there are multiple choices one can take



#### Is the division unique?

Unfortunately, this is not enough to uniquely determine a multivariate polynomial division

Consider 
$$I = \langle xy - x, xy - y - 1 \rangle$$
. What is  $xy = ? \mod I$  
$$xy = x \mod I \qquad xy = y + 1 \mod I$$

Problem normally fixed by introducing Groebner Bases

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow G = \langle y^2 - 1, x - y - 1 \rangle$$
 (Lexicographic)

Any possible combination of the elements of G will result in the same polynomial remainder

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow G = \langle y^2 - 1, x - y - 1 \rangle$$
 (Lexicographic)

Any possible combination of the elements of G will result in the same polynomial remainder

$$xy \stackrel{\text{2}}{=} (y+1)y = y + y^2 \stackrel{\text{1}}{=} y + 1 \mod G$$

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow G = \langle y^2 - 1, x - y - 1 \rangle$$
 (Lexicographic)

Any possible combination of the elements of G will result in the same polynomial remainder

$$xy \stackrel{?}{=} (y+1)y = y + y^2 \stackrel{1}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{1}{=} x \stackrel{?}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{?}{=} (y+1)y^2 \stackrel{1}{=} y + 1 \mod G$$

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow G = \langle y^2 - 1, x - y - 1 \rangle$$
 (Lexicographic)

Any possible combination of the elements of G will result in the same polynomial remainder

$$xy \stackrel{?}{=} (y+1)y = y + y^2 \stackrel{1}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{1}{=} x \stackrel{?}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{?}{=} (y+1)y^2 \stackrel{1}{=} y + 1 \mod G$$

Groebner bases can be very difficult to calculate and are often computational bottlenecks!

#### **Groebner Bases**

A Groebner basis G is a set of generators for the ideal I that has many nice properties

For this talk: Roots of G=0 are the same as I=0, and polynomial division ambiguities fixed

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow G = \langle y^2 - 1, x - y - 1 \rangle$$
 (Lexicographic)

Any possible combination of the elements of G will result in the same polynomial remainder

$$xy \stackrel{?}{=} (y+1)y = y + y^2 \stackrel{1}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{1}{=} x \stackrel{?}{=} y + 1 \mod G$$
 
$$xy^2 \stackrel{?}{=} (y+1)y^2 \stackrel{1}{=} y + 1 \mod G$$

Groebner bases can be very difficult to calculate and are often computational bottlenecks!

#### **Avoiding Groebner Bases**

Claim: We can explicitly avoid computing a Groebner basis, and still obtain the correct result from polynomial division, using row reduction [Faugére, 1999] [Buchberger, 1985]

Allows us to compute polynomial divisions without needing to reconstruct the "intermediate" Groebner Basis

#### **Row Reduction Again**

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

#### **Row Reduction Again**

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

Seed a linear system by multiplying I by  $x^n y^m$ 

#### **Row Reduction Again**

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

Seed a linear system by multiplying I by  $x^n y^m$ 

#### **Row Reduction Again**

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

Seed a linear system by multiplying I by  $x^n y^m$ 

Read off from top row:  $f(x,y) = y + 1 \mod I$  No explicit Groebner Basis required!

Irreducible monomials

#### **Row Reduction Again**

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

Seed a linear system by multiplying I by  $x^n y^m$ 

Read off from top row:  $f(x,y) = y + 1 \mod I$  No explicit Groebner Basis required!

Irreducible monomials

Important to note: this approach does not escape the complexity of computing Groebner Bases

#### Row Reduction Again

We consider again  $I = \langle xy - x, xy - y - 1 \rangle$  and let  $f(x,y) = xy^2$ 

Seed a linear system by multiplying I by  $x^n y^m$ 

Read off from top row:  $f(x,y) = y + 1 \mod I$  No explicit Groebner Basis required!

Irreducible monomials

Important to note: this approach does not escape the complexity of computing Groebner Bases

For example: the size of the system one needs to generate is unclear a priori and can be very large

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices

[Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices

Companion matrices are built from taking polynomial divisions of a given function.

[Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices

[Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

Companion matrices are built from taking polynomial divisions of a given function.

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices

[Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Companion matrices are built from taking polynomial divisions of a given function.

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

$$M_{f(x,y)}:$$

$$m_1 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots$$

$$m_2 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots$$

$$\vdots$$

$$mod I(x,y)$$

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices [Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Companion matrices are built from taking polynomial divisions of a given function.

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

$$M_{f(x,y)}: \begin{array}{c} m_1 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots \\ m_2 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots \\ \vdots & \vdots & \ddots \end{array} \\ m_3 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots \\ m_4 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots \\ \vdots & \vdots & \ddots \end{array}$$

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices [Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Companion matrices are built from taking polynomial divisions of a given function.

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

$$M_{f(x,y)}: \begin{array}{c} m_1 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots \\ m_2 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots \\ \vdots & \vdots & \ddots \end{array} \\ \begin{array}{c} mod \ I(x,y) & \longrightarrow \\ M_{f(x,y)} = \begin{bmatrix} c_{11} & c_{12} & \cdots \\ c_{21} & c_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

Key properties of companion matrices:

$$M_{f_1+f_2} = M_{f_1} + M_{f_2}$$
  $M_{f_1 f_2} = M_{f_1} M_{f_2} = M_{f_2} M_{f_1}$   $M_{f_{inv}} = M_f^{-1}$ 

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices [Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Companion matrices are built from taking polynomial divisions of a given function.

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

$$M_{f(x,y)}: \begin{array}{c} m_1 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots \\ m_2 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots \\ \vdots & \vdots & \ddots \end{array} \\ \begin{array}{c} mod \ I(x,y) & \longrightarrow \\ M_{f(x,y)} = \begin{bmatrix} c_{11} & c_{12} & \cdots \\ c_{21} & c_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

Key properties of companion matrices:

$$M_{f_1+f_2} = M_{f_1} + M_{f_2}$$
  $M_{f_1 f_2} = M_{f_1} M_{f_2} = M_{f_2} M_{f_1}$   $M_{f_{inv}} = M_f^{-1}$ 

Remainder can be recovered as:

$$f(x,y) = (0, \cdots, 0, 1) \cdot M_{f(x,y)} \cdot m^T \mod I$$

#### **Avoiding Large Systems**

If we want to reduce polynomials with large monomial powers, the system to row reduce can become very large very quickly. Solution to this problem: Companion Matrices [Buchberger, 1985]

[Sturmfels, 2002]

[Cox, Little O'Shea, 2015]

[Telen, 2020]

[Brunello, Chestnov, Mastrolia, 2024]

Companion matrices are built from taking polynomial divisions of a given function.

Let  $m = \{ \cdots y, 1 \}$  be the irreducible monomials of a polynomial system.

$$M_{f(x,y)}: \begin{array}{c} m_1 \cdot f(x,y) = c_{11}m_1 + c_{12}m_2 + \cdots \\ m_2 \cdot f(x,y) = c_{21}m_1 + c_{22}m_2 + \cdots \\ \vdots & \vdots & \ddots \end{array} \\ \begin{array}{c} mod \ I(x,y) & \longrightarrow \\ M_{f(x,y)} = \begin{bmatrix} c_{11} & c_{12} & \cdots \\ c_{21} & c_{22} & \cdots \\ \vdots & \vdots & \ddots \end{bmatrix}$$

Key properties of companion matrices:

$$M_{f_1+f_2} = M_{f_1} + M_{f_2}$$
  $M_{f_1 f_2} = M_{f_1} M_{f_2} = M_{f_2} M_{f_1}$   $M_{f_{inv}} = M_f^{-1}$ 

Remainder can be recovered as:

$$f(x,y) = (0, \cdots, 0, 1) \cdot M_{f(x,y)} \cdot m^T \mod I$$

Strategy: Build  $M_x$  and  $M_y$  and you can reduce anything with just matrix multiplication!

Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

#### Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

$$M_x: \quad \begin{array}{ccc} y \cdot x = y + 1 & \operatorname{mod} I \\ 1 \cdot x = y + 1 & \operatorname{mod} I \end{array} \longrightarrow M_x = \left[ \begin{array}{ccc} 1 & 1 \\ 1 & 1 \end{array} \right]$$

#### Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

#### Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

Can now consider any function and build it with companion matrices

$$f(x,y) = xy^2 \longrightarrow M_{f(x,y)} = M_x \cdot M_y^2 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

#### Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

Can now consider any function and build it with companion matrices

$$f(x,y) = xy^2 \longrightarrow M_{f(x,y)} = M_x \cdot M_y^2 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \longrightarrow r(x,y) = (0,1) \cdot \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} y \\ 1 \end{bmatrix} = y+1$$

#### Examples

$$I = \langle xy - x, xy - y \rangle \longrightarrow m = \{y, 1\}$$

Can now consider any function and build it with companion matrices

$$f(x,y) = xy^2 \longrightarrow M_{f(x,y)} = M_x \cdot M_y^2 = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \longrightarrow r(x,y) = (0,1) \cdot \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} y \\ 1 \end{bmatrix} = y+1$$

Can immediately write down the answer for much more complicated expressions!

$$g(x,y) = a + \frac{x}{y^{100} - 3x + 2} \longrightarrow M_{g(x,y)} = 1 + M_x \left( M_y^{100} - 3M_x + 2 1 \right)^{-1} = \begin{bmatrix} \frac{1}{3}(3a - 1) & -\frac{1}{3} \\ -\frac{1}{3} & \frac{1}{3}(3a - 1) \end{bmatrix}$$

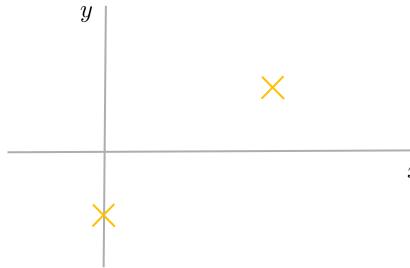
$$g(x,y) = \frac{1}{3}(3a-1) - \frac{y}{3} \mod I$$

#### Variable Elimination

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$

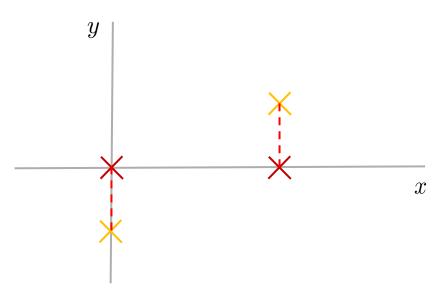
#### Variable Elimination

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$



#### Variable Elimination

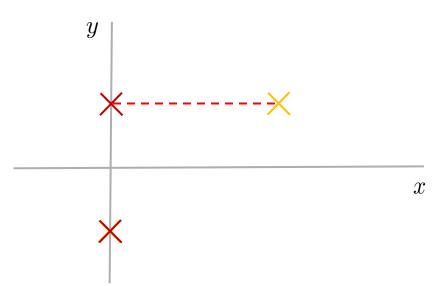
$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$



$$\operatorname{Elim}_{y}(\mathcal{I}) = \langle x(x-2) \rangle$$

#### Variable Elimination

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$



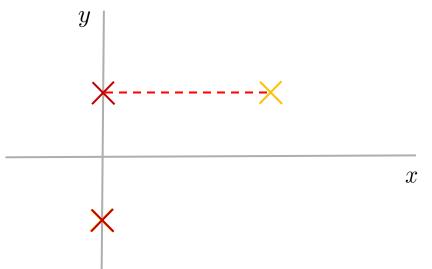
$$\operatorname{Elim}_y(\mathcal{I}) = \langle x(x-2) \rangle$$

$$\operatorname{Elim}_x(\mathcal{I}) = \langle y^2 - 1 \rangle$$

#### Variable Elimination

Often one is interested in projecting/eliminating an equation system down onto one variable "slices"

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$



$$\operatorname{Elim}_y(\mathcal{I}) = \langle x(x-2) \rangle$$

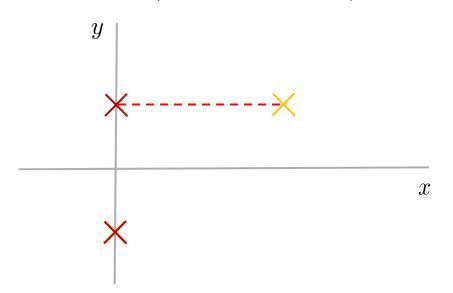
$$\operatorname{Elim}_x(\mathcal{I}) = \langle y^2 - 1 \rangle$$

The eigenvalues of companion matrices encode the roots of the polynomial system. Can be conveniently accessed by computing characteristic polynomials

#### Variable Elimination

Often one is interested in projecting/eliminating an equation system down onto one variable "slices"

$$I = \langle xy - x, xy - y - 1 \rangle \longrightarrow \{x^* = 0, y^* = -1\} \cup \{x^* = 2, y^* = 1\}$$



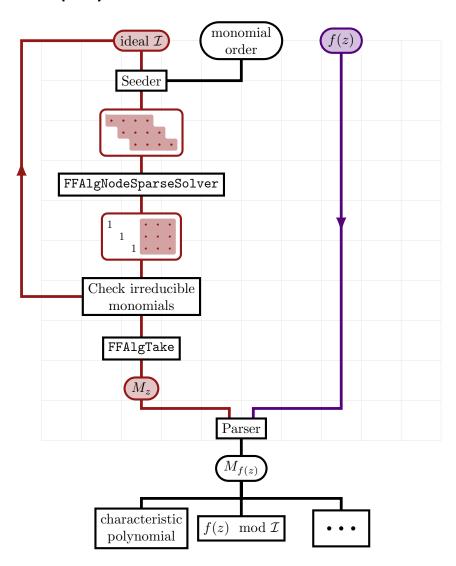
$$\operatorname{Elim}_y(\mathcal{I}) = \langle x(x-2) \rangle$$

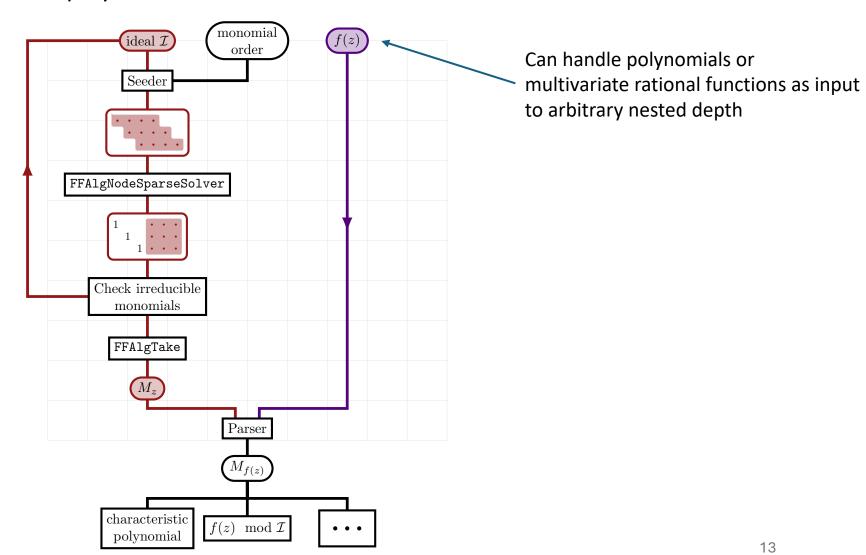
$$\operatorname{Elim}_x(\mathcal{I}) = \langle y^2 - 1 \rangle$$

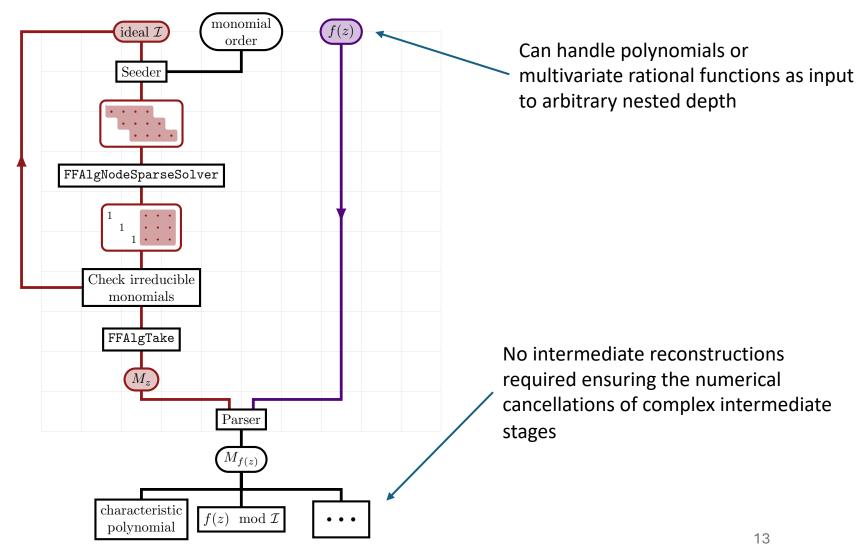
The eigenvalues of companion matrices encode the roots of the polynomial system. Can be conveniently accessed by computing characteristic polynomials

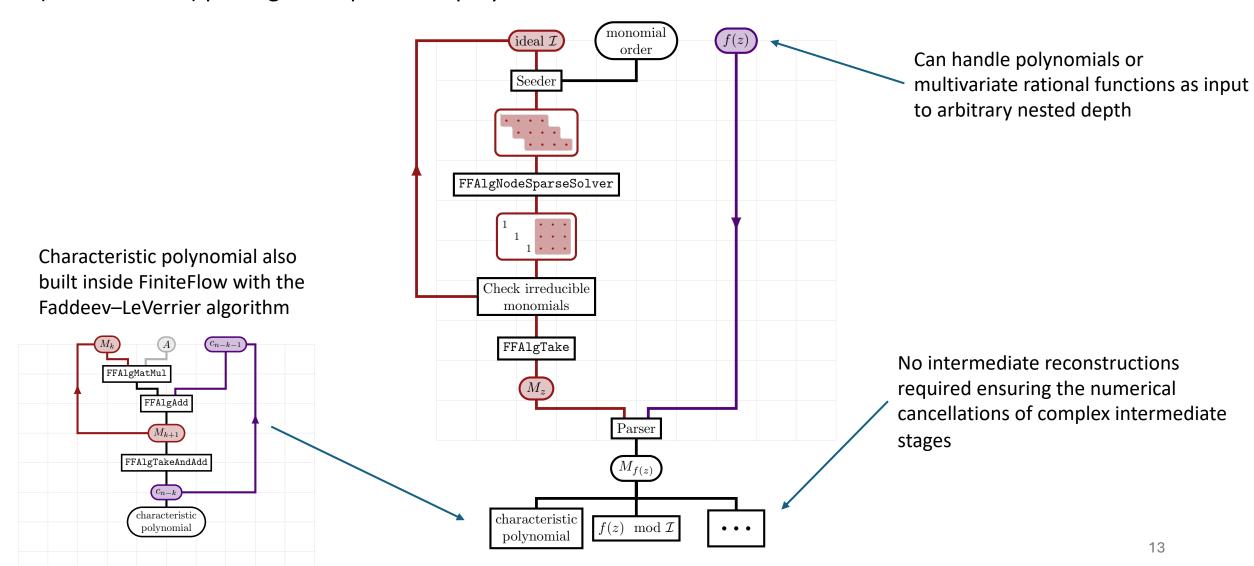
$$\operatorname{Elim}_{x}(\mathcal{I}) = \det(M_{y} - y\mathbb{1}) = \det\begin{bmatrix} -y & 1\\ 1 & -y \end{bmatrix} = y^{2} - 1$$

$$\operatorname{Elim}_{y}(\mathcal{I}) = \det(M_{x} - x\mathbb{1}) = \det\begin{bmatrix} 1 - x & 1\\ 1 & 1 - x \end{bmatrix} = x(x - 2)$$









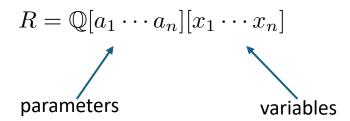
## Advantages and Disadvantages (1/3)

Complexity of polynomial ideals

$$R=\mathbb{Q}[a_1\cdots a_n][x_1\cdots x_n]$$
 parameters variables

### Advantages and Disadvantages (1/3)

#### Complexity of polynomial ideals



"Variable complexity": How many equations are needed for finding a Groebner Basis

Groebner Basis algorithms have fine tuned procedures for keeping this down to a minimum Our approach (currently) relies on a much coarser and overcomplete system of equations

## Advantages and Disadvantages (1/3)

#### Complexity of polynomial ideals

$$R = \mathbb{Q}[a_1 \cdots a_n][x_1 \cdots x_n]$$
 parameters

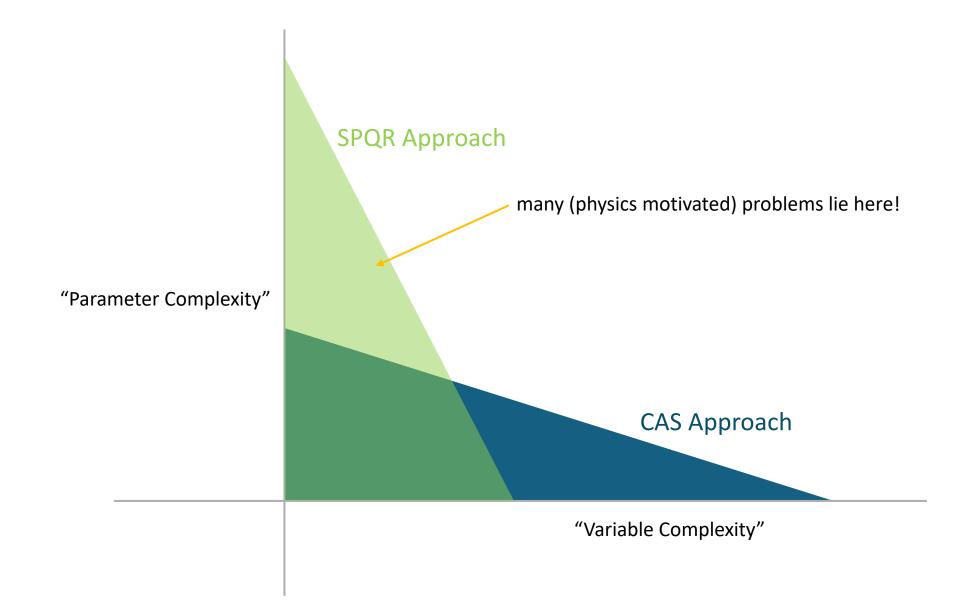
"Variable complexity": How many equations are needed for finding a Groebner Basis

Groebner Basis algorithms have fine tuned procedures for keeping this down to a minimum Our approach (currently) relies on a much coarser and overcomplete system of equations

"Parameter complexity": How complicated are the coefficients of the Groebner Basis polynomials

Groebner Basis algorithms suffer from complicated symbolic processing at intermediate stages Reconstruction over finite fields completely avoids this problem as cancellations happen numerically! Can speed up computations by orders of magnitude

## Advantages and Disadvantages (2/3)



## Advantages and Disadvantages (3/3)

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate  $\{x,y,z\}$   $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

# Advantages and Disadvantages (3/3)

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate 
$$\{x,y,z\}$$
  $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

| Resultant              | Singular | Macaulay 2 | Mathematica (+ tricks) | SPQR |
|------------------------|----------|------------|------------------------|------|
| $\mathcal{R}(3,5,7,d)$ |          |            |                        |      |
| $\mathcal{R}(3,5,c,d)$ |          |            |                        |      |
| $\mathcal{R}(3,b,c,d)$ |          |            |                        |      |
| $\mathcal{R}(a,b,c,d)$ |          |            |                        |      |
|                        |          |            |                        |      |

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate 
$$\{x,y,z\}$$
  $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

| Resultant              | Singular        | Macaulay 2      | Mathematica (+ tricks) | SPQR            |
|------------------------|-----------------|-----------------|------------------------|-----------------|
| $\mathcal{R}(3,5,7,d)$ | $\approx 0.01s$ | $\approx 0.06s$ | $\approx 0.03s$        | $\approx 0.18s$ |
| $\mathcal{R}(3,5,c,d)$ |                 |                 |                        |                 |
| $\mathcal{R}(3,b,c,d)$ |                 |                 |                        |                 |
| $\mathcal{R}(a,b,c,d)$ |                 |                 |                        |                 |
|                        |                 |                 |                        |                 |

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate 
$$\{x,y,z\}$$
  $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

| Resultant              | Singular         | Macaulay 2       | Mathematica (+ tricks) | SPQR            |
|------------------------|------------------|------------------|------------------------|-----------------|
| $\mathcal{R}(3,5,7,d)$ | $\approx 0.01s$  | $\approx 0.06s$  | $\approx 0.03s$        | $\approx 0.18s$ |
| $\mathcal{R}(3,5,c,d)$ | $\approx 53.29s$ | $\approx 12.40s$ | $\approx 5.03s$        | $\approx 0.20s$ |
| $\mathcal{R}(3,b,c,d)$ |                  |                  |                        |                 |
| $\mathcal{R}(a,b,c,d)$ |                  |                  |                        |                 |
|                        |                  |                  |                        |                 |

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate 
$$\{x,y,z\}$$
  $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

| Resultant              | Singular         | Macaulay 2       | Mathematica (+ tricks) | SPQR            |
|------------------------|------------------|------------------|------------------------|-----------------|
| $\mathcal{R}(3,5,7,d)$ | $\approx 0.01s$  | $\approx 0.06s$  | $\approx 0.03s$        | $\approx 0.18s$ |
| $\mathcal{R}(3,5,c,d)$ | $\approx 53.29s$ | $\approx 12.40s$ | $\approx 5.03s$        | $\approx 0.20s$ |
| $\mathcal{R}(3,b,c,d)$ | > 7d             | > 7d             | $\approx 4h  39m$      | $\approx 0.46s$ |
| $\mathcal{R}(a,b,c,d)$ |                  |                  |                        |                 |
|                        |                  |                  |                        |                 |

#### Resultant Benchmarking (Preliminary)

$$R = \mathbb{Q}(a, b, c, d)[x, y, z]$$

$$I = \langle a + x^2y^2 + y^3 + z - 1, ax + cxy^2 + cy + z^2 - 2, a + bxy^2 + b + x^2y^2, -c + dxz + xyz + 1 \rangle$$

Task: Eliminate 
$$\{x,y,z\}$$
  $\longrightarrow$   $\mathcal{R}(a,b,c,d)$ 

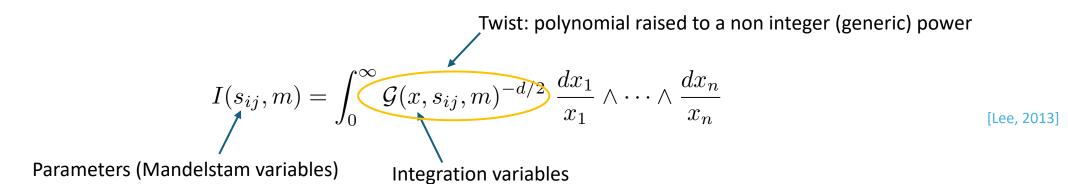
| Resultant              | Singular         | Macaulay 2       | Mathematica (+ tricks) | SPQR            |
|------------------------|------------------|------------------|------------------------|-----------------|
| $\mathcal{R}(3,5,7,d)$ | $\approx 0.01s$  | $\approx 0.06s$  | $\approx 0.03s$        | $\approx 0.18s$ |
| $\mathcal{R}(3,5,c,d)$ | $\approx 53.29s$ | $\approx 12.40s$ | $\approx 5.03s$        | $\approx 0.20s$ |
| $\mathcal{R}(3,b,c,d)$ | > 7d             | > 7d             | $\approx 4h  39m$      | $\approx 0.46s$ |
| $\mathcal{R}(a,b,c,d)$ | ?                | ?                | >7d                    | $\approx 1.89s$ |
|                        |                  |                  |                        |                 |

9 MB degree 34 polynomial

The Finite Fields approach is solving a less refined set of equations, but isn't slowed down by intermediate cancellations

#### Landau Singularities of Feynman (Euler) Integrals

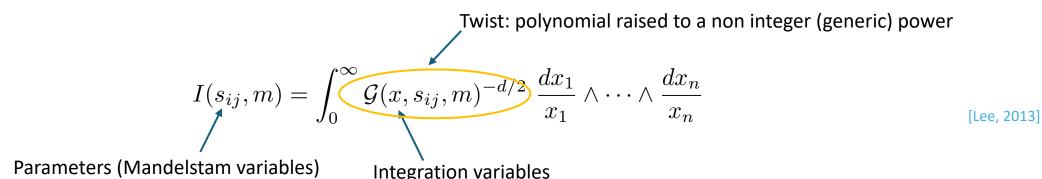
Feynman integrals are Euler/Twisted Period integrals



#### Landau Singularities of Feynman (Euler) Integrals

Landau Analysis: where are the branch points of  $I(s_{ij}, m)$  located?

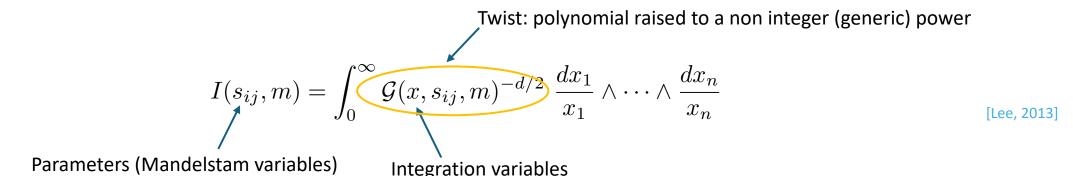
Feynman integrals are Euler/Twisted Period integrals



[Landau, 1960] [Cutkosky, 1960] [Abreu, Berghoff, Bourjaily, Britto, Correia, Duhr, Fevola, Gardi, Giroux, Hannesdottir, Helmer, Lippestreu, Matsubara-Heo, McLeod, Mizera, Panzer, Papathanasiou, Polackova, Schwartz, Tellander, Telen, Vergu, Wiesmann 2017-2025]

#### Landau Singularities of Feynman (Euler) Integrals

Feynman integrals are Euler/Twisted Period integrals



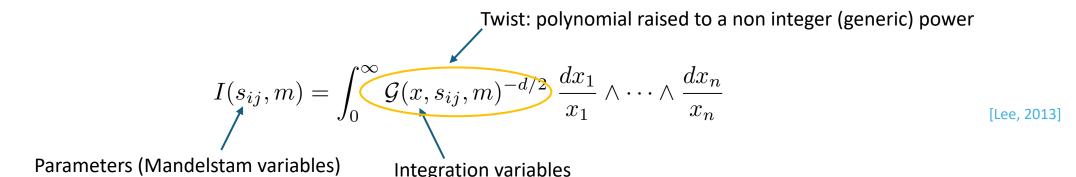
Landau Analysis: where are the branch points of  $I(s_{ij}, m)$  located?

[Landau, 1960] [Cutkosky, 1960] [Abreu, Berghoff, Bourjaily, Britto, Correia, Duhr, Fevola, Gardi, Giroux, Hannesdottir, Helmer, Lippestreu, Matsubara-Heo, McLeod, Mizera, Panzer, Papathanasiou, Polackova, Schwartz, Tellander, Telen, Vergu, Wiesmann 2017-2025]

Euler/Twisted Period representations allow us to associate an Euler characteristic  $\chi$  to a given Feynman integral

#### Landau Singularities of Feynman (Euler) Integrals

Feynman integrals are Euler/Twisted Period integrals



Landau Analysis: where are the branch points of  $I(s_{ij}, m)$  located?

[Landau, 1960] [Cutkosky, 1960] [Abreu, Berghoff, Bourjaily, Britto, Correia, Duhr, Fevola, Gardi, Giroux, Hannesdottir, Helmer, Lippestreu, Matsubara-Heo, McLeod, Mizera, Panzer, Papathanasiou, Polackova, Schwartz, Tellander, Telen, Vergu, Wiesmann 2017-2025]

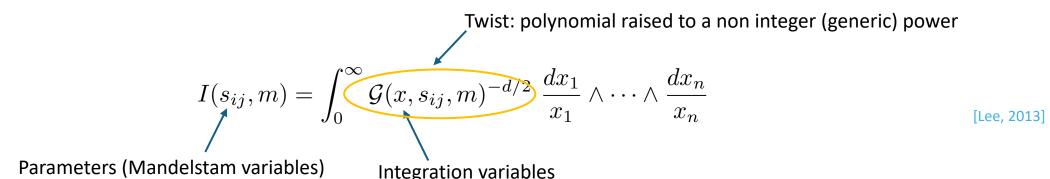
Euler/Twisted Period representations allow us to associate an Euler characteristic  $\chi$  to a given Feynman integral

The Landau Variety can be defined as the values of  $\{s_{ij},m\}$  for which the Euler characteristic drops in value

[Chestnov, Matsubara-Heo, Munch, Takayama, 2023] [Mizera, Fevola, Telen, 2023/24]

#### Landau Singularities of Feynman (Euler) Integrals

Feynman integrals are Euler/Twisted Period integrals



Landau Analysis: where are the branch points of  $I(s_{ij}, m)$  located?

[Landau, 1960] [Cutkosky, 1960] [Abreu, Berghoff, Bourjaily, Britto, Correia, Duhr, Fevola, Gardi, Giroux, Hannesdottir, Helmer, Lippestreu, Matsubara-Heo, McLeod, Mizera, Panzer, Papathanasiou, Polackova, Schwartz, Tellander, Telen, Vergu, Wiesmann 2017-2025]

Euler/Twisted Period representations allow us to associate an Euler characteristic  $\chi$  to a given Feynman integral

The Landau Variety can be defined as the values of  $\{s_{ij}, m\}$  for which the Euler characteristic drops in value

[Chestnov, Matsubara-Heo, Munch, Takayama, 2023] [Mizera, Fevola, Telen, 2023/24]

 $\chi$  can be computed by solving systems of polynomial equations

#### Computing Euler Characteristics for Landau Analysis

Computing 
$$\chi$$
:  $\omega = d \log \left( G(z)^{-d/2} \right)$ 

$$\text{Computing } \chi \colon \quad \omega = \mathrm{d} \log \left( G(z)^{-d/2} \right) \qquad \omega = -\frac{d}{2} \left( \frac{\partial_1 G}{G} dx_1 + \dots + \frac{\partial_n G}{G} dx_n \right) \qquad \quad \chi = \# \text{ solutions to } \omega = 0$$

$$\chi = \#$$
 solutions to  $\omega = 0$ 

[Lee, 2013] [Mastrolia, Mizera 2018]

#### Computing Euler Characteristics for Landau Analysis

Computing 
$$\chi$$
:  $\omega = \mathrm{d} \log \left( G(z)^{-d/2} \right)$ 

$$\text{Computing } \chi \colon \quad \omega = \mathrm{d} \log \left( G(z)^{-d/2} \right) \qquad \omega = -\frac{d}{2} \left( \frac{\partial_1 G}{G} dx_1 + \dots + \frac{\partial_n G}{G} dx_n \right) \qquad \quad \chi = \# \text{ solutions to } \omega = 0$$

$$\chi = \#$$
 solutions to  $\omega = 0$ 

[Lee, 2013] [Mastrolia, Mizera 2018]

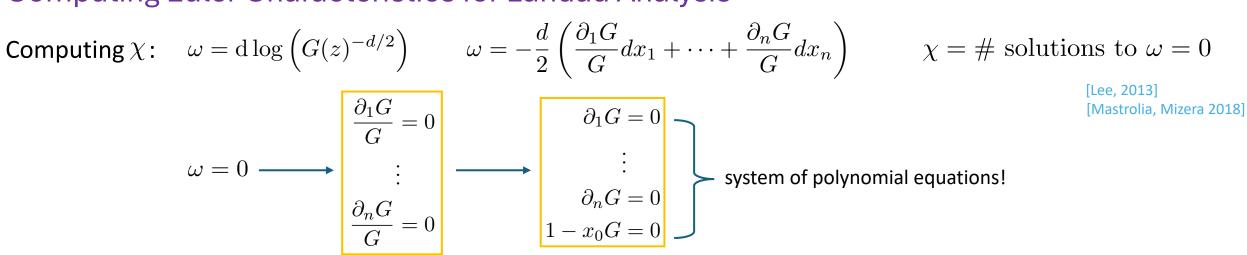
$$\omega = 0 \longrightarrow \frac{\frac{\partial_1 G}{G}}{\vdots} = 0$$

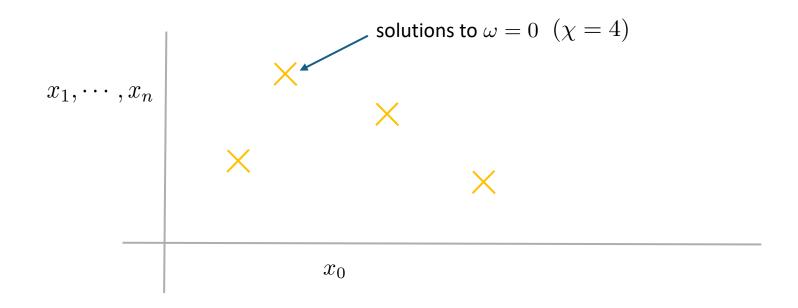
$$\vdots$$

$$\frac{\partial_n G}{G} = 0$$

#### Computing Euler Characteristics for Landau Analysis

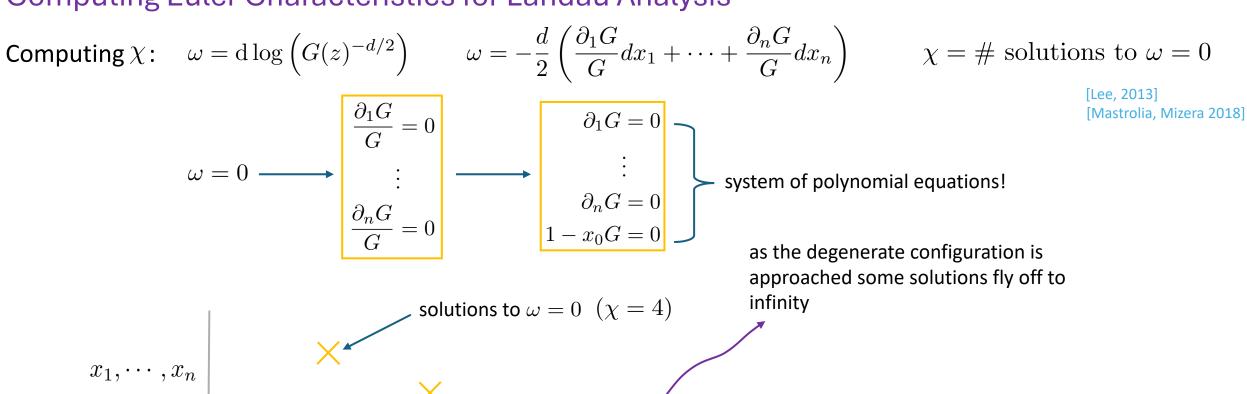
#### Computing Euler Characteristics for Landau Analysis





#### Computing Euler Characteristics for Landau Analysis

 $x_0$ 



18

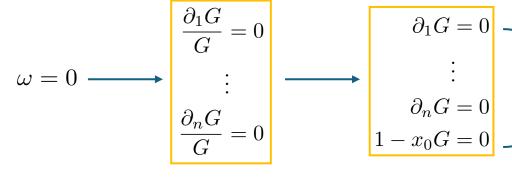
#### Computing Euler Characteristics for Landau Analysis

Computing 
$$\chi$$
:  $\omega = d \log \left( G(z)^{-d/2} \right)$   $\omega = -\frac{d}{2} \left( \frac{\partial_1 G}{G} dx_1 + \dots + \frac{\partial_n G}{G} dx_n \right)$   $\chi = \# \text{ solutions to } \omega = 0$ 

$$\omega = -\frac{d}{2} \left( \frac{\partial_1 G}{G} dx_1 + \dots + \frac{\partial_n G}{G} dx_n \right)$$

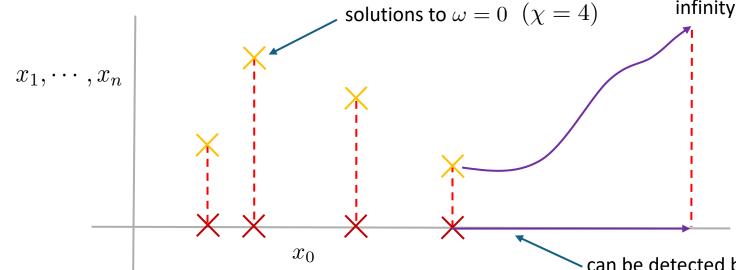
$$\chi = \#$$
 solutions to  $\omega = 0$ 

[Lee, 2013] [Mastrolia, Mizera 2018]



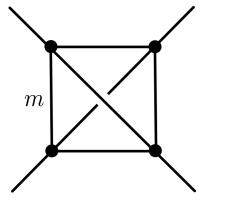
system of polynomial equations!

as the degenerate configuration is approached some solutions fly off to infinity



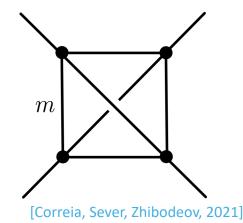
can be detected by checking coefficients of the remaining one variable polynomial

Computing Euler Characteristics for Landau Analysis: Three loop envelope (preliminary)



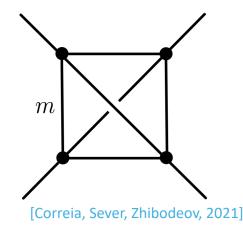
[Correia, Sever, Zhibodeov, 2021]

Computing Euler Characteristics for Landau Analysis: Three loop envelope (preliminary)



Horrendous integral:  $\chi = 60(!)$  in the top (max cut) sector alone

#### Computing Euler Characteristics for Landau Analysis: Three loop envelope (preliminary)

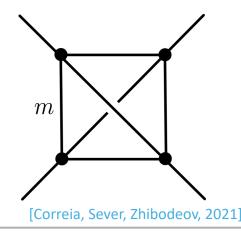


Horrendous integral:  $\chi = 60(!)$  in the top (max cut) sector alone

PLD/SOFIA most complicated letter found:  $27(m^2)^3 + 4s^2t + 4st^2$ 

[Fevola, Mizera, Telen, 2023] [Correia, Giroux, Mizera, 2025]

#### Computing Euler Characteristics for Landau Analysis: Three loop envelope (preliminary)



Horrendous integral:  $\chi = 60(!)$  in the top (max cut) sector alone

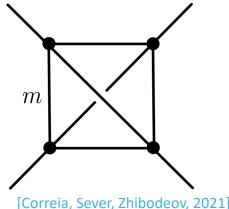
PLD/SOFIA most complicated letter found:  $27(m^2)^3 + 4s^2t + 4st^2$ 

[Fevola, Mizera, Telen, 2023] [Correia, Giroux, Mizera, 2025]

#### Euler characteristic strategy

Two new simple letters:  $\{s^2 + st + t^2, m^2s^2 + m^2st + s^2t + m^2t^2 + st^2\}$ 

#### Computing Euler Characteristics for Landau Analysis: Three loop envelope (preliminary)



Horrendous integral:  $\chi = 60(!)$  in the top (max cut) sector alone

PLD/SOFIA most complicated letter found:  $27(m^2)^3 + 4s^2t + 4st^2$ 

[Fevola, Mizera, Telen, 2023] [Correia, Giroux, Mizera, 2025]

#### [Correla, Sever, Zimboucov, 2021]

### Euler characteristic strategy

Two new simple letters:  $\{s^2 + st + t^2, m^2s^2 + m^2st + s^2t + m^2t^2 + st^2\}$ 

#### Four new complicated letters:

```
 \left\{ 27\, m2^4\, s^2 + 108\, m2^4\, s\, t + 162\, m2^3\, s^2\, t + 54\, m2^2\, s^3\, t + 4\, m2\, s^4\, t + 108\, m2^4\, t^2 + 162\, m2^3\, s\, t^2 + 45\, m2^2\, s^2\, t^2 - 6\, m2\, s^3\, t^2 - s^4\, t^2 - 18\, m2^2\, s\, t^3 - 20\, m2\, s^2\, t^3 - 2\, s^3\, t^3 - 9\, m2^2\, t^4 - 10\, m2\, s\, t^4 - s^2\, t^4\,, \\ 108\, m2^4\, s^2 - 9\, m2^2\, s^4 + 108\, m2^4\, s\, t + 162\, m2^3\, s^2\, t - 18\, m2^2\, s^2\, t^2 - 18\, m2^2\, s^3\, t - 10\, m2\, s^4\, t + 27\, m2^4\, t^2 + 162\, m2^3\, s\, t^2 + 45\, m2^2\, s^2\, t^2 - 20\, m2\, s^3\, t^2 - s^4\, t^2 + 54\, m2^2\, s\, t^3 - 6\, m2\, s^2\, t^3 - 2\, s^3\, t^3 + 4\, m2\, s\, t^4 - s^2\, t^4\,, \\ 27\, m2^4\, s^2 - 54\, m^2\, s\, t + 162\, m2^3\, s^2\, t - 54\, m2^2\, s^3\, t + 4\, m2\, s^4\, t + 27\, m2^4\, t^2 + 162\, m2^3\, s\, t^2 - 117\, m2^2\, s^2\, t^2 + 22\, m2\, s^3\, t^2 - s^4\, t^2 - 54\, m2^2\, s\, t^3 + 22\, m2\, s^2\, t^3 - 2\, s^3\, t^3 + 4\, m2\, s\, t^4 - s^2\, t^4\,, \\ 65\, 536\, m2^{12}\, + 270\, 336\, m2^{10}\, s^2 + 33\, 024\, m2^8\, s^4 + 1024\, m2^6\, s^6 + 270\, 336\, m2^{10}\, s\, t - 458\, 752\, m2^9\, s^2\, t + 66\, 048\, m2^8\, s^3\, t - 1276\, 416\, m2^7\, s^4\, t + 3072\, m2^6\, s^5\, t - 137\, 472\, m2^5\, s^6\, t - 4096\, m2^3\, s^8\, t + 270\, 336\, m2^{10}\, t^2 - 458\, 752\, m2^9\, s\, t^2 + 99\, 072\, m2^8\, s^2\, t^2 - 25\, 52\, 832\, m2^7\, s^3\, t^2 - 3\, 427\, 584\, m2^6\, s^4\, t^2 - 412\, 416\, m2^5\, s^5\, t^2 + 149\, 472\, m2^4\, s^6\, t^2 - 16\, 384\, m2^3\, s^7\, t^2 + 768\, m2^2\, s^8\, t^2 + 66\, 048\, m2^8\, s\, t^3 - 25\, 52\, 832\, m2^7\, s^2\, t^3 - 6\, 860\, 288\, m2^6\, s^3\, t^3 - 687\, 360\, m2^5\, s^4\, t^3 + 448\, 416\, m2^4\, s^5\, t^3 - 49\, 888\, m2^3\, s^6\, t^3 + 3072\, m2^2\, s^7\, t^3 - 48\, m2\, s^8\, t^3 + 3072\, m2^2\, s^7\, t^3 - 48\, m2\, s^8\, t^3 + 3024\, m2^8\, t^4 - 1276\, 416\, m2^7\, s\, t^4 - 3\, 427\, 584\, m2^6\, s^2\, t^4 - 687\, 360\, m2^5\, s^3\, t^4 + 597\, 888\, m2^4\, s^4\, t^4 - 92\, 3200\, m2^3\, s^5\, t^4 + 6144\, m2^2\, s^6\, t^4 - 192\, m2\, s^7\, t^4 + s^8\, t^4 + 3072\, m2^5\, s\, t^6 + 448\, 416\, m2^4\, s^3\, t^5 + 76\, 80\, m2^2\, s^5\, t^5 - 336\, m2\, s^6\, t^5 + 4\, s^7\, t^5 + 1024\, m2^6\, t^6 - 137\, 472\, m2^5\, s\, t^6 + 149\, 472\, m2^4\, s^2\, t^6 - 49\, 888\, m2^3\, s^3\, t^6 + 6144\, m2^2\, s^4\, t^6 - 336\, m2\, s^5\, t^6 + 6\, s^6\, t^6 - 16\, 384\, m
```

### Conclusions and Outlook

SPQR is a new open-source Mathematica package for performing polynomial division. It leverages finite field sampling and reconstruction to process Macaulay matrices from complex polynomial systems with high efficiency.

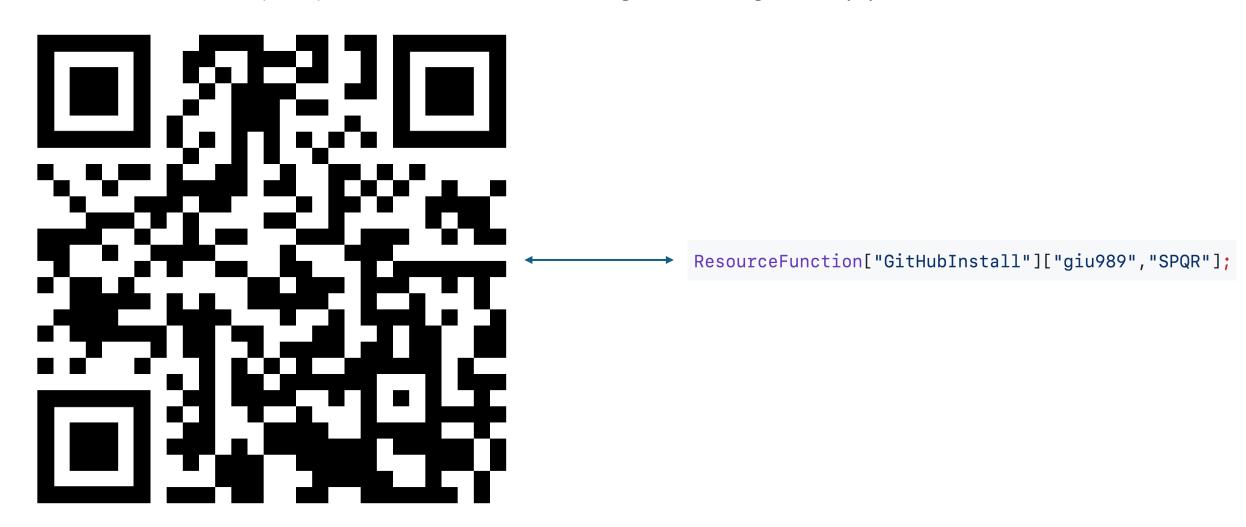
This approach avoids heavy symbolic cancellations, often leading to significant speedups compared to traditional Groebner basis approaches.

The companion matrix formalism helps contain the Macaulay system size, making it possible to handle larger and more complicated problems

Future development directions: A way to generate a smaller set of equations for the row reduction would allow for the tackling of even more complicated problems — perhaps possible to build equation systems based on the steps carried out by Groebner Basis algorithms/interface to current Groebner basis tools?

A reconstruction algorithm that factors expressions could save many sample points for sparse rational function outputs

(Beta) version is available now at github.com/giu989/spqr



### Thank you for listening!

(Beta) version is available now at github.com/giu989/spqr

