

# Improving Particle Identification in the Belle II TOP detector through Machine Learning



Cecilia Antonioli  
University and INFN of Padova



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on Nuclear Physics

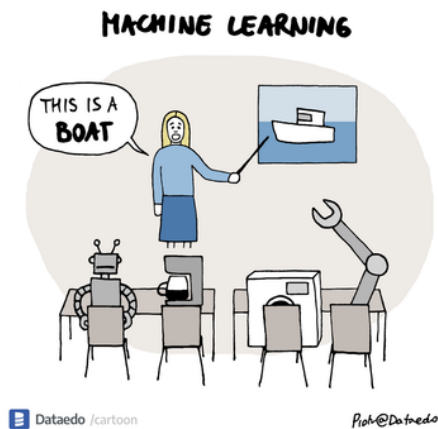
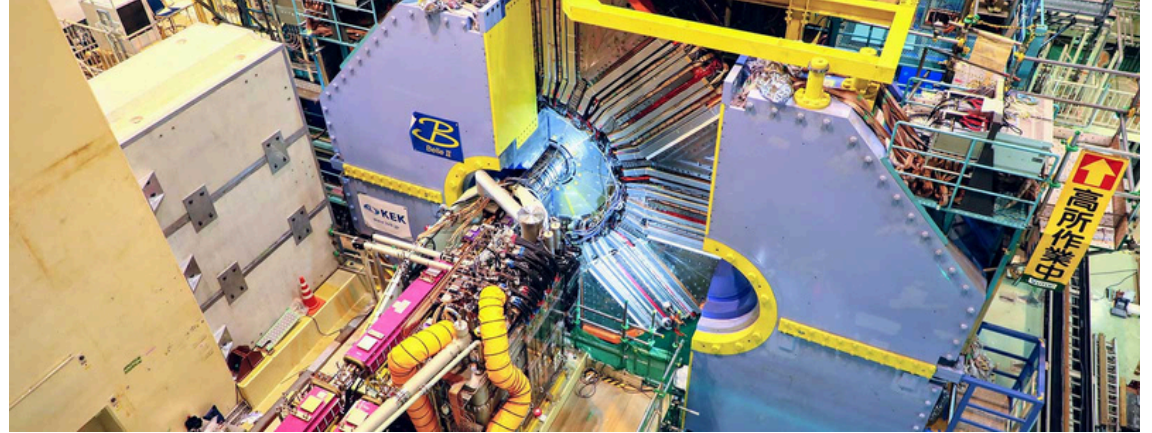


January 31, 2025, Bormio, Italy

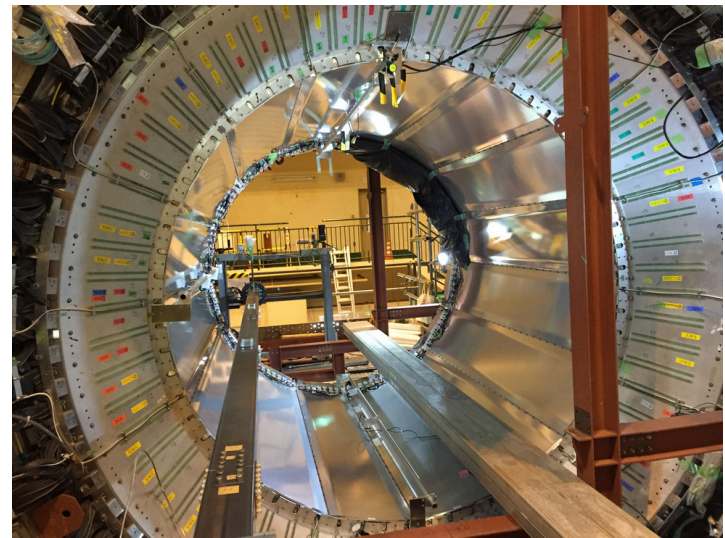


# Outline

- Introduction
- Belle II experiment
- TOP counter
- TOP working principle
- TOP PID Likelihood
- TOP PID with Machine Learning



<https://dataedo.com>



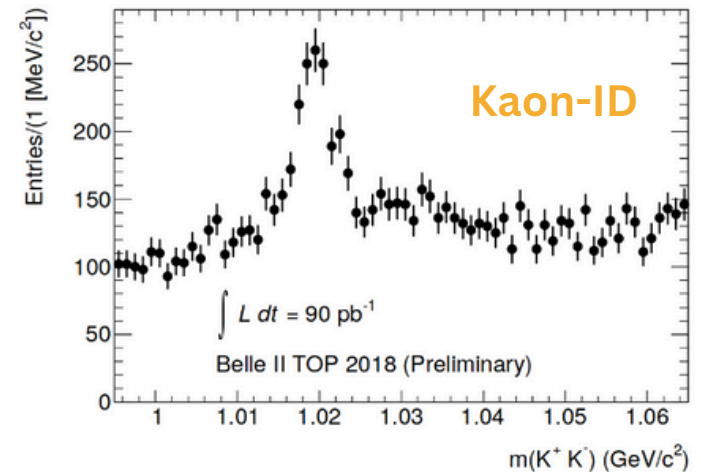
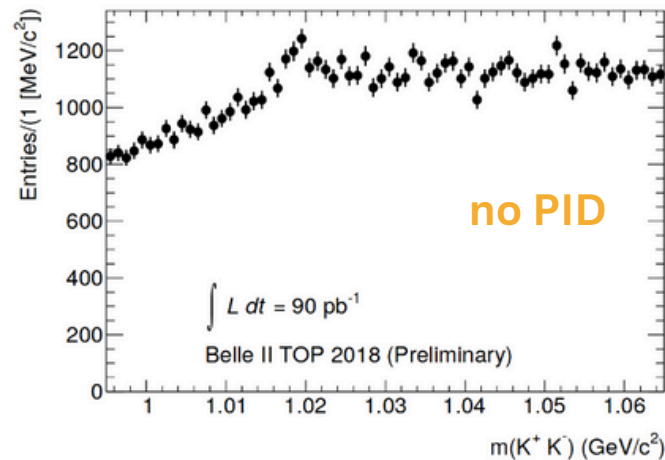
# Introduction

Reliable particle identification (PID) is essential for a flavor physics experiment

At  $B$ -factories, PID is required for

- the tagging of the  $B$ -meson flavor
- precision measurements of rare  $B/D$  decays
- ...

An example of  
PID effect on  
 $\phi \rightarrow K^+ K^-$   
reconstruction



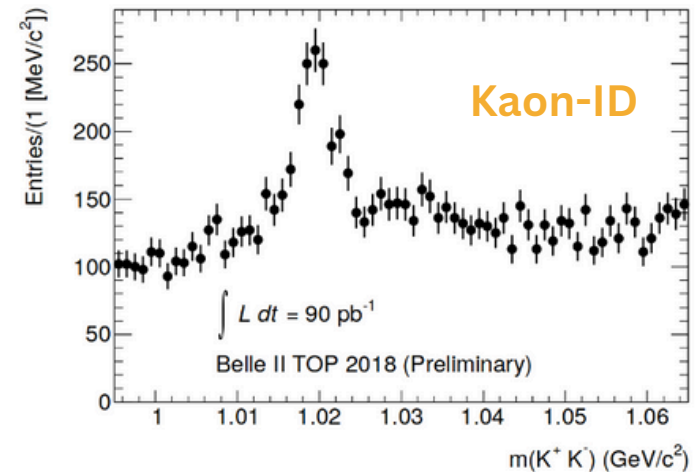
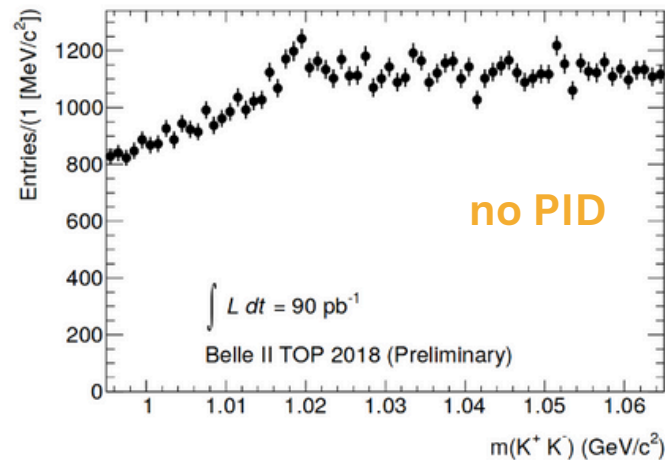
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Belle PID performance

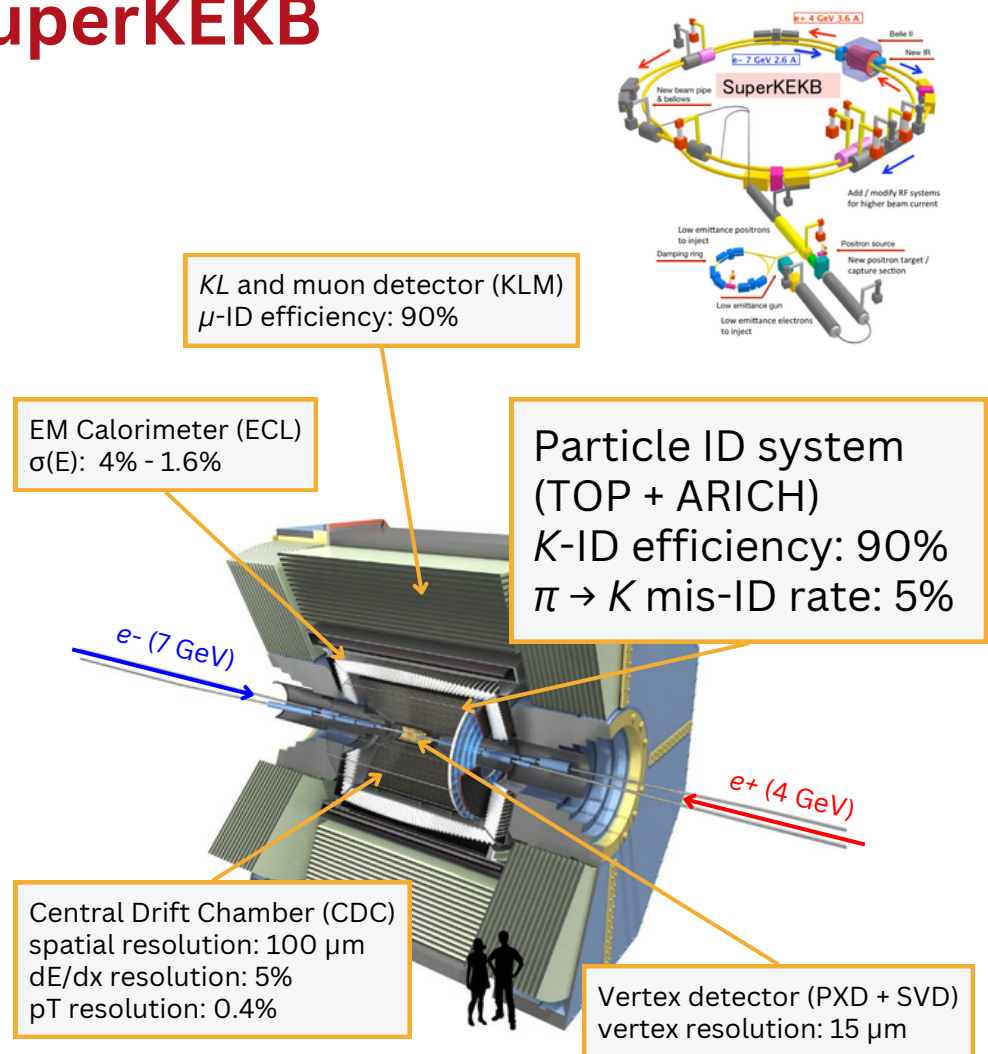
- $K$ -ID efficiency: 90%
- $\pi \rightarrow K$  mis-ID rate: 10%

# Belle II experiment at SuperKEKB

- Belle II is a luminosity frontier experiment to search for Physics Beyond the Standard Model
- It is located at SuperKEKB, the asymmetric  $e^+e^-$  collider at KEK in Tsukuba, Japan
- Collisions are (mostly) at the  $Y(4S)$  resonance,  $\sqrt{s} = 10.58$  GeV
- Peak luminosity record (Dec. 2024)  
 $L = 5.1 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$
- Accumulated  $575 \text{ fb}^{-1}$

## PID at Belle II

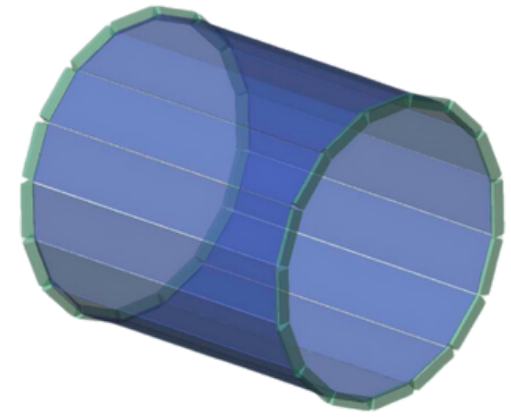
- Two dedicated PID devices:
  - **TOP in the barrel**
  - ARICH in the forward endcap
- All Belle II sub-detectors (except PXD) contribute to PID
- Six types of “stable” charged particles:  $e, \mu, \pi, K, p, d$



# TOP counter

TOP stands for **Time-Of-Propagation**

It consists of 16 modules arranged around the Central Drift Chamber (CDC) in the barrel region





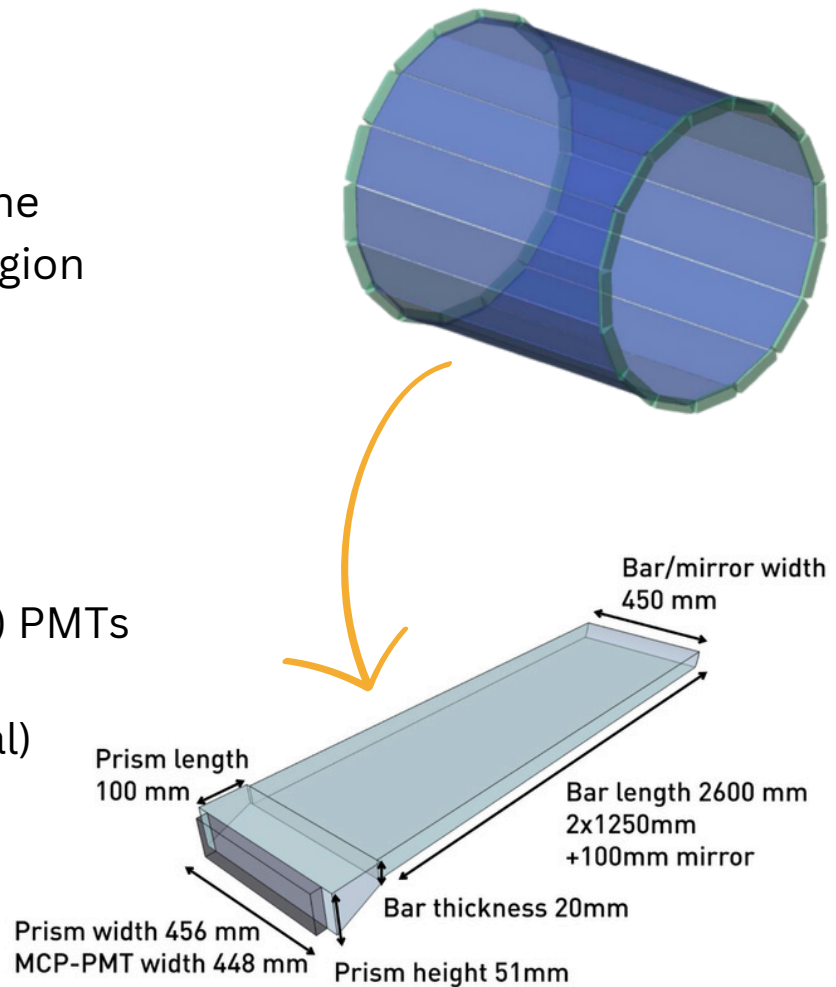
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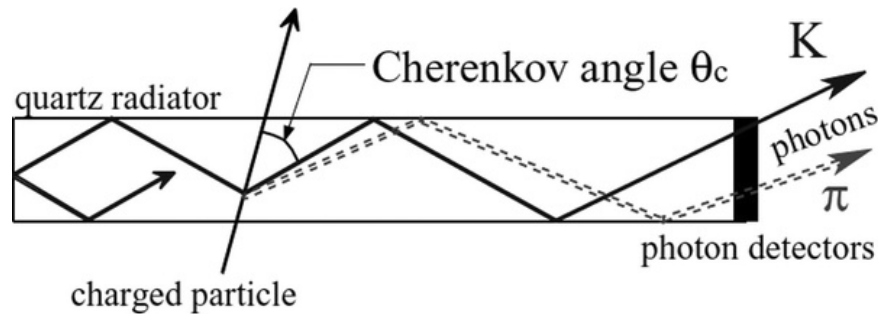
Each module consists of

- 2 quartz ( $n = 1.47$ ) bars glued together
- a focusing mirror at one end
- a small expansion prism at the other end
- an array of 32 Micro Channel Plate (MCP) PMTs
  - arranged in 2 rows
  - $4 \times 4$  channels each (512 pixels in total)
  - transit time spread  $< 50$  ps



# TOP working principle

TOP is a ring-imaging Cherenkov device



Dependence on particle mass and momentum

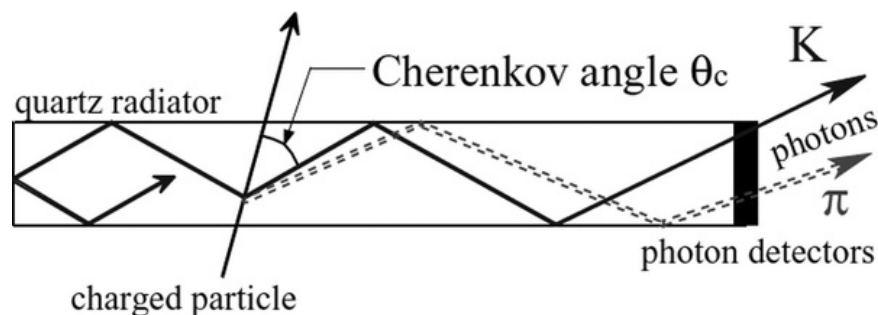
$$\cos \theta_C = \frac{1}{n\beta}$$

- Photons propagate within the quartz bar by internal reflection
- The 2D information of a Cherenkov ring-image is given by the **arrival time** and the **hit position** of the Cherenkov photons at the photon detector plane



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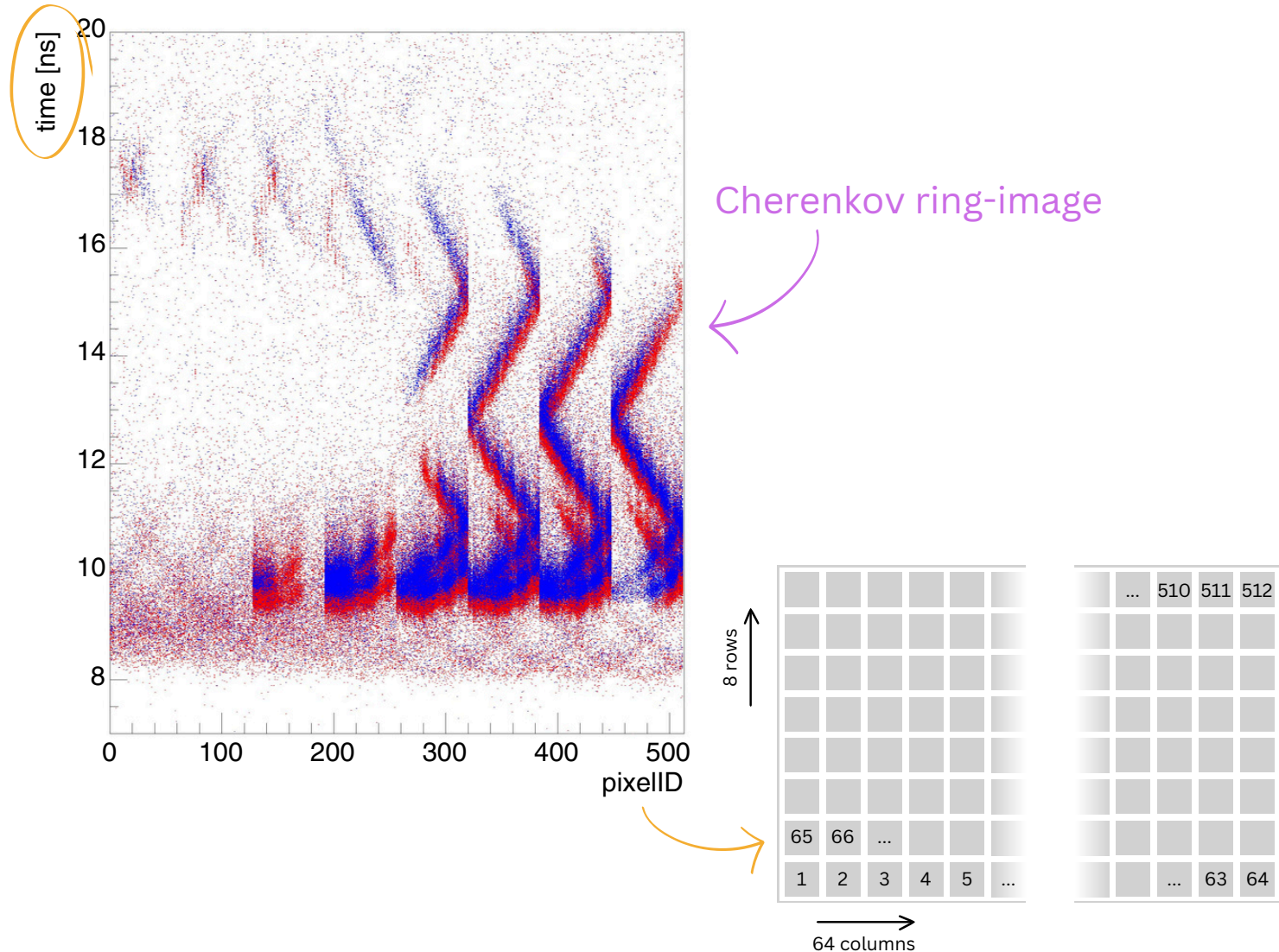
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→ **K and  $\pi$**  (with same momentum, impact position and impact angle on the bar) emit Cherenkov photons at **different  $\theta_c$**  → different path length → **different time of propagation and hit position on the photon detector plane**

- Time resolution < 100 ps for good PID performance

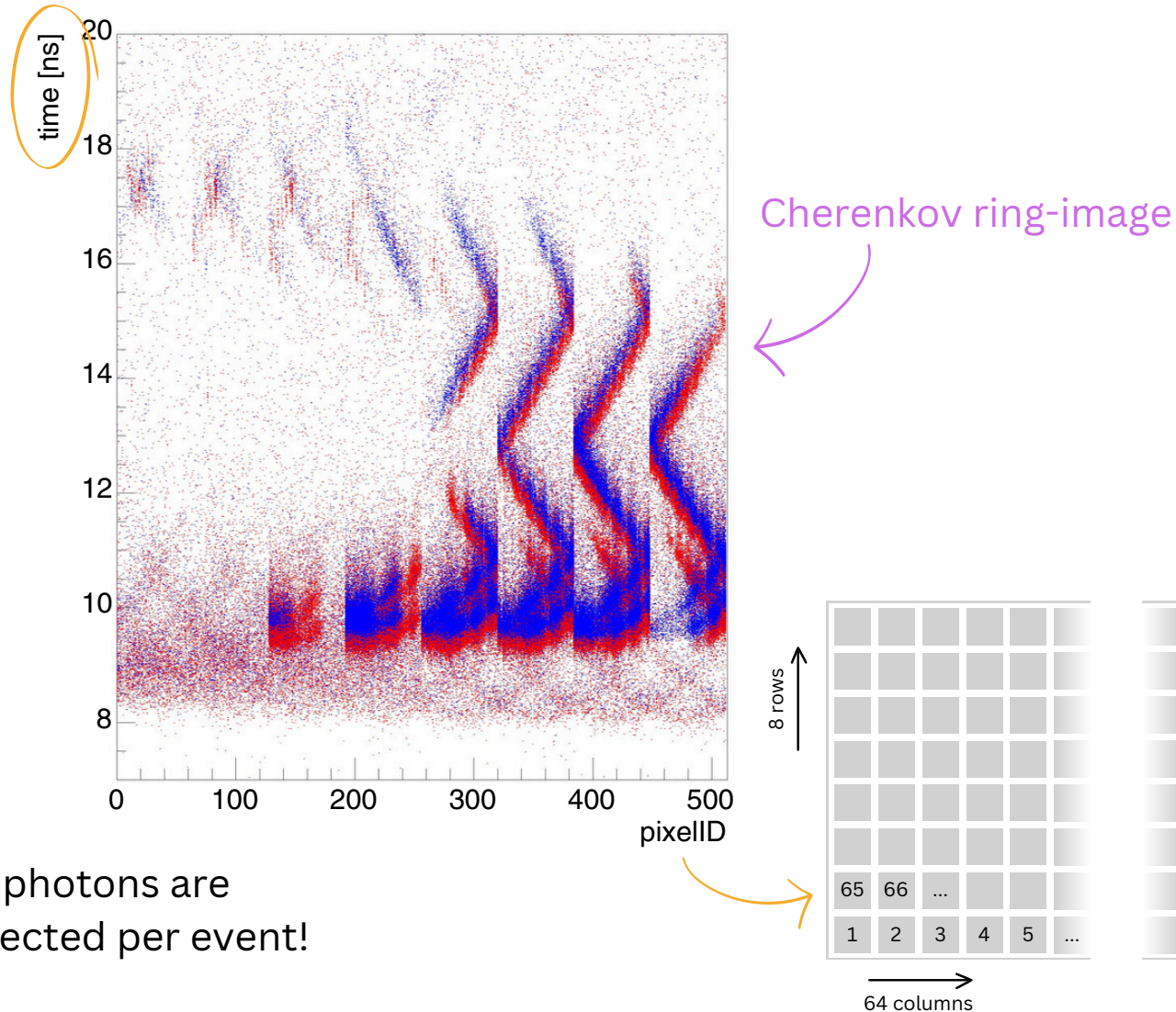
# Photon pattern

Example of measured pattern for thousands of photons, for simulated **pions** and **kaons** with  $p = 2.0 \text{ GeV}/c$ ,  $\theta = 90 \text{ deg}$ ,  $\varphi = 41.5 \text{ deg}$



# Photon pattern

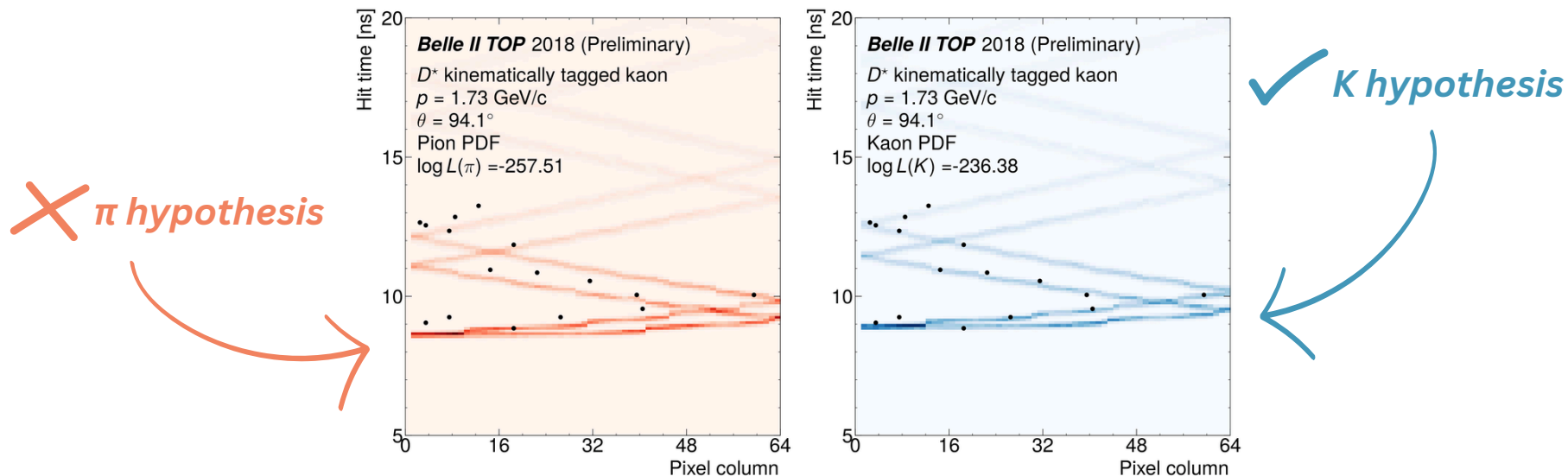
Example of measured pattern for thousands of photons, for simulated **pions** and **kaons** with  $p = 2.0 \text{ GeV}/c$ ,  $\theta = 90 \text{ deg}$ ,  $\varphi = 41.5 \text{ deg}$



**Note:** 20-40 photons are typically detected per event!

# TOP PID Likelihood

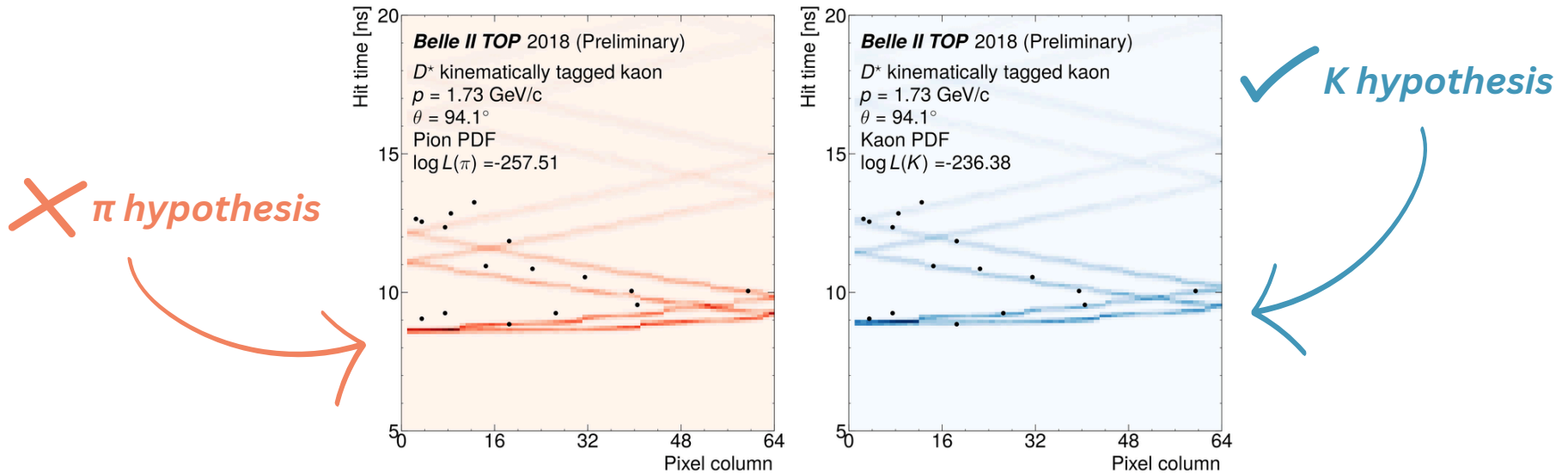
We compare the **measured 2D distribution  $x - t$**  ( $x$  = pixel column) (black dots) of the photon hits with the **expected pattern analytically calculated** (colored lines) for  $K$  and  $\pi$  hypotheses  $\rightarrow K$  and  $\pi$  TOP likelihoods



**Note:** the tracking system measures particle momentum, impact position and impact angle on the TOP bar

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The ratios of the TOP likelihoods are used to assign TOP PID probabilities

$$P_K = \frac{\mathcal{L}_K}{\mathcal{L}_K + \mathcal{L}_\pi} \quad P_\pi = 1 - P_K \quad (\text{binary PID})$$

TOP only binary PID gives 85% of  $K$ -ID efficiency with 10%  $\pi \rightarrow K$  mis-ID rate

# TOP PID with Machine Learning (ML)

## Why ML?

- The calculation of analytical TOP likelihoods requires a highly detailed simulation of all components of the TOP
- The simulation cannot perfectly reproduce the geometry of the TOP modules and the differences between them

→ With ML we can train using the data measured by the TOP (and the tracking system), so we do not need to simulate the TOP counter very precisely



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## Training flow



## Past results

- Boosted Decision Tree (BDT) for  $K$  and  $\pi$  separation
- Improved PID performance for particle gun events
  - Performance much decreased for generic MC events

# (Very) Preliminary results with CNN

## Proposal

- Use a Convolutional Neural Network (CNN) for  $K$  and  $\pi$  separation
  - CNNs are highly effective for pattern recognition

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## Proposal

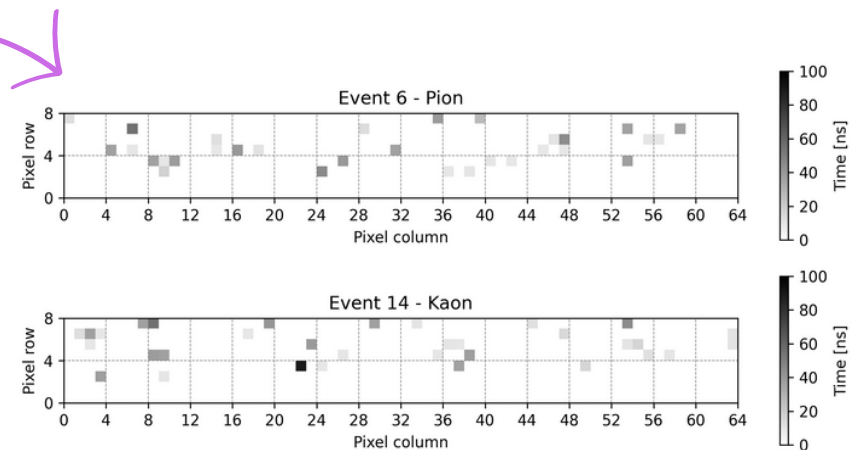
- Use a Convolutional Neural Network (CNN) for  $K$  and  $\pi$  separation
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## Simulated particle gun events

- ~200k particles ( $K^+$  and  $\pi^+$ ) from the interaction point
- $p = 2.0$  GeV/c,  $\theta = 90$  deg,  $\varphi = 41.5$  deg

## CNN model

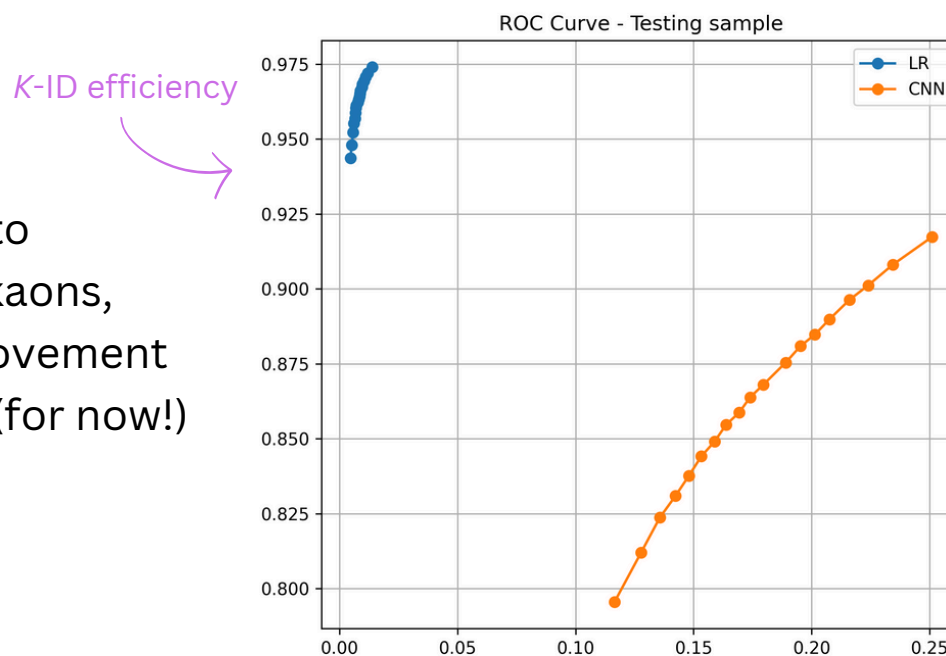
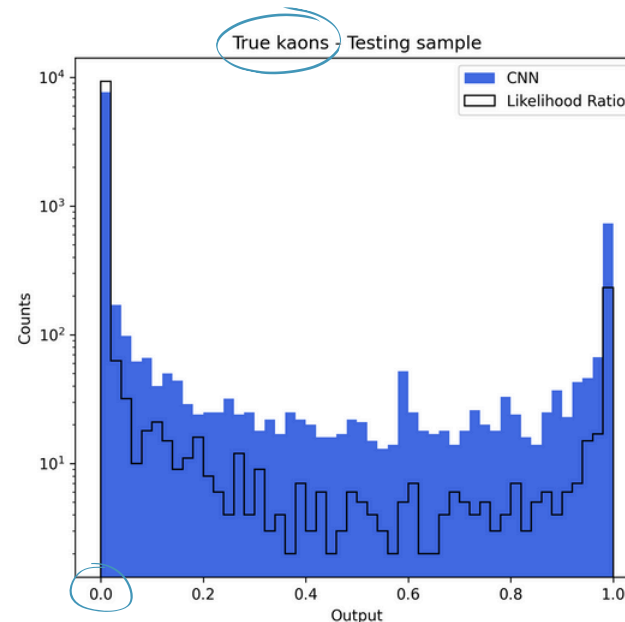
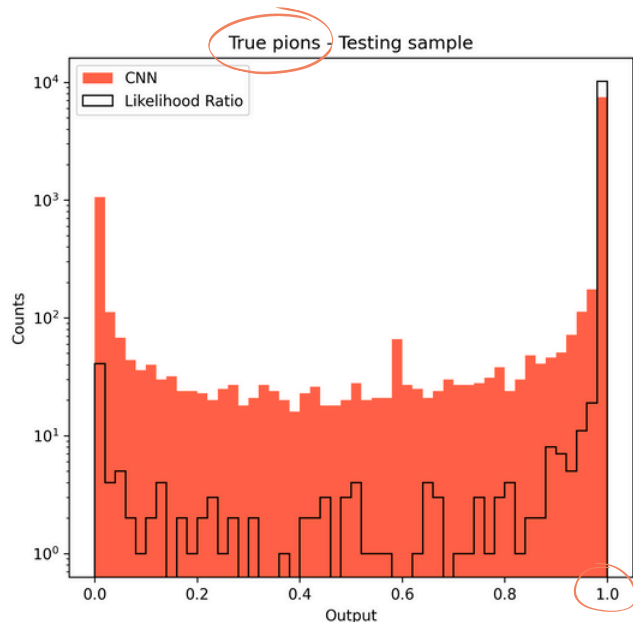
- Supervised learning
- Input:
  - images (8 x 64 x 1) (row x col x time)
- Network:
  - convolutional layers + dense layers
- Output:
  - binary classification: 1 for  $\pi$ , 0 for  $K$
- Training sample (90%) + Testing sample (10%)
- Training for 1000 epochs



# (Very) Preliminary results with CNN

Output:

- 1 for  $\pi$
- 0 for  $K$



$K$ -ID efficiency

$\pi \rightarrow K$  mis-ID rate

The network is able to separate pions and kaons, but there is no improvement in PID performance (for now!)

# Conclusion

- Belle II PID performance is better than Belle one
- TOP is a new concept Cherenkov detector type for PID that relies on precise timing of individual photons
- TOP only binary PID gives 85% of  $K$ -ID efficiency with 10%  $\pi \rightarrow K$  mis-ID rate

## Can we do better?

- We are exploring ML techniques for the TOP counter with the aim of improving PID performance
- Improved PID performance with BDT for particle gun events
- **Work in progress with CNN for particle gun events**
  - First tentative with images (row x col x time) as input
  - It is planned to use images (col x time) as input
- When we move to real data, we will have to take into account the dependence of PID performance on background conditions

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