

Phase transitions solutions I

①

1. Starting from $[\partial_\mu] = 1$, $[d^d x] = -d$, $[S] = 0$,

$$[\phi] = [A_\mu] = \frac{d-2}{2}$$

$$[m^2] = 2,$$

$$[g^2] = [\lambda] = 4-d,$$

So, the gauge coupling is:

-superrenormalisable in 3d,

-marginal in 4d,

-nonrenormalisable in 5d.

2. First introduce Schwinger's proper time,

$$\int \frac{1}{Q^2} = \int \int_0^\infty dt e^{-tQ^2}$$

$$= \sum_{n \in \mathbb{Z}} T \frac{\Omega_d}{(2\pi)^d} \int_0^\infty dq \cdot q^{d-1} e^{-tq^2} \int_0^\infty dt e^{-t\omega_n^2} \quad \left. \vphantom{\int_0^\infty dt e^{-t\omega_n^2}} \right\} \text{introduce radial momentum}$$

$$= \sum_n T \frac{\Omega_d}{(2\pi)^d} \cdot \frac{1}{2} \int_0^\infty du u^{\frac{d}{2}-1} e^{-u} \int_0^\infty dt \cdot t^{-\frac{d}{2}+2} e^{-t\omega_n^2}$$

$$= \sum_n T \frac{\Omega_d}{(2\pi)^d} \cdot \frac{1}{2} \Gamma\left(\frac{d}{2}\right) \frac{\omega_n^{d-2}}{2\pi\Gamma n} \int_0^\infty dv v^{(-\frac{d}{2}+1)+1} e^{-v}$$

$$= \frac{(2\pi)^{d-2}}{(2\pi)^d} \cdot \frac{2 \cdot \pi^{d/2} \Gamma\left(\frac{d}{2}\right) \Gamma\left(-\frac{d}{2}+2\right)}{2\Gamma\left(\frac{d}{2}\right) \left(-\frac{d}{2}+1\right)} \cdot \sum_{n=1}^\infty 2 \cdot n^{d-2} \cdot \frac{1}{\Gamma^{d-1}}$$

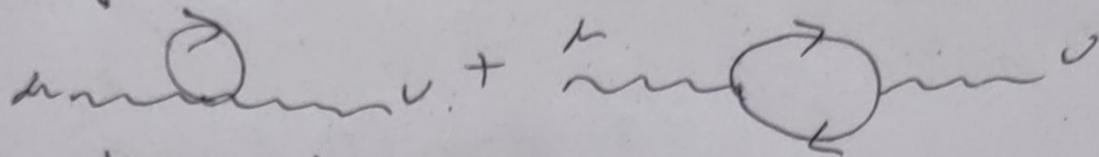
$$d=3-2\epsilon \left\{ \begin{aligned} &= \frac{2 \cdot \pi^{3/2} \cdot \pi^{1/2} \Gamma^2}{(2\pi)^2 \left(-\frac{1}{2}\right)} \underbrace{\Gamma\left(-1+2\epsilon\right)}_{-\frac{1}{2} + O(\epsilon)} = \frac{\Gamma^2}{12} \end{aligned} \right.$$

3. As before, there are no UV parts of the loop integrals in the 3d EFT, so

(2)

$$T_{\text{EFT}}^{\mu\nu} A_\mu A_\nu(0) = M_D^2 \delta_{\mu 0} \delta_{\nu 0}.$$

In the 4d theory, there is no tree-level diagram. At one-loop, we have:



The first diagram is easier,

$$\text{Diagram 1} = -2g^2 \delta_{\mu\nu} \int \frac{1}{Q^2} = -\frac{g^2 T^2}{6} \delta_{\mu\nu}.$$

Symmetry factor is 1. vertex

The second diagram reads,

$$\text{Diagram 2} = +g^2 \int \frac{(2Q_\mu)(2Q_\nu)}{Q^4} \equiv 4g^2 I_{\mu\nu}$$

$$\text{Consider } T^2 \frac{d}{dT^2} \int \frac{1}{Q^2} = \frac{1}{2} \int \frac{1}{Q^2} - \int \frac{Q_0^2}{Q^4} = T^2 \frac{d}{dT^2} \left(\frac{T^2}{12} \right) = \frac{T^2}{12}$$

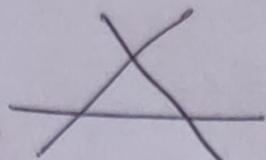
$$\Rightarrow \int \frac{Q_0^2}{Q^4} = -\frac{T^2}{24}$$

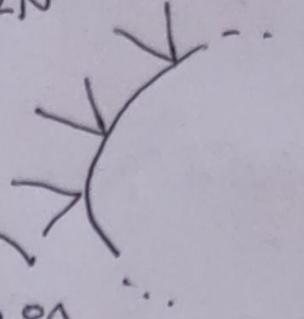
$$\delta_{ij} \int \frac{q_i q_j}{Q^4} = \int \frac{(Q^2 - Q_0^2)}{Q^4} = \frac{T^2}{12} + \frac{T^2}{24} = 3 \cdot \frac{T^2}{24}$$

$$\Rightarrow I_{\mu\nu} = \frac{T^2}{24} (-\delta_{\mu 0} \delta_{\nu 0} + \delta_{\mu i} \delta_{\nu i})$$

$$\Rightarrow T^{\mu\nu} A_\mu A_\nu(0) = \frac{g^2 T^2}{6} [\delta_{\mu\nu} + \delta_{\mu 0} \delta_{\nu 0} - \delta_{\mu i} \delta_{\nu i}]$$

$$= \begin{cases} \frac{g^2 T^2}{3} & , \mu = \nu = 0 \\ 0 & , \text{otherwise.} \end{cases}$$

4. a) $C_6 \phi^6$ 

$C_{2N} \phi^{2N}$ 
 N pairs of legs on one loop

b) $C_6 \sim \frac{\lambda^3}{\pi^4}$, { π 's optional

$C_{2N} \sim \frac{\lambda^N T^3}{T^N \pi^{2N-2}}$

N.B. some Ts from loop, others from canonical normalisation.

5. $\bar{\Phi}_{min}^2 = -\frac{m_3^2}{\lambda_3}, 0$, so $V_{EFT}(\bar{\Phi}_{min}) = -\frac{1}{2} \frac{m_3^4}{\lambda_3} + \frac{m_3^4}{4\lambda_3}, 0$
 $m_3^2(T_c) = 0$

$\frac{df}{dT} \Big|_{T_c^-} = -\frac{m_3^4}{4\lambda_3} \Big|_{T_c} - \frac{T}{2} \frac{m_3^2}{\lambda_3} \frac{dm_3^2}{dT} \Big|_{T_c} + \frac{T}{4} \frac{m_3^4}{\lambda_3^2} \frac{d\lambda_3}{dT} \Big|_{T_c} = 0$

$\frac{d^2f}{dT^2} \Big|_{T_c^-} = -\frac{T}{2\lambda_3} \left(\frac{dm_3^2}{dT} \right)^2 \Big|_{T_c} \neq 0$