

# Differential Reduction

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# Historical note

**1999 (ONHELL2) hep-ph: 9905379**

$$J_{011}(\sigma, \beta, \alpha) = \int \frac{d^n k_1 d^n k_2}{[(p - k_1)^2]^\sigma [(k_1 - k_2)^2 + m^2]^\alpha [k_2^2 + m^2]^\beta} \Big|_{p^2 = -m^2},$$

$$J_{011}(1, 2, 2) = \frac{2}{3}\zeta_2 - \varepsilon \frac{2}{3}\zeta_3 + \varepsilon^2 3\zeta_4 - \varepsilon^3 [\zeta_5] + \varepsilon^4 [\zeta_6] + \varepsilon^5 [\zeta_7]$$

where  $n = 4 - 2\varepsilon$  is the dimensionality of space time.

## Davydychev-Kalmykov: hep-th/0012189

$$\begin{aligned} & (3n - 8)J_{011}(1, 1, 1) + 6m^2 J_{011}(1, 1, 2) \\ &= 2(m^2)^{n-3} \Gamma\left(\frac{n}{2} - 1\right) \Gamma(3 - n) \Gamma\left(2 - \frac{n}{2}\right) . \end{aligned}$$

- ▶ Tarasov (1997): failed
- ▶ Czakon (2006): failed

## Kalmykov-Kniehl: math-ph/1105.5319

$$J_{012}(\sigma, \beta, \alpha) = \int \frac{d^n k_1 d^n k_2}{[(p - k_1)^2]^\sigma [(k_1 - k_2)^2 + M^2]^\alpha [k_2^2 + m^2]^\beta} \Big|_{p^2 = -m^2},$$

where  $n = 4 - 2\varepsilon$  is the dimensionality of space time.

$$\begin{aligned} & (3n-8)J_{012}(1, 1, 1) + 4m^2 J_{012}(1, 2, 1) + 2M^2 J_{012}(1, 1, 2) \\ &= 2(M^2)^{n-3} \Gamma\left(\frac{n}{2}-1\right) \Gamma(3-n) \Gamma\left(2-\frac{n}{2}\right). \end{aligned}$$

- ▶ TARCER:
- ▶ LiteRed:
- ▶ Azurite:

## Kniehl-Tarasov: hep-th-1602.00115

$$J_{123}(\sigma, \beta, \alpha) = \int \frac{d^n k_1 d^n k_2}{[(p - k_1)^2 - M_1^2]^\sigma [(k_1 - k_2)^2 - M_2^2]^\alpha [k_2^2 - M_3^2]^\beta} \Big|_{p^2=}$$

where  $n = 4 - 2\varepsilon$  is the dimensionality of space time.

$$\begin{aligned} & 2M_1^2 J_{123}(2, 1, 1) + 4M_2^2 J_{123}(1, 2, 1) + 2M_3^2 J_{123}(1, 1, 2) \\ & + (3n - 8) J_{123}(1, 1, 1) \\ & = 2(M_1)^{n-3} (M_3)^{n-3} \Gamma\left(\frac{n}{2} - 1\right) \Gamma(3 - n) \Gamma\left(2 - \frac{n}{2}\right) . \end{aligned}$$

# Is there something beyond IBP?

## 1-loop example

$$J_{01}(\sigma, \alpha) = \int \frac{d^n k_1}{[(p - k_1)^2]^\sigma [(k_1^2 - M^2)]^\alpha}$$

where  $n = 4 - 2\varepsilon$  is the dimensionality of space time.

$$J_{01}(\sigma, \alpha) = C(\sigma, \alpha) {}_2F_1 \left( \sigma, \sigma + \alpha - \frac{n}{2}; \frac{n}{2}; \frac{p^2}{M^2} \right),$$

where  $C(\sigma, \alpha)$  is the ratio of Gamma-functions.

# Contiguous relations versus IBP

F. Gauss, 1823

$$\begin{aligned}
 & P_1(a, b, c, z) {}_2F_1 \left( \begin{matrix} a + I_1, b + I_2 \\ c + I_3 \end{matrix} \middle| z \right) \\
 + & P_2(a, b, c, z) {}_2F_1 \left( \begin{matrix} a + J_1, b + J_2 \\ c + J_3 \end{matrix} \middle| z \right) \\
 + & P_3(a, b, c, z) {}_2F_1 \left( \begin{matrix} a + K_1, b + K_2 \\ c + K_3 \end{matrix} \middle| z \right) = 0,
 \end{aligned}$$

where  $\{I, K, L\}$  are integer and  $a, b, c$  are generic.

# Feynman Diagram as Mellin-Barnes Integral

Our starting point is the multiple Mellin-Barnes representation for Feynman Diagram

$$\begin{aligned} \Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D}; \vec{z}) &= \int_{-i\infty}^{+i\infty} \phi(\vec{t}) d\vec{t} \\ &= \text{Const} \int_{-i\infty}^{+i\infty} \prod_{a,b,c,r} \frac{\Gamma(\sum_{i=1}^m A_{ai} t_i + B_a)}{\Gamma(\sum_{j=1}^r C_{bj} t_j + D_b)} dt_c z_k^{\sum_l \alpha_{kl} t_l}, \end{aligned}$$

where  $z_k$  are the ratio of Mandelstam variables and  $A, B, C, D$  are some matrices and vectors depending in a linear way on the dimension of space-time  $n$  and the powers of the propagators.



# From Mellin-Barnes Integral to PDE

Let us define the polynomials  $P_i$  and  $Q_i$  as

$$\frac{P_i(\vec{t})}{Q_i(\vec{t})} = \frac{\phi(\vec{t} + \mathbf{e}_i)}{\phi(\vec{t})},$$

where  $\mathbf{e}_j$  is a unit vector with nonzero element at  $j$ -place.

Then, the function  $\Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D}; \vec{z})$  satisfy to the system of linear differential equations

$$L_j \Phi := \left[ Q_i(\vec{t}) \Big|_{t_j \rightarrow \theta_j} \frac{1}{z_i} - P_i(\vec{t}) \Big|_{t_j \rightarrow \theta_j} \right] \Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D}; \vec{z}),$$

where  $\theta_i = z_i \frac{d}{dz_i}$ .

# Prolongation procedure

Let us consider the set of PDE ( $L_i$ ) operators

$$L_j := P_j(\theta) - z_j Q_j(\theta)$$

We can prolong this system of equations by adding the new equations

$$\theta_{\bar{a}} L_j = 0.$$

In accordance with Cartan-Kuranishi prolongation theorem after a finite number of prolongations the system is either in involution form or incompatible.

$$L_j \Phi \Rightarrow \left\{ \vec{d}\Phi(\vec{z}) = \Omega^r(\vec{z})\Phi(\vec{z}), \quad \vec{d} \left[ \vec{d}\Phi(\vec{z}) \right] = 0 \right\}.$$

## StepUp perators

$$\Phi(\vec{A}; \vec{B}; \vec{C}; \vec{D}; z) \sim \int_{-i\infty}^{+i\infty} \prod_{a,b,c,r} \frac{\Gamma(\sum_{i=1}^m A_{ai}t_i + B_a)}{\Gamma(\sum_{j=1}^r C_{bj}t_j + D_b)} dt_c z^k \sum_l \alpha_{kl} t_l,$$

The function  $\Phi$  satisfy to differential contiguous relations:

$$\Phi(\mathbf{A}, \vec{B} + e_a; \mathbf{C}, \vec{D}; \vec{z}) = \left( \sum_{i=1}^m A_{ai} \theta_i + B_a \right) \Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D}; \vec{z}),$$

$$\Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D} - e_b; \vec{z}) = \left( \sum_{j=1}^r C_{bj} \theta_j + D_b \right) \Phi(\mathbf{A}, \vec{B}; \mathbf{C}, \vec{D}; \vec{z}).$$

# Construction of inverse differential operators

- ▶ There are linear differential operators  $R$  changing the value of the discrete variables by one unit:

$$R_K(\vec{z}) \frac{\partial^K}{\partial \vec{z}} \Phi(\vec{J}; \vec{z}) = \Phi(\vec{J} \pm e_K; \vec{z}),$$

where  $R_K(\vec{z})$  are polynomial functions.

- ▶ There is a closed system of differential equations:

$$\vec{d}\Phi(\vec{J}; \vec{z}) = \Omega(\vec{z})\Phi(\vec{J}; \vec{z}), \quad \vec{d} \left[ \vec{d}\Phi(\vec{J}; \vec{z}) \right] = 0.$$

- ▶ There is an algorithmic solution for the construction of inverse linear differential operators  $B$ :

$$B_L(\vec{z}) \frac{\partial^L}{\partial \vec{z}} \left( R_K(\vec{z}) \frac{\partial^K}{\partial \vec{z}} \right) \Phi(\vec{J}; \vec{z}) \equiv \Phi(\vec{J}; \vec{z}).$$

# Literature

M. Saito, B. Sturmfels, N. Takayama,  
*Gröbner Deformations of Hypergeometric Differential  
Equations,*

# Differential Reduction

Applying the direct or inverse differential operators to the function  $\Phi$ , the value of parameters can be changed by an arbitrary integer number:

$$S(\vec{z})\Phi(\vec{J} + \vec{m}; \vec{z}) = \sum_{j=0}^r S_j(\vec{z}) \frac{\partial^j}{\partial \vec{z}} \Phi(\vec{J}; \vec{z}),$$

where  $\vec{m}$  is a set of integers,  $S$  and  $S_j$  are polynomials and  $r$  is the holonomic rank (the number of linearly independent solutions) of the system of differential equations. In the end, the derivatives are converted into finite difference:

$$\sum_{j=0}^r S_j(\vec{z}) \frac{\partial^j}{\partial \vec{z}} \Phi(\vec{J}; \vec{z}) = \sum_{j=0}^r S_j(\vec{z}) \Phi(\vec{J} + j; \vec{z})$$

# Example: one-fold Mellin-Barnes integral

Let us consider the function

$$\Phi(\vec{A}; \vec{B}; \vec{C}; \vec{D}; z) = C_{\Phi} \int_{\gamma+iR} dt \frac{\prod_{i=0}^K \Gamma(A_i + t) \prod_{j=0}^L \Gamma(C_j - t)}{\prod_{k=0}^R \Gamma(B_k + t) \prod_{l=0}^J \Gamma(D_l - t)} \Gamma(-t) z^t$$

Then:

$$\left\{ \theta(\theta + \vec{B} - 1)(\theta - \vec{C})(-1)^{L+1-J} - z(\theta + \vec{A})(\theta - \vec{D} + 1) \right\} \Phi = 0,$$

where  $\theta = z \frac{d}{dz}$

Let us consider the non-confluent differential equation, when the order of differential operator in l.h.s. and in r.h.s. are equal to each other, so that the function  $\Phi$  satisfy to the differential equation of order  $p$ . In this case there are  $p$ -linearly independent solutions of differential equation.

# Factorization

- ▶ The following factorization is possible

$$\int dt \frac{\Gamma(A+m+t)}{\Gamma(A+t)} z^t F(t) = (A+m-1+\theta) \cdots (A+\theta) \int dt \Gamma(A+t) z^t F(t) .$$

where  $m$  is positive integer.

- ▶ Factorization of the differential equation

$$z(\theta+1+a)f(z) = (\theta+a)(zf(z)) ,$$

where  $a$  is an arbitrary parameter.



# Example: one-loop massless box (Tarasov)

$$\begin{aligned}
 & \int \frac{d^n k}{[k^2]^{a_1} [(k+p_1)^2]^{a_2} [(k+p_1+p_2)]^{a_3} [(k+p_1+p_2+p_3)]^{a_4}} \\
 & \sim \int_{-i\infty}^{i\infty} dt \left(\frac{s}{t}\right)^t \Gamma(-t) \Gamma(a_1+t) \Gamma(a_3+t) \\
 & \quad \Gamma\left(a - \frac{n}{2} + t\right) \Gamma\left(\frac{n}{2} - a_{134} - t\right) \Gamma\left(\frac{n}{2} - a_{123} - t\right) \\
 & \Rightarrow \theta\left(\theta + a_{134} - \frac{n}{2}\right) \left(\theta + a_{123} - \frac{n}{2}\right) + z\left(\theta + a - \frac{n}{2}\right) (\theta + a_1) (\theta + a_3) .
 \end{aligned}$$

# Example: $J_{012}$

$$J_{012} \equiv \int \frac{d^n(k_1 k_2)}{[(k_1 - p)^2]^\sigma [k_1^2 - M^2]^\alpha [(k_1 - k_2)^2 - m^2]^\beta} \Big|_{p^2=m^2}$$

This integral corresponds to differential equation of order 4.  
For integer  $\sigma, \alpha, \beta$  is could be rewritten as

$$\left(\theta - \frac{n}{2} + l_1\right) (\theta - n + l_2) \left[ \theta \left(\theta - n + \frac{1}{2} + l_3\right) + z \left(\theta - \frac{3n}{2} + l_4\right) \right]$$

# Sunrise: Mellin-Barnse

Let us consider  $L$ -loop sunrise

$$J(\vec{M}_j^2; \vec{\alpha}_j; p^2) = \int \prod_{j=1}^L \frac{d^n k_j}{[k_j^2 - M_j^2]^{\alpha_j}} \times \frac{1}{[(p - \dots - k_L)^2 - M_{L+1}^2]^{\alpha_{L+1}}},$$

Its MB representation is the following:

$$\begin{aligned} J(\vec{M}_j^2; \vec{\alpha}_j; p^2) &= (p^2)^{\frac{n}{2}L - \alpha} [i^{1-n} \pi^{n/2}]^L \\ &\times \int \left\{ \prod_{j=1}^{L+1} dt_j \frac{\Gamma(-t_j) \Gamma(\frac{n}{2} - \alpha_j - t_j)}{\Gamma(\alpha_j)} \left(-\frac{M_j^2}{p^2}\right)^{t_j} \right\} \\ &\times \frac{\Gamma(\alpha - \frac{n}{2}L + \vec{t})}{\Gamma(\frac{n}{2}(L+1) - \alpha - \vec{t})}, \end{aligned}$$

## Sunrise: contiguous relations

$$\Phi(A, B; \{C_k\}; \{z_1\}) = \int \prod_{j=1}^K dt_j \Gamma(-t_j) \Gamma(C_j - t_j) z_j^{t_j} \frac{\Gamma(A + \vec{t})}{\Gamma(B - \vec{t})}.$$

$$\Phi(A, B; \{\}, C_j + 1, \{\}; \vec{z}) = (C_j - \theta_j) \Phi(A, B; \{\}, C_j, \{\}; \vec{z}),$$

$$\Phi(A + 1, B; \{C_k\}; \vec{z}) = \left(A + \sum_{j=1}^K \theta_j\right) \Phi(A, B; \{C_k\}; \vec{z}),$$

$$\Phi(A, B - 1; \{C_k\}; \vec{z}) = \left(B - 1 - \sum_{j=1}^K \theta_j\right) \Phi(\vec{A}; B; \{C_k\}; \vec{z}),$$

where

$$\theta_j = z_j \frac{d}{dz_j}, \quad j = 1, \dots, m.$$

## Sunrise: PDE

A linear system of partial differential equations (PDE) for the function  $\Phi$  can be derived in two steps: (I) at the first step we define the polynomials  $P$  and  $Q$  as:

$$\frac{P_j}{Q_j} = \frac{\phi(t_j + 1)}{\phi(t_j)} .$$

These polynomials define the corresponding system of differential equations (step II):

$$\frac{P_j^\Phi}{Q_j^\Phi} = - \frac{\left( A + \sum_{j=1}^K t_j \right) \left( 1 - B + \sum_{j=1}^K t_j \right)}{(1 - C_j + t_j)(1 + t_j)} \Rightarrow$$

$$L_j^\Phi : (\theta_j - C_j) \theta_j \Phi = -z_j \left( \sum_{j=1}^K \theta_j + A \right) \left( \sum_{j=1}^K \theta_j + (1 - B) \right) \Phi ,$$

# Sunrise

- ▶ holonomic rank ( $2^K$ ): Lauricella (1893):

$$d\Phi(\vec{z}_K) = \Omega^{(2K)}(\vec{z})\Phi(\vec{z}),$$

- ▶ zero of  $b$ -functio: Saito (1995)  
when parameters  $A, B, \{C_i\}$  satisfy some linear combinations,

$$f_a(A, B, C_j) = 0, \quad a = 1, \dots, p$$

the additional differential operators are generated so that the Puiseux type solution appear.

- ▶ How to find the corresponding linear combination of parameters and how to define the minimal set of additional differential equations.

# Zero of $b$ -function

- ▶ Our "old" approach to these problems is based on studying the inverse differential operators: the exceptional case of parameters, when dimension of the solution space is reduced, corresponds to the condition that the denominators of functions are equal to zero for an arbitrary values of  $z$ ;  
However, the inverse differential operators have a very complicated structure, which gives rise to technical problems in the analysis of the number of independent PDEs.
- ▶ New algorithm: evaluation of the dimension of the invariant subspace of the differential contiguous operators

# GKZ: criteria of reducibility

M. Saito,  
F. Beukers,  
A. Dickenstein, L. Matusevich, E. Miller,  
M. Schulze, U. Walther,  
T. Sadykov,  
F. Beukers, G. Heckman,  
K. Mimachi, T. Sasaki,



# What is happen when monodromy is reducible

Let  $\Phi$  be the set of solutions for the system of linear differential operators  $L_j^\Phi$ :

$$L_j^\Phi \Phi = 0 .$$

Let  $S(A, B, \vec{C})$  denote the local solution space of operators  $L_j^\Phi(A, B, \vec{C})$  around some point  $z_0$ .

The contiguous differential operators  $B_{A,B,C}$  map the solution space  $S(A, B, \vec{C})$  to the solution space

$S(A \pm I_1, B \pm I_2, \vec{C} \pm \vec{I}; \vec{z})$ , where  $\{I_a\}$  are set of integers.

When monodromy is reducible there is monodromy invariant subspace (invariant under action of monodromy) in the space of solutions. In this case the contiguous differential operators has a non-trivial kernel and it is necessary to evaluate their dimension.

# Practical evaluation: I

$$L_j^\Phi(A, B, \vec{C}) : \left[ (\theta_j - C_j) \theta_j + z_j \left( \sum_{j=1}^K \theta_j + A \right) \left( \sum_{j=1}^K \theta_j + (1 - B) \right) \right],$$

Let us consider the equation  $B_A^+ \Phi = 0$ , where  $B_A^+$  is defined by

$$B_A^+ : \left( A + \sum_{j=1}^K \theta_j \right) \Phi = 0$$

Then the system of equations reduces to

$$L_j^\Phi(A, B, \vec{C}) \Phi \equiv (\theta_j - C_j) \theta_j \Phi \equiv 0, \quad j = 1, \dots, K.$$

# Practical evaluation: II

$$L_j^\Phi(A, B, \vec{C})\Phi \equiv (\theta_j - C_j)\theta_j\Phi \equiv 0, \quad j = 1, \dots, K.$$

When  $C_j \neq 0$  the solution  $\Phi_0$  of this equation has the following form:

$$\Phi_0 = c_0 + \sum_{i=1}^K c_i z_i^{C_i} + \sum_{\substack{i,j=1 \\ i < j}}^K c_{i,j} z_i^{C_i} z_j^{C_j} + \dots + \text{Const.} \times \prod_{i=1}^K z_i^{C_i}.$$

Applying operator  $B_A^+$  to function  $\Phi_0$  we get:

$$\begin{aligned} (A + \sum_{j=1}^K \theta_j)\Phi_0 \equiv 0 &= A c_0 + \sum_{i=1}^K c_i (A + C_i) z_i^{C_i} \\ &+ \sum_{i,j=1}^K c_{i,j} (A + C_i + C_j) z_i^{C_i} z_j^{C_j} + \dots \end{aligned}$$

# Solution

Under conditions that

$$A, C_j, \notin \mathbb{Z}, \quad A + \sum_{j=1}^K C_j - C_a = 0, \quad a = 1, \dots, K,$$

there is an invariant subspace of dimension  $K$  for operator  $B_A^+$ . Similar consideration can be done also for operator  $B_B^+$ . In particular, it is easy to show that under conditions that

$$B, C_j \notin \mathbb{Z}, \quad B + \sum_{j=1}^K C_j = 0,$$

there is one-dimensional invariant subspace.

# L-loop sunrise diagram

For sunrise

$$A = \alpha + \alpha_{L+1} - \frac{n}{2}L, \quad D = \alpha - \frac{n}{2}(L-1), \quad C_j = \frac{n}{2} - \alpha_j.$$

To find the dimension of the invariant subspace, it is necessary to find all solutions of the following system of algebraic equations:

$$\frac{n}{2}L - \sum_{S_1} \frac{n}{2} = 0 \pmod{\mathbb{Z}}, \quad (2a)$$

$$\frac{n}{2}(L+1) - \sum_{S_2} \frac{n}{2} = 0 \pmod{\mathbb{Z}}, \quad (2b)$$

where  $S_1$  and  $S_2$  are any subsets of  $1, \dots, L+1$ ,  $\mathbb{Z} = \{\dots, -1, 0, 1, \dots\}$ , and  $n$  is non-integer.

# $L$ -loop sunrise diagram

$$\frac{n}{2}L - \sum_{S_1} \frac{n}{2} = 0 \pmod{\mathbb{Z}},$$

The subset  $S_1$  can be constructed in  $L + 1$  different ways (it includes all possible combinations of  $L$  out of the  $L + 1$  massive lines).

$$\frac{n}{2}(L + 1) - \sum_{S_2} \frac{n}{2} = 0 \pmod{\mathbb{Z}},$$

there is only one solution of the second equation (the subset  $S_2$  includes all the lines).

# $L$ -loop sunrise diagram

The number  $N_J$  of irreducible master integrals of the  $L$ -loop sunrise diagram with generic values of masses and momenta is equal to

$$N_J = 2^{L+1} - L - 2 .$$

For example, for  $L = 1, 2, 3, 4, 5, 6$ , we have  $N_J = 1, 4, 11, 26, 57, 120$ , respectively.

## Bubble: MB

The massive bubble integrals corresponds to the following function:

$$\Psi(A, D; \{C_k\}; z_K) = \int \prod_{j=1}^K dt_j \Gamma(-t_j) z_j^{t_j} \\ \times \Gamma(C_j - t_j) \Gamma(A + \vec{t}) \Gamma(D + \vec{t}) .$$

In this case we have:

$$\frac{P_j^\Psi}{Q_j^\Psi} = \frac{\left(A + \sum_{j=1}^K t_j\right) \left(D + \sum_{j=1}^K t_j\right)}{(1 - C_j + t_j)(1 + t_j)} \Rightarrow$$

$$L_j^\Psi : (\theta_j - C_j) \theta_j \Psi = z_j \left( \sum_{j=1}^K \theta_j + A \right) \left( \sum_{j=1}^K \theta_j + D \right) \Psi ,$$



# Conclusion

- ▶ 1-fold MB: counting, reduction, analytical evaluation of  $\varepsilon$ -expansion. Factorization play an important role.
- ▶ k-fold MB: depends on the complexity. Typically limited by  $k = 2, 3$ .
- ▶ evaluation of singular locus of Feynman Diagram (Oaku, 1994).
- ▶ evaluation of zero of b-functions related with Feynman Diagram.
- ▶ construction of coefficients of  $\varepsilon$ -expansion - mainly in application to multivariable hypergeometric functions.